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Nutanix Certified Professional - Multicloud Infrastructure (NCP-MCI) 7.5 NCP-MCI-7.5 Prüfungsfragen mit Lösungen (Q66-Q71):

66. Frage

An administrator is configuring Runway Analysis settings in Prism Central and selects Auto Detect under Reserve Capacity For Failure.

How will runway capacity be calculated in this configuration?

- A. The runway analysis reserves capacity only for storage resources while CPU and memory remain unchanged.
- B. The runway analysis calculates capacity using the full cluster resources but automatically adds a performance buffer.
- **C. The runway analysis excludes the resources of the largest node so estimates account for a node failure.**
- D. The runway analysis reserves a fixed 10% of cluster CPU, memory, and storage capacity by default.

Antwort: C

Begründung:

Nutanix documentation for Updating Capacity Configurations explains that the Reserve Capacity For Failure option determines whether runway analysis should account for the impact of a node failure, and when Auto Detect is selected, Prism Central automatically uses the cluster's failure assumptions rather than the full unconstrained cluster total. In practical runway terms, that means the calculation reflects the loss of the node whose failure would have the greatest effect on usable capacity. Among the provided options, the best match for that documented logic is D: the runway analysis excludes the resources of the largest node so estimates account for a node failure. (Nutanix Portal) This behavior is important because runway is intended to answer "how long until I run out of safe usable capacity," not just "how long until all raw resources are consumed." Nutanix therefore lets administrators model capacity while preserving headroom for failure scenarios. The fixed 10% answer is too generic and not how Nutanix documents the option. Storage-only reservation also misses the fact that runway tracks CPU, memory, and storage dimensions. So, based on Nutanix's Auto Detect wording and the resilience-oriented design of runway planning, D is the most authentic answer. (Nutanix Portal)

67. Frage

An administrator is trying to move an asynchronous PD workload from one cluster to another by taking advantage of PD-Based DR when an error message is displayed in Prism.

Error updating protection domain. Protection domain is already active on source site " cluster name ". Please trigger migrate from source site to activate the protection domain.

What would cause this error to appear?

- A. Must " disable " first before trying to activate a PD
- **B. Trying to " activate " the PD while the primary cluster is reachable**
- C. Must " Promote " the secondary site first before activating
- D. VMs must be migrated from the VM page instead of using DR

Antwort: B

Begründung:

Nutanix documentation for Performing Failover in PD-based DR includes the exact error message quoted in the question: "Protection domain is already active on source site ... Please trigger migrate from source site to activate the protection domain." Nutanix shows this message when the protection domain is still active on the source cluster and the proper action is a planned migrate from the source, not an activate at the target. In other words, the source cluster is still reachable and authoritative, so trying to activate the protection domain on the other side is the wrong operation. That makes D the correct answer. (Nutanix Portal) This is a classic Nutanix DR distinction between planned migration and unplanned failover/activation. If the primary cluster is still available, Nutanix expects the administrator to use migrate from the source site. Activation at the destination is reserved for failover conditions when the source cannot safely coordinate the move. The error itself tells you the reason if you read it carefully: the protection domain is still active on the source site. Therefore the root cause is that the administrator is trying to activate the PD while the primary cluster is still reachable and still owns the active copy, which is exactly option D. (Nutanix Portal)

68. Frage

An administrator has been tasked to remove a node from a Nutanix cluster running SQL VMs to help with a hardware refresh. After the node removal started, the administrator received the following error:

Node node_uuid cannot be removed: Cluster needs at least 5 usable nodes.

What action does the administrator need complete to remove the node?

- **A. Add the replacement node to the cluster first and then remove the original node.**

- B. Change the cluster Replication Factor (RF) to RF2 and then remove the node.
- C. Shutdown the CVM and use ncli to force the removal of the node.
- D. Change the storage containers Replication Factor (RF) to RF2 and remove the node.

