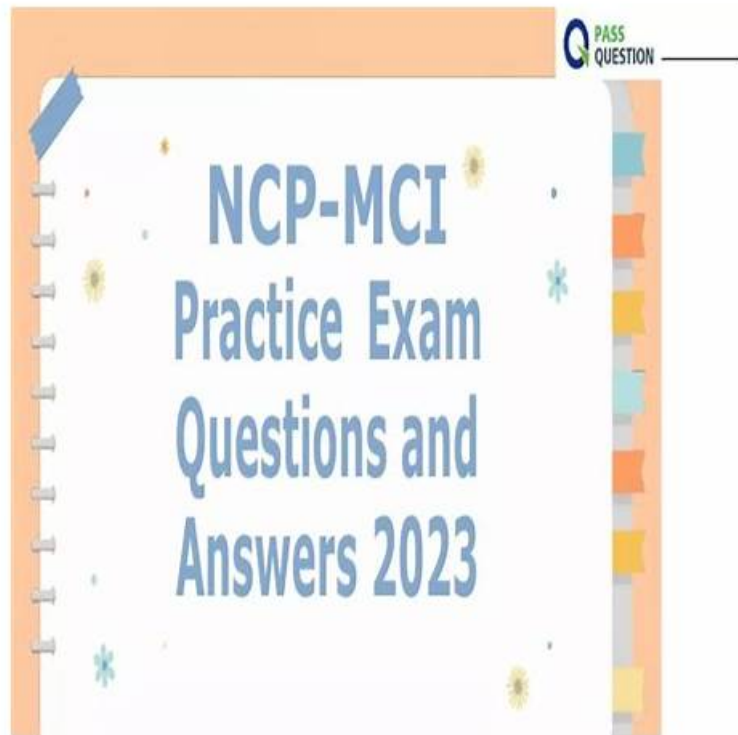


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## Nutanix Certified Professional - Multicloud Infrastructure (NCP-MCI) 7.5 Sample Questions (Q75-Q80):

### NEW QUESTION # 75

An administrator is tasked with configuring a remote site for Data Protection. At the source site, the VMs are in a storage container named Marketing, but they need the data to be replicated to a storage container named Backups at the destination site.

What must be configured in order to accomplish this goal?

- A. vStore PD
- B. Network mapping
- C. vStore mapping
- D. Network Compression

**Answer: C**

Explanation:

In Nutanix PD-based disaster recovery, when the source storage container name and the destination storage container name are different, the administrator must explicitly configure a vStore mapping. Nutanix documentation says that each vStores entry maps a local source storage container to a remote target storage container. Nutanix also documents that if you want replication from a local vStore to a remote vStore with different names, you provide the mapping between the local and target containers. That is exactly what this question is asking: source container Marketing, destination container Backups, and replication must know how those two names correspond. ( Nutanix Portal ) The other choices do not control storage-container placement for replicated data. Network mapping is about network connectivity for failover or recovery testing, not where the storage data lands. Network compression is unrelated to container targeting. vStore PD is not the Nutanix feature name that solves this requirement.

Nutanix's own remote-container best-practice guidance recommends establishing vStore mappings so the target container is deterministic and properly aligned to the protection design. Therefore, the correct and authentic Nutanix answer is C. vStore mapping. ( Nutanix Portal )

### NEW QUESTION # 76

An administrator is configuring Runway Analysis settings in Prism Central and selects Auto Detect under Reserve Capacity For Failure.

How will runway capacity be calculated in this configuration?

- A. The runway analysis reserves capacity only for storage resources while CPU and memory remain unchanged.
- B. The runway analysis excludes the resources of the largest node so estimates account for a node failure.
- C. The runway analysis calculates capacity using the full cluster resources but automatically adds a performance buffer.
- D. The runway analysis reserves a fixed 10% of cluster CPU, memory, and storage capacity by default.

**Answer: B**

Explanation:

Nutanix documentation for Updating Capacity Configurations explains that the Reserve Capacity For Failure option determines whether runway analysis should account for the impact of a node failure, and when Auto Detect is selected, Prism Central automatically uses the cluster's failure assumptions rather than the full unconstrained cluster total. In practical runway terms, that means the calculation reflects the loss of the node whose failure would have the greatest effect on usable capacity. Among the provided options, the best match for that documented logic is D: the runway analysis excludes the resources of the largest node so estimates account for a node failure. ( Nutanix Portal ) This behavior is important because runway is intended to answer "how long until I run out of safe usable capacity," not just "how long until all raw resources are consumed." Nutanix therefore lets administrators model capacity while preserving headroom for failure scenarios. The fixed 10% answer is too generic and not how Nutanix documents the option. Storage-only reservation also misses the fact that runway tracks CPU, memory, and storage dimensions. So, based on Nutanix's Auto Detect wording and the resilience-oriented design of runway planning, D is the most authentic answer. ( Nutanix Portal )

### NEW QUESTION # 77

An administrator is trying to migrate a VM to a new container. The Migration of vDisks stalls. What could be the cause of this?

