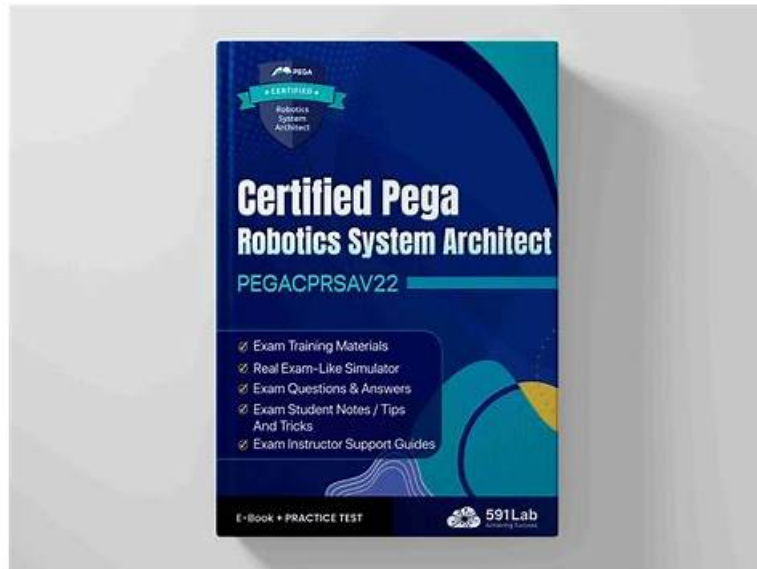


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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q65-Q70):

NEW QUESTION # 65

Which two statements are valid for the given automation? (Choose two.)

- A. Assign Main[b]NearestStore with the new value when the value of the NearestStore changes.

- B. Assign Main[b]NearestStore with the new value only if the value changed belongs to an active key.
- C. The value of the NearestStore changes when the automation is initiated.
- D. The automation is initiated when the value of the NearestStore changes.

Answer: B,C

NEW QUESTION # 66

You are designing an attended project for a banking customer. This project requires you to import new customers from a text file to a lookup table.

Which steps do you take to gain access to the ImportDelimitedFile method of the lookup table within an automation?

- A. Drag the lookup table from the Locals section of the Palette to the automation surface to open the Select action window, and then filter for the ImportDelimitedFile method.
- B. Open the Globals tab, filter for the ImportDelimitedFile method, and then drag it to the design surface.
- C. Drag the lookup table from the Globals section of the Palette to the automation surface to open the Select action window, and then filter for the ImportDelimitedFile method.
- D. Select the ImportDelimitedFile method in a design form of the user interface to open the Select action window.

Answer: C

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The Lookup Table is a global component in Pega Robot Studio that can be accessed from multiple automations within a project. To use its methods-such as ImportDelimitedFile, FindRecord, or AddRecord-you must drag the lookup table instance from the Globals section to the automation surface.

According to the Pega Robotics System Design and Implementation Guide, section "Using Lookup Tables in Automations":

"Lookup tables are global components that store data used across automations.

To call lookup table methods, drag the table from the Globals section of the Palette to the automation design surface.

The Select Action dialog box will open, allowing you to filter and select from available methods such as ImportDelimitedFile, FindRecord, and ClearTable." Detailed Reasoning:

* A. Select the ImportDelimitedFile method in a design form... - Incorrect. The lookup table is not part of the UI form

* B. Drag the lookup table from the Locals section... - Incorrect. Lookup tables exist under Globals, not Locals.

* C. Open the Globals tab and filter... - Incorrect. You must drag the component onto the automation surface to expose its methods.

* D. Drag the lookup table from the Globals section... - Correct. This exposes the ImportDelimitedFile method through the Select Action dialog.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Lookup Tables and Global Data Components section (Pega Robotics 19.1 and later).

NEW QUESTION # 67

You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.

Why are you unable to interrogate the desired application controls?

- A. The StartOnProject property of the application is set to false.
- B. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- C. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- D. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.

Answer: D

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.

According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:

"The StartMethod property defines how Pega Robot Studio connects to or starts an application.

When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.

If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:

- * The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.

- * For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).

- * If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.

- * As a result, the bullseye tool will not function because no valid application handle is established for interrogation.

Option Analysis:

- * A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.

- * B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.

- * C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.

- * D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation. Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration - StartMethod and Path Property Requirements section (Pega Robotics 19.1 and later).

NEW QUESTION # 68

When interrogating an application in a Chrome or Edge browser without X-ray Vision enabled, Pega Robot Studio uses only three match rules to uniquely identify the control. Which three match rules does Pega Robot Studio use when interrogating Chrome or Edge? (Choose Three)

- A. Web Control Children match rule
- B. Property Value match rule
- C. Control Children match rule
- D. Attribute Value match rule
- E. Element Path match rule
- F. Native Control match rule

Answer: B,D,E

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

According to the Pega Robotics Interrogation and Matching Engine Documentation:

"When you interrogate controls in a web application using Chrome or Edge browsers without X-ray Vision, Pega Robot Studio utilizes a simplified set of match rules because these browsers do not expose a full DOM structure with automation identifiers." The documentation specifies:

"In non-X-ray Vision interrogation mode, the following three match rules are applied automatically to identify a control:

- * Attribute Value Match Rule - Matches a control by its defined attribute (such as 'id', 'name', or 'class').

- * Property Value Match Rule - Matches the control based on its property values exposed during interrogation (for example, 'InnerText' or 'TagName').

- * Element Path Match Rule - Matches the control by its relative position in the DOM hierarchy." It also states:

"Without X-ray Vision, browser-specific identifiers and deep hierarchical context are not available; therefore, only the Attribute Value, Property Value, and Element Path rules are utilized for Chrome and Edge interrogation." References (Exact Extract Source):

- * Pega Robotics Studio User Guide - Web Adapter and Match Rules Section

- * Pega Academy - Robotics System Architect Course (Interrogation in Web Applications)

- * Pega Robotics Help - Interrogation with and without X-ray Vision

Final Verified answer: B, C, F

NEW QUESTION # 69

You interrogated a web application. All controls and objects matched, and the automations worked as coded.

During the pilot, the solution failed on the web application. The IT department had released a new version of the web application.

Upon review of the new version, you determined that the web page hierarchy changed.

Which interrogation option do you use to correct the solution?

- A. Select Element
- B. Debug Matching
- C. Replace Control
- D. Default

Answer: C

Explanation:

References:

NEW QUESTION # 70

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