Antwort: A

Begründung:

The error message is tied to resilience requirements. Nutanix documentation states that Replication Factor 3 requires at least five nodes so data remains online even if two nodes fail concurrently. If removing a node would drop the cluster below the minimum usable-node requirement, Nutanix blocks the operation. The safest and supported way to proceed during a hardware refresh is to add the replacement node first, restore compliant cluster capacity, and then remove the original node. (Nutanix Portal) The wrong answers all involve bypassing or weakening resilience inappropriately. Changing cluster or container RF to RF2 just to remove a node would reduce fault tolerance and is not the right answer for a SQL environment where resilience matters. Force-removal is also not the supported operational answer in a healthy refresh workflow. This question tests whether the administrator understands that node lifecycle actions are constrained by Nutanix fault-tolerance rules. When the cluster says it needs at least five usable nodes, the correct action is not to override the rule but to satisfy it by adding capacity first. Therefore A is the correct answer. (Nutanix Portal)

69. Frage

An administrator supports multiple AHV clusters under Prism Central and uses Intelligent Operations playbooks for remediation. The organization recently standardized alert policies, but the alert policy names and IDs change between environments due to automated deployments and periodic updates.

The requirement is to trigger a remediation playbook for any alert that matches a defined performance pattern (for example, impact type and severity plus a keyword pattern), regardless of which specific alert policy generated it, while avoiding unrelated non-performance alerts.

Which playbook trigger best meets the requirement?

- A. Alert trigger - configured to a single alert policy so the playbook triggers only when that specific policy generates an alert.
- B. Webhook trigger - configured so an external system calls the playbook endpoint only when performance incidents are detected.
- C. Event trigger - configured for a single event type so the playbook triggers when that event type is generated for the selected entities.
- **D. Alerts Matching Criteria trigger - configured with the required alert filters so the playbook triggers for any alert meeting the criteria.**

Antwort: D

Begründung:

The key requirement here is that the playbook must fire based on a pattern of alert characteristics, not on one fixed alert policy name or ID. Nutanix Intelligent Operations documentation provides a trigger type specifically for this purpose: Alerts Matching Criteria. That trigger lets administrators filter alerts using criteria such as severity, type, title patterns, and similar attributes, which is exactly what is needed when policy identifiers vary across environments but the response logic should stay consistent. It avoids binding the playbook to one alert definition and instead binds it to the alert behavior that matters operationally. (Nutanix) A single Alert trigger would be too brittle because it ties the automation to one named alert policy. A Webhook trigger would move the matching logic outside Prism and add unnecessary external dependency when the requirement can already be met natively. An Event trigger is also too broad or mismatched because the question is explicitly about filtering alerts by performance-related characteristics. Nutanix created "Alerts Matching Criteria" to handle precisely this kind of cross-environment, pattern-based automation. Therefore, A is the best answer because it gives the administrator scalable, environment-agnostic remediation logic while still excluding unrelated alerts through filters. (Nutanix)

70. Frage

An administrator needs to be able to use remaining capacity for storage and memory.

What settings should the administrator set to accomplish this?

- A. Capacity High Availability and Memory Reservation
- B. Storage Capacity and Memory High Availability
- C. Rebuild Capacity Reservation and Memory Reservation
- **D. Rebuild Capacity Reservation and High Availability**

Antwort: D

Begründung:

Nutanix separates storage resiliency reservation from compute high availability. For storage, the relevant setting is Rebuild Capacity Reservation, which reserves storage space so the cluster can self-heal and rebuild after node, block, or rack failure. For memory and compute, the relevant concept is High Availability, which reserves or accounts for host resources needed to restart workloads after a host failure. Putting those together gives the combination that best governs the remaining usable storage and memory capacity while preserving fault tolerance. That makes C the most correct answer.

The distractors either use non-standard phrasing or split the concepts incorrectly. "Memory Reservation" by itself is not the standard Nutanix answer when the exam is asking about cluster-wide restart capacity and usable memory after failure accounting. Nutanix administrators think in terms of HA for compute-memory protection and rebuild capacity reservation for storage protection. If the goal is to manage the usable remaining capacity for both storage and memory correctly, the right pair is Rebuild Capacity Reservation and High Availability. Therefore C is the authentic answer.

71. Frage

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