- A. Insufficient storage space to create the target snapshot.
- B. Insufficient storage space to create the source snapshot.
- **C. Insufficient storage space in the target storage container.**
- D. Insufficient storage space in the local storage container.

**Answer: C**

Explanation:

A Nutanix vDisk live migration moves the VM's virtual disks into a new storage container while the VM remains online. For that to complete, the destination container must have enough available capacity to receive the migrated vDisk objects. If the target container lacks space, the migration can stall or fail because Nutanix cannot fully place the destination copy and complete the handoff. This makes insufficient storage space in the target storage container the most direct explanation. Nutanix migration and storage workflows consistently rely on adequate target-side capacity before the move can finish successfully. ( portal.nutanix.com ) The distractors are less precise. Source-side snapshots can be part of protection or internal workflow behavior, but the question is specifically about moving to a new container, so target capacity is the key gating factor.

"Local storage container" is too vague and is not the normal object referenced in this workflow.

Operationally, the right next step is to confirm free space, reservations, and any capacity constraints on the destination container before retrying the migration. That is why B is the best answer.

#### NEW QUESTION # 78

A corporate security policy mandates strict protection against boot-level rootkits and requires the isolation of NTLM password hashes from the running operating system to prevent "pass-the-hash" attacks.

During the initial testing phase, the administrator deploys a test VM using the standard AHV creation workflow. While configuring the guest operating system, administrator attempts to enable Windows Defender Credential Guard via Group Policy. However, the feature fails to start, and the system logs indicate that the underlying virtualization platform does not meet the necessary hardware security requirements.

Which specific configuration change must the administrator apply to the VM to satisfy the security policy requirements?

- A. Enable UEFI firmware, configure the disk controller to use the IDE bus, and add a vTPM device.
- B. Enable Generation 2 firmware, check the VBS flag, and add a vTPM device.
- **C. Enable UEFI firmware, check the Secure Boot option, and add a Virtual Trusted Platform Module (vTPM) device.**
- D. Enable Legacy BIOS firmware, check the Secure Boot option, and add a vTPM device.

**Answer: C**

Explanation:

Nutanix AHV documentation for Windows Defender Credential Guard support states that the VM must be configured with UEFI and Secure Boot enabled, and Nutanix security guidance for vTPM explains that vTPM is used to protect Windows credentials and is part of the trusted platform features required by modern Windows security functions. Together, these requirements map directly to option D: enable UEFI firmware, enable Secure Boot, and add a vTPM device.

The other options each contain a flaw. IDE is not the correct secure-boot bus choice in these workflows, legacy BIOS does not satisfy the modern secure boot requirement, and "Generation 2 firmware" is Hyper-V- oriented wording rather than the standard AHV requirement stated in Nutanix docs. The policy in the question explicitly mentions rootkit resistance and credential isolation, both of which are tied to Secure Boot and TPM- backed trust. Therefore Nutanix's documented VM configuration that satisfies those requirements is exactly what is described in D.

#### NEW QUESTION # 79

Which storage-optimization method is recommended for full clone VDI workloads?

- A. Thin Provisioning
- **B. Capacity deduplication**
- C. Erasure Coding
- D. Post-process map reduce

**Answer: B**

Explanation:

Nutanix documentation specifically identifies deduplication as providing the greatest benefit for common data sets, and it explicitly calls out full-clone VDI workloads as one of the strongest matches. In a full-clone desktop environment, many virtual desktops contain highly similar operating-system files, application binaries, and repeated data blocks. Capacity deduplication is designed to eliminate those repeated blocks and therefore reduce the total physical storage consumed by the environment. This is exactly why Nutanix recommends deduplication for such use cases.

The other answers are less targeted. Thin provisioning is useful generally but is not the signature optimization for repeated-content VDI storage. Erasure coding is powerful for write-cold data and capacity efficiency, but it is not the primary answer Nutanix recommends for full-clone VDI patterns. "Post-process map reduce" is not the standard storage-efficiency answer expected in this context. For exam purposes, whenever Nutanix asks about full-clone VDI, the important association is with capacity deduplication, because that feature directly exploits the high block similarity across cloned desktops. Therefore B is the correct and most authentic answer.

## NEW QUESTION # 80

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