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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q58-Q63):

NEW QUESTION # 58

You can adjust how users interact with a robotics project on their desktops. Which file stores the settings that control user functions and desktop robotic access?

- A. PegaConfig.xml

- B. PegaStudioConfig.xml
- C. CommonConfig.xml
- **D. PegaRuntimeConfig.xml**

Answer: D

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The PegaRuntimeConfig.xml file contains configuration settings that control how users interact with Pega Robot Runtime on their desktops.

These settings define parameters such as:

- * Robot tray icon visibility
- * Notification preferences
- * Runtime startup behavior
- * Access permissions for attended automation

According to the Pega Robotics System Design and Implementation Guide, section "Runtime Configuration Settings":

"The PegaRuntimeConfig.xml file defines user interaction settings and behavior of Pega Robot Runtime on end-user desktops. It specifies configurations related to user access, tray icon visibility, notification pop-ups, and desktop automation permissions."

Detailed Reasoning:

- * A. PegaConfig.xml - Not a valid configuration file in Pega Robotics.
- * B. CommonConfig.xml - Used for shared system-wide connectivity and Robot Manager settings.
- * C. PegaStudioConfig.xml - Stores configuration data for Pega Robot Studio (developer-specific).
- * **D. PegaRuntimeConfig.xml - Correct. Defines desktop-level user interaction and Runtime behavior.**

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Runtime Configuration File Overview section (Pega Robotics 19.1 and later).

NEW QUESTION # 59

You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.

Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- **B. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.**
- C. The StartOnProject property of the application is set to false.
- D. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.

Answer: B

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.

According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:

"The StartMethod property defines how Pega Robot Studio connects to or starts an application.

When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.

If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:

- * The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
- * For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
- * If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
- * As a result, the bullseye tool will not function because no valid application handle is established for interrogation.

Option Analysis:

- * A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.

- * B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
- * C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
- * D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation. Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined. Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration - StartMethod and Path Property Requirements section (Pega Robotics 19.1 and later).

NEW QUESTION # 60

You are deploying a robotic project to Pega Robot Manager. Which file stores the Pega Robot Manager server settings?

- A. PegaConfig.xml
- B. PegaStudioConfig.xml
- C. PegaRuntimeConfig.xml
- **D. CommonConfig.xml**

Answer: D

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

When deploying robotic solutions to Pega Robot Manager, the connection and authentication details - such as Robot Manager server URL, authentication mode, and registration configuration - are stored in the file CommonConfig.xml.

This configuration file is shared between both Pega Robot Studio and Pega Robot Runtime, ensuring that both use consistent connectivity settings.

According to the Pega Robotics System Design and Implementation Guide, section "Pega Robot Manager Integration and Configuration Files":

"The CommonConfig.xml file contains shared configuration information that is used by both Pega Robot Studio and Pega Robot Runtime.

It includes global settings such as:

- * Connection information for Pega Robot Manager (URL, ports, authentication)
- * Deployment configuration values
- * Environment registration and runtime connectivity settings.

PegaRuntimeConfig.xml and PegaStudioConfig.xml are used for local settings only, while CommonConfig.xml stores the Robot Manager connection configuration used during deployment." Detailed Reasoning:

- * A. PegaStudioConfig.xml - Used for developer-specific configuration within Robot Studio, not for deployment or server settings.
- * B. CommonConfig.xml - Correct. This file contains the Robot Manager connectivity configuration and shared settings.
- * C. PegaRuntimeConfig.xml - Controls runtime behavior on client machines, not Robot Manager connections.
- * D. PegaConfig.xml - Not a valid configuration file in Pega Robotics.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Pega Robot Manager Configuration and CommonConfig.xml Overview section (Pega Robotics 19.1 and later).

NEW QUESTION # 61

When you debug an automation, you have three function keys to use for navigating the breakpoints. Drag each navigation rule on the left to the box next to the correct function key on the right.

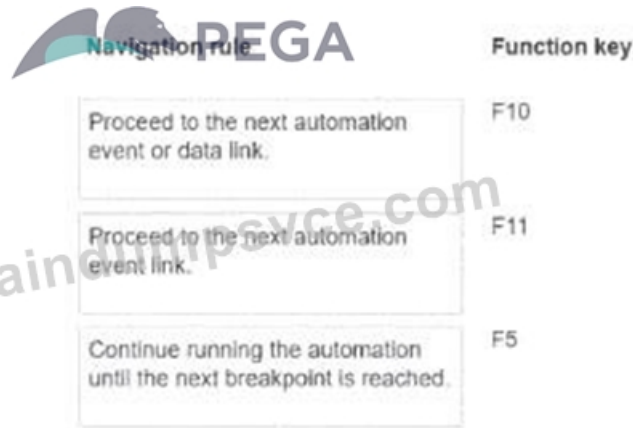
Navigation rule	Function key
Proceed to the next automation event or data link.	F10
Proceed to the next automation event link.	F11
Continue running the automation until the next breakpoint is reached.	F5

Answer:

Explanation:



Explanation:



When debugging automations in Pega Robot Studio, developers use specific function keys to control the flow of execution at breakpoints. Each key provides a distinct method for navigating through the automation logic during a debugging session. According to the Pega Robotics System Design and Implementation Guide, section "Debugging Automations - Function Keys and Breakpoint Navigation":

"During debugging, Pega Robot Studio allows you to step through the automation's logic using three primary navigation commands:

* F10 (Step Over): Executes the current step and proceeds to the next event or data link, without stepping into nested automations or sub-events.

* F11 (Step Into): Executes the current step and enters any nested event link or sub-automation to debug internal logic.

* F5 (Continue): Continues running the automation until the next breakpoint is encountered." Detailed Reasoning:

* F10 - Step Over

* Moves to the next automation event or data link at the same level.

* Skips over nested or child automations while still executing them.

* F11 - Step Into

* Moves into the next automation event link or nested automation to debug its internal process.

* Useful when you need to analyze detailed event flow inside another automation.

* F5 - Continue

* Resumes automation execution at normal speed until it encounters the next breakpoint or finishes.

* Used to verify execution results after setting conditional breakpoints.

Final Correct Matching:

Navigation Rule

Function Key

Proceed to the next automation event or data link.

F10

Proceed to the next automation event link.

F11

Continue running the automation until the next breakpoint is reached.

F5

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Debugging Automations - Step Over, Step Into, and Continue Execution section (Pega Robotics 19.1 and later).

NEW QUESTION # 62

Runtime produces an error when debugging a solution. The error message references that a control does not have the necessary value to complete an activity. The control depends upon the completion of a second activity in another project to provide its value. Which two debugging options provide a benefit when referencing threads for issue resolution? (Choose two.)

- A. Dissert a log file for propagating data
- B. Insert Try and Catch components to an automation
- C. Use the Automation Playback
- D. Add studio execution log entries

Answer: C,D

NEW QUESTION # 63

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