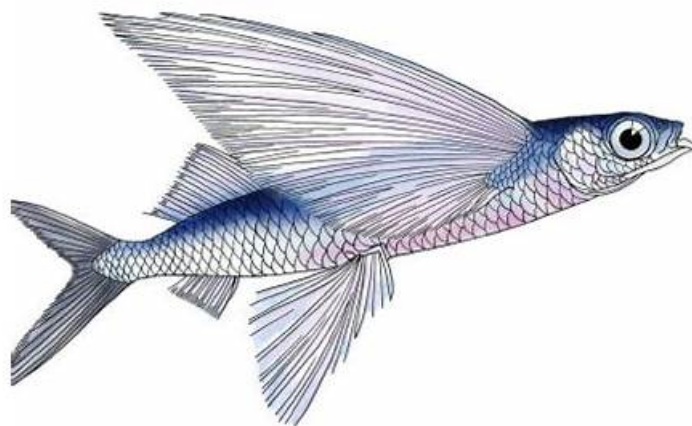


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Kubernetes and Cloud Native Associate (KCNA) Study Guide

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& Jorge Valenzuela

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Linux Foundation Kubernetes and Cloud Native Associate Sample Questions (Q174-Q179):

NEW QUESTION # 174

Which of the following is a challenge derived from running cloud native applications?

- A. The lack of different container images available in public image repositories.
- B. The operational costs of maintaining the data center of the company.
- C. Cost optimization is complex to maintain across different public cloud environments.
- D. The lack of services provided by the most common public clouds.

Answer: C

Explanation:

The correct answer is B. Cloud-native applications often run across multiple environments-different cloud providers, regions, accounts/projects, and sometimes hybrid deployments. This introduces real cost-management complexity: pricing models differ (compute types, storage tiers, network egress), discount mechanisms vary (reserved capacity, savings plans), and telemetry/charge attribution can be inconsistent. When you add Kubernetes, the abstraction layer can further obscure cost drivers because costs are incurred at the infrastructure level (nodes, disks, load balancers) while consumption happens at the workload level (namespaces, Pods, services).

Option A is less relevant because cloud-native adoption often reduces dependence on maintaining a private datacenter; many organizations adopt cloud-native specifically to avoid datacenter CapEx/ops overhead. Option C is generally untrue-public registries and vendor registries contain vast numbers of images; the challenge is more about provenance, security, and supply chain than "lack of images." Option D is incorrect because major clouds offer abundant services; the difficulty is choosing among them and controlling cost/complexity, not a lack of services.

Cost optimization being complex is a recognized challenge because cloud-native architectures include microservices sprawl, autoscaling, ephemeral environments, and pay-per-use dependencies (managed databases, message queues, observability). Small misconfigurations can cause big bills: noisy logs, over-requested resources, unbounded HPA scaling, and egress-heavy architectures. That's why practices like FinOps, tagging/labeling for allocation, and automated guardrails are emphasized.

So the best answer describing a real, common cloud-native challenge is B.

NEW QUESTION # 175

What native runtime is Open Container Initiative (OCI) compliant?

- A. gvisor
- B. kata-containers
- C. runV
- D. runC

Answer: D

Explanation:

The Open Container Initiative (OCI) publishes open specifications for container images and container runtimes so that tools across the ecosystem remain interoperable. When a runtime is "OCI-compliant," it means it implements the OCI Runtime Specification (how to run a container from a filesystem bundle and configuration) and/or works cleanly with OCI image formats through the usual layers (image → unpack → runtime). runC is the best-known, widely used reference implementation of the OCI runtime specification and is the low-level runtime underneath many higher-level systems. In Kubernetes, you typically interact with a higher-level container runtime (such as containerd or CRI-O) through the Container Runtime Interface (CRI). That higher-level runtime then uses a low-level OCI runtime to actually create Linux namespaces/cgroups, set up the container process, and start it. In many default installations, containerd delegates to runC for this low-level "create/start" work.

The other options are related but differ in what they are: Kata Containers uses lightweight VMs to provide stronger isolation while still presenting a container-like workflow; gVisor provides a user-space kernel for sandboxing containers; these can be used with Kubernetes via compatible integrations, but the canonical "native OCI runtime" answer in most curricula is runC. Finally, "runV" is

not a common modern Kubernetes runtime choice in typical OCI discussions. So the most correct, standards-based answer here is A (runC) because it directly implements the OCI runtime spec and is commonly used as the default low-level runtime behind CRI implementations.

