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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q65-Q70):

NEW QUESTION # 65
Which two of the following Tool Windows are used in Pega Robot Studio? (Choose two.)

- A. Menu toolbar
- B. Solution Explorer
- C. Object Explorer
- D. Designer windows

Answer: A,D

NEW QUESTION # 66
While preparing for packaging and deployment, you decide to remove all remaining breakpoints from the automations in each project.
Which two ways can you delete automation breakpoints? (Choose Two)

- A. Click a breakpoint in an automation, and then press the Delete key.
- B. Right-click a breakpoint in an automation, and then select Remove Breakpoint.
- C. Use the hot keys to remove each automation link that includes a breakpoint.
- D. Right-click an automation on the automation surface, and then select Delete all breakpoints.
- E. Clear all automation breakpoints in the Breakpoints tab of the Debugging tools window.

Answer: B,E

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
When debugging automations in Pega Robot Studio, breakpoints are used to pause execution at specific points in an automation to inspect data and control flow. Before deploying or packaging a robotic solution, it is recommended to remove or clear all breakpoints to ensure that the production build executes uninterrupted.
According to the Pega Robotics System Design and Implementation Guide, section "Debugging Automations and Managing Breakpoints":
"Breakpoints can be added, enabled, disabled, or deleted directly from the automation design surface or from the Debugging Tools window.
To remove breakpoints, developers can:
* Right-click a breakpoint in the automation and select Remove Breakpoint.
* Clear all breakpoints globally from the Breakpoints tab within the Debugging Tools window.
Breakpoints are maintained per automation and persist between sessions until manually removed or cleared." Detailed Reasoning:
* A. Clear all automation breakpoints in the Breakpoints tab of the Debugging tools window.
* Correct. This is the global method to remove all existing breakpoints across multiple automations at once.
* The Breakpoints tab under Debug # Windows # Breakpoints lists every active breakpoint and includes the Clear All option to delete them.
* B. Right-click a breakpoint in an automation, and then select Remove Breakpoint.
* Correct. This is the direct method for deleting an individual breakpoint from within a specific automation.
* C. Use the hot keys to remove each automation link that includes a breakpoint.
* Incorrect. There is no hot key dedicated to breakpoint removal in Pega Robot Studio.
* D. Right-click an automation on the automation surface, and then select Delete all breakpoints.
* Incorrect. There is no such option available at the automation (background surface) level.
Breakpoints are only removable individually or through the Breakpoints tab.
* E. Click a breakpoint in an automation, and then press the Delete key.
* Incorrect. The Delete key removes automation components, not debugging breakpoints.

Final Correct Answers:

A). Clear all automation breakpoints in the Breakpoints tab of the Debugging tools window.

B). Right-click a breakpoint in an automation, and then select Remove Breakpoint.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Debugging Automations - Managing, Disabling, and Removing Breakpoints section (Pega Robotics 19.1 and later).

NEW QUESTION # 67

Match this robot activity completion status on the left to the unattended automation scenario on the right.

Answer:

Explanation:

Explanation:

In Pega Robot Studio, when an automation (especially one invoked as a robot activity by Pega Platform) finishes execution, it must return a Completion Status. This status helps the Pega Platform determine the outcome of the automation and decide whether to continue the workflow, retry, or handle an exception.

According to the Pega Robotics System Design and Implementation Guide, section "Robot Activity Completion Status and Workflow Integration":

"Each robotic activity returns a Completion Status to the Pega Platform after execution.

The completion status communicates the final outcome of the automation's operation, indicating whether it successfully completed, encountered errors, or produced invalid data.

The most common statuses used are:

* Complete: The automation ran successfully, and data passed all validation checks.

* DidNotComplete: The automation ran to completion, but business validation failed or data was deemed invalid.

* CompletedWithErrors: The automation could not complete execution due to a system or process error." Detailed Reasoning:

* Complete

* Indicates that the robotic automation successfully executed and the resulting data passed all validation checks within Pega.

* This allows the Pega case flow to continue normally.

* Correct Match: "If data passes business validation, the processing flow continues."

* CompletedWithErrors

* Used when the automation fails to complete due to a technical issue or system error (for example, an application did not load or a connector failed).

* This causes the flow to route as a failure in Pega.

* Correct Match: "If the automation fails to complete, it routes as a failure."

* DidNotComplete

* Indicates that the automation successfully executed technically but failed business validation, such as incorrect data, missing inputs, or business rule mismatches.

* Correct Match: "If the automation completes processing, but the data fails business validation." Final Correct Matching Order:

Completion Status

Automation Description

Complete

If data passes business validation, the processing flow continues.

CompletedWithErrors

If the automation fails to complete, it routes as a failure.

DidNotComplete

If the automation completes processing, but the data fails business validation.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Robot Activity Completion Status - RPA and RDA Integration Behavior section (Pega Robotics 19.1 and later).

NEW QUESTION # 68

An application includes Assisted Sign-On by default with Pega Robot Studio?

- A. Pega Sales Automation
- B. Pega Customer Service
- C. Pega Customer Decision Hub
- D. Pega Robot Manager

Answer: B

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
Assisted Sign-On (ASO) is a feature of Pega Robot Studio that allows users to securely store and automatically populate login credentials for applications used in automations.
By default, Pega Customer Service (PCS) applications are integrated with Assisted Sign-On to streamline agent desktop interactions and reduce manual logins when launching multiple applications.
According to the Pega Robotics System Design and Implementation Guide, section "Assisted Sign-On Integration with Pega Applications":
"Pega Customer Service applications include Assisted Sign-On by default.
This feature uses Credential Manager and Runtime configuration to securely authenticate users across multiple enterprise systems during attended robotic operations." Detailed Reasoning:
* A. Pega Sales Automation - Does not include ASO by default.
* B. Pega Customer Decision Hub - Focused on decision management, not attended user login automation.
* C. Pega Customer Service - Correct. Assisted Sign-On is preconfigured for Customer Service use cases to streamline agent authentication.
* D. Pega Robot Manager - Used for deployment and management of bots, not for user authentication.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Assisted Sign-On (ASO) Configuration and Customer Service Integration section (Pega Robotics 19.1 and later).

NEW QUESTION # 69
You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.
Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- B. The StartOnProject property of the application is set to false.
- C. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.
- D. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.

Answer: C

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application.
When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.
According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:
"The StartMethod property defines how Pega Robot Studio connects to or starts an application.
When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.
If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:
* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.
Option Analysis:
* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation.
Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration - StartMethod and Path Property Requirements section (Pega Robotics
19.1 and later).

NEW QUESTION # 70

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