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## Huawei HCIP-AI-EI Developer V2.5 Sample Questions (Q51-Q56):

### NEW QUESTION # 51

If OpenCV is used to read an image and save it to variable "img" during image preprocessing, (h, w) = img.shape[:2] can be used to obtain the image size.

- A. FALSE
- **B. TRUE**

**Answer: B**

Explanation:

In OpenCV, an image read into a variable such as img is represented as a NumPy array. The .shape attribute returns the dimensions in the format (height, width, channels). Using img.shape[:2] slices the first two elements, giving the height (h) and width (w). This method is a standard practice for quickly retrieving image dimensions in preprocessing workflows.

Exact Extract from HCIP-AI EI Developer V2.5:

"OpenCV stores images as NumPy arrays. The shape property returns (height, width, channels). Accessing shape[:2] returns the image height and width." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Image Reading and Writing with

#### NEW QUESTION # 52

The accuracy of object location detection can be evaluated using the intersection over union (IoU) value, which is a ratio. The denominator is the overlapping area between the prediction bounding box and ground truth bounding box, and the numerator is the area of union encompassed by both boxes.

- A. TRUE
- B. FALSE

**Answer: B**

Explanation:

The IoU metric is defined as:

$$\text{IoU} = (\text{Area of Overlap}) / (\text{Area of Union})$$

\* Numerator: Area of overlap between the predicted bounding box and the ground truth bounding box.

\* Denominator: Area of union of both bounding boxes.

The statement given in the question reverses the numerator and denominator, which is why it is incorrect. IoU is crucial for object detection evaluation, and higher IoU values indicate better localization accuracy.

Exact Extract from HCIP-AI EI Developer V2.5:

"Intersection over Union (IoU) is calculated as the ratio of the intersection area between prediction and ground truth bounding boxes to their union area." Reference: HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Object Detection Metrics

#### NEW QUESTION # 53

The technologies underlying ModelArts support a wide range of heterogeneous compute resources, allowing you to flexibly use the resources that fit your needs.

- A. FALSE
- B. TRUE

**Answer: B**

Explanation:

ModelArts is built to support a variety of compute resources, including CPUs, GPUs, and Ascend AI processors. This heterogeneous resource pool allows users to select the hardware that best matches their training or inference requirements, ensuring cost efficiency and optimal performance for different workloads.

Exact Extract from HCIP-AI EI Developer V2.5:

"ModelArts supports heterogeneous compute environments, enabling selection among CPUs, GPUs, and Ascend processors for flexible AI development." Reference: HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: ModelArts Infrastructure

#### NEW QUESTION # 54

Huawei Cloud ModelArts is a one-stop AI development platform that supports multiple AI scenarios. Which of the following scenarios are supported by ModelArts?

- A. Image classification
- B. Speech recognition
- C. Object detection
- D. Video analytics

**Answer: A,B,C,D**

Explanation:

ModelArts provides an integrated environment for data labeling, model training, deployment, and management, supporting various AI application scenarios:

\* Image classification for categorizing visual content.

\* Object detection for locating and identifying multiple objects in images or video frames.

\* Speech recognition for converting speech to text.

\* Video analytics for automated video content analysis.

Exact Extract from HCIP-AI EI Developer V2.5:

"ModelArts supports a wide range of AI tasks including image classification, object detection, speech recognition, and intelligent video analytics." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: ModelArts Overview

### NEW QUESTION # 55

Which of the following statements about the functions of the encoder and decoder is true?

- A. The encoder converts context vectors into variable-length output sequences.
- B. The output lengths of the encoder and decoder are the same.
- C. The decoder converts variable-length input sequences into fixed-length context vectors, encoding the information of the input sequences in the context vectors.
- **D. The encoder converts variable-length input sequences into fixed-length context vectors, encoding the information of the input sequences in the context vectors.**

**Answer: D**

Explanation:

In an encoder-decoder architecture:

\* The encoder processes variable-length inputs and encodes them into fixed-length context vectors that summarize the input. (C is correct.)

\* The decoder generates output sequences from this context, which may be of variable length.

\* A describes the decoder incorrectly; B mixes roles; D is false because output length depends on the target sequence, not the encoder output length.

Exact Extract from HCIP-AI EI Developer V2.5:

"The encoder transforms variable-length sequences into context vectors, which the decoder uses to generate variable-length outputs." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Encoder-Decoder Functions

### NEW QUESTION # 56

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