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## **Nutanix Certified Professional - Multicloud Infrastructure (NCP-MCI) 7.5**

## Sample Questions (Q48-Q53):

### NEW QUESTION # 48

An administrator needs to adjust the settings of an existing virtual machine. Which parameter is restricted from modification once the VM has been created?

- A. vCPU count
- B. Boot priority
- C. Memory allocation
- **D. BIOS mode**

**Answer: D**

Explanation:

Nutanix documentation for updating a VM through Prism Central states explicitly: "BIOS mode: You cannot modify the BIOS mode after the VM is created." That wording directly answers the question and makes A the correct option. By contrast, vCPU count and memory allocation are common VM settings that administrators can adjust as part of lifecycle management, and boot priority can also be changed in supported conditions.

The only one Nutanix calls out as restricted after creation is the BIOS mode. (Nutanix Portal) This reflects how foundational firmware mode is to VM identity and boot architecture. Once the VM is created using Legacy BIOS or UEFI, many guest-OS assumptions, boot-device structures, and security options depend on that original firmware model. Nutanix therefore locks this parameter after creation instead of treating it as an ordinary runtime edit. For exam preparation, this is a classic item to memorize: CPU and memory can generally be changed, but BIOS mode cannot be modified after VM creation. So the authentic Nutanix answer here is A. BIOS mode. (Nutanix Portal)

### NEW QUESTION # 49

A Windows VM will be cloned repeatedly and each clone needs OS-level customization during deployment. What is the most efficient method to accomplish this task?

- **A. Guest customization profile**
- B. Create template for each deployment
- C. Clone and manually configure
- D. Create a VM from snapshot

**Answer: A**

Explanation:

Nutanix documents guest customization profiles as reusable operating-system customization definitions that can be applied during VM deployment. This is precisely what makes them the most efficient answer when a Windows VM will be cloned repeatedly and each clone requires OS-level customization such as naming, identity settings, or first-boot configuration. Instead of creating a separate template each time or manually editing each deployed clone, the administrator creates one reusable customization profile and applies it across deployments. That makes C the correct answer.

This is especially important at scale. Manual post-clone configuration is error-prone and time-consuming, while per-deployment templates create management sprawl. Nutanix's design encourages reusable policy- or profile-based standardization so that repeated deployments remain consistent and secure. For Windows, that typically means Sysprep-oriented OS customization combined with reusable deployment logic. In other words, the question is asking for the most efficient method, and Nutanix's documented answer to repeatable OS customization is the guest customization profile. Therefore C is the authentic choice.

### NEW QUESTION # 50

How many S3 targets are supported for Prism Central point-in-time backups?

- A. 0
- **B. 1**
- C. 2
- D. 3

**Answer: B**

Explanation:

Nutanix documentation for Prism Central point-in-time backup states that the system supports one point-in-time backup target at a time. Nutanix further documents that Prism Central can be backed up to registered clusters, Nutanix Objects, AWS S3, or generic S3-compliant storage, but the platform still supports only one active point-in-time backup target concurrently. Therefore the correct answer is A. 1.

This question is easy to overthink because the product supports multiple target types, but that is different from supporting multiple simultaneous configured S3 targets for one Prism Central instance. Nutanix's wording is explicit and leaves little ambiguity: one backup target at a time. That means answers B, C, and D are not consistent with the documented PC backup design. So for a study guide grounded in current official Nutanix documentation, the authentic answer is A.

#### NEW QUESTION # 51

An administrator receives intermittent "VM I/O latency" complaints from two application teams that share the same AHV cluster. In Prism Central, multiple performance-related alerts appear across the same 30 minute window, but only some VMs are impacted. The administrator needs to collect the most relevant platform logs for escalation, minimizing noise and ensuring the bundle covers the exact time window when the alert condition occurred. The organization also requires that the log bundle can be attached to a support case without manual repackaging.

Which approach best satisfies the requirement?

- A. Enable auto-resolve for the alert policy so the alert clears after the condition stops, then collect logs later if the alert returns.
- B. Create a new custom alert policy with a stricter threshold so the alert triggers more consistently, then rely on the alert history instead of collecting logs.
- C. Export the Alerts list to CSV (up to the export limit), then attach the CSV to the case as the primary diagnostic artifact for performance troubleshooting.
- **D. In the alert details, identify impacted entities and timestamps, collect logs for the relevant time window, and upload the bundle using a case-number upload option.**

**Answer: D**

Explanation:

Nutanix documentation for log collection in Prism Central and related Logbay guidance supports collecting logs for a specific time range, which is exactly what this question requires to minimize noise and capture only the relevant 30-minute incident window. Nutanix also documents that when sending logs to Nutanix Support FTP, the administrator can enter a support case number, allowing the bundle to be attached to the case without manual repackaging. That makes D the strongest answer: use the alert details to identify the impacted entities and timestamps, collect the logs for that time window, and upload them using the support-case workflow. (Nutanix Portal) The other options do not produce the right diagnostic artifact. Auto-resolve only affects alert state, not log quality. Tightening thresholds may generate more alerts, but it does not replace collecting platform logs. Exporting a CSV of alerts can help summarize incidents, but it is not the primary evidence Nutanix Support needs for performance troubleshooting. Nutanix's supported model is very clear: identify the incident timing, collect the appropriate logs for that window, and upload the bundle in a support-compatible way. Therefore D is the authentic answer from a Nutanix troubleshooting workflow perspective. (Nutanix Portal)

#### NEW QUESTION # 52

What is the minimum number of nodes required for a storage container with Replication Factor 2 and Erasure Coding?

- A. 0
- B. 1
- C. 2
- **D. 3**

**Answer: D**

Explanation:

Nutanix documentation for Erasure Coding is explicit: a cluster must have a minimum of four nodes to enable erasure coding, and for RF2 the minimum remains four nodes. Nutanix further explains that RF3 with erasure coding requires six nodes, which helps distinguish the two thresholds clearly for exam purposes. Since the question asks specifically about Replication Factor 2 and Erasure Coding, the minimum supported node count is 4. (Nutanix) This question is testing one of the most common node-count rules in Nutanix storage efficiency. A three-node cluster can provide RF2 storage, but that does not automatically mean erasure coding is available there.

Erasure coding introduces its own resiliency and stripe-width requirements, and Nutanix sets the minimum at four nodes for RF2. The values 5 and 6 are distractors meant to confuse RF2 and RF3 rules. Because the official requirement is four nodes for RF2 EC,

the correct answer is B. ( Nutanix )

## NEW QUESTION # 53

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