NEW QUESTION # 176

Explain the difference between a Deployment and a StatefulSet in Kubernetes.

- A. Deployments are used for stateless applications, while StatefulSets are used for stateful applications that require persistent storage and unique identities.
- B. Deployments handle rolling updates, while StatefulSets only support manual updates.
- C. Deployments are used for managing the lifecycle of a single Pod, while StatefulSets manage multiple Pods.
- D. Deployments are used for deploying and managing stateless applications, while StatefulSets are used for deploying and managing stateful applications.
- E. Deployments are responsible for scheduling Pods, while StatefulSets manage the lifecycle of Services.

Answer: A,D

Explanation:

Deployments are used for deploying and managing stateless applications, while StatefulSets are used for deploying and managing stateful applications. Deployments are ideal for applications where the state of each Pod is not important, while StatefulSets are designed for applications that require persistent storage, unique network identities, and ordered scaling.

NEW QUESTION # 177

Which of the following options include resources cleaned by the Kubernetes garbage collection mechanism?

- A. Terminated pods, completed jobs, and objects without owner references.
- B. Unused container and container images, and obsolete logs from the kubelet.
- C. Stale or expired CertificateSigningRequests (CSRs) and old deployments.
- D. Nodes deleted by a cloud controller manager and obsolete logs from the kubelet.

Answer: A

Explanation:

Kubernetes garbage collection (GC) is about cleaning up API objects and related resources that are no longer needed, so the correct answer is D. Two big categories it targets are (1) objects that have finished their lifecycle (like terminated Pods and completed Jobs, depending on controllers and TTL policies), and (2) "dangling" objects that are no longer referenced properly—often described as objects without owner references (or where owners are gone), which can happen when a higher-level controller is deleted or when dependent resources are left behind.

A key Kubernetes concept here is OwnerReferences: many resources are created "owned" by a controller (e.g., a ReplicaSet owned by a Deployment, Pods owned by a ReplicaSet). When an owning object is deleted, Kubernetes' garbage collector can remove dependent objects based on deletion propagation policies (foreground/background/orphan). This prevents resource leaks and keeps the cluster tidy and performant.

The other options are incorrect because they refer to cleanup tasks outside Kubernetes GC's scope. Kubelet logs (B/C) are node-level files and log rotation is handled by node/runtime configuration, not the Kubernetes garbage collector. Unused container images (C) are managed by the container runtime's image GC and kubelet disk pressure management, not the Kubernetes API GC. Nodes deleted by a cloud controller (B) aren't "garbage collected" in the same sense; node lifecycle is handled by controllers and cloud integrations, but not as a generic GC cleanup category like ownerRef-based object deletion.

So, when the question asks specifically about "resources cleaned by Kubernetes garbage collection," it's pointing to Kubernetes object lifecycle cleanup: terminated Pods, completed Jobs, and orphaned objects—exactly what option D states.

NEW QUESTION # 178

Which is the correct kubectl command to display logs in real time?

- A. kubectl logs -c test-container-1
- B. kubectl logs -f test-container-1
- C. kubectl logs -l test-container-1
- D. kubectl logs -p test-container-1

Answer: B

Explanation:

To stream logs in real time with `kubectl`, you use the follow option `-f`, so `D` is correct. In Kubernetes, `kubectl` logs retrieves logs from containers in a Pod. By default, it returns the current log output and exits. When you add `-f`, `kubectl` keeps the connection open and continuously prints new log lines as they are produced, similar to `tail -f` on Linux. This is especially useful for debugging live behavior, watching startup sequences, or monitoring an application during a rollout.

The other flags serve different purposes. `-p` (as seen in option A) requests logs from the previous instance of a container (useful after a restart/crash), not real-time streaming. `-c` (option B) selects a specific container within a multi-container Pod; it doesn't stream by itself (though it can be combined with `-f`). `-l` (option C) is used with `kubectl logs` to select Pods by label, but again it is not the streaming flag; streaming requires `-f`.

In real troubleshooting, you commonly combine flags, e.g. `kubectrl logs -f pod-name -c container-name` for streaming logs from a specific container, or `kubectrl logs -f -l app=myapp` to stream from Pods matching a label selector (depending on kubectrl behavior/version). But the key answer to "display logs in real time" is the follow flag: `-f`.

Therefore, the correct selection is D.

NEW QUESTION # 179

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