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## Huawei HCIP-AI-EI Developer V2.5 Sample Questions (Q61-Q66):

### NEW QUESTION # 61

The accuracy of object location detection can be evaluated using the intersection over union (IoU) value, which is a ratio. The denominator is the overlapping area between the prediction bounding box and ground truth bounding box, and the numerator is the area of union encompassed by both boxes.

- A. FALSE
- B. TRUE

**Answer: A**

Explanation:

TheIoUmetric is defined as:

$$IoU = (\text{Area of Overlap}) / (\text{Area of Union})$$

\* Numerator:Area of overlap between the predicted bounding box and the ground truth bounding box.

\* Denominator:Area of union of both bounding boxes.

The statement given in the question reverses the numerator and denominator, which is why it is incorrect. IoU is crucial for object detection evaluation, and higher IoU values indicate better localization accuracy.

Exact Extract from HCIP-AI EI Developer V2.5:

"Intersection over Union (IoU) is calculated as the ratio of the intersection area between prediction and ground truth bounding boxes to their union area." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Object Detection Metrics

### NEW QUESTION # 62

Vision transformer (ViT) performs well in image classification tasks. Which of the following is the main advantage of ViT?

- A. It can process high-resolution images to enhance classification accuracy.
- **B. The self-attention mechanism is used to capture global features of images, improving classification accuracy.**
- C. It can handle small datasets with minimal labeling required.
- D. It achieves fast convergence without using pre-trained models.

**Answer: B**

Explanation:

The Vision Transformer (ViT) applies the transformer architecture to image patches. Its key advantage is the use of self-attention to capture global dependencies and relationships between all parts of an image. This allows ViT to excel in classification accuracy, especially on large datasets with sufficient pre-training.

Exact Extract from HCIP-AI EI Developer V2.5:

"ViT applies self-attention to image patches, enabling global feature extraction and improving classification performance compared to local receptive fields in CNNs." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Transformer Models in Vision

### NEW QUESTION # 63

The development of large models should comply with ethical principles to ensure the legal, fair, and transparent use of data.

- **A. TRUE**
- B. FALSE

**Answer: A**

Explanation:

Ethical AI development requires ensuring that large models are trained and deployed in a way that respects laws, fairness, and transparency. This includes preventing bias, ensuring user privacy, protecting intellectual property, and being transparent about data usage and decision-making processes.

Exact Extract from HCIP-AI EI Developer V2.5:

"The development and deployment of large models must follow ethical principles to ensure legal, fair, and transparent use of data, avoiding bias and misuse." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Ethical AI Practices

### NEW QUESTION # 64

In an image preprocessing experiment, the `cv2.imread("lena.png", 1)` function provided by OpenCV is used to read images. The parameter "1" in this function represents a ----- -channel image. (Fill in the blank with a number.)

**Answer:**

Explanation:

3

Explanation:

In OpenCV:

\* `cv2.imread(filename, 1)` reads the image in color mode.

\* This loads the image as a 3-channel BGR image (Blue, Green, Red).

\* Other modes: 0 for grayscale, -1 for unchanged (including alpha channel).

Exact Extract from HCIP-AI EI Developer V2.5:

"When the second parameter of `cv2.imread` is 1, the image is read in color mode, resulting in a 3-channel BGR image."

### NEW QUESTION # 65

The image saturation can be enhanced by processing the \_\_\_\_\_ component of the HSV color space. (Enter H, S, or V.)

**Answer:**

Explanation:

S

Explanation:

In the HSV (Hue, Saturation, Value) color model:

- \* H represents hue (color type).
- \* S represents saturation (color intensity or vividness).
- \* V represents brightness.

To enhance saturation in an image, adjustments are made to the S component. Increasing S increases the color vividness, making the image appear more vibrant, while reducing S moves colors toward grayscale. This approach is widely used in image enhancement tasks, especially in object recognition and segmentation, where vivid colors improve feature contrast.

Exact Extract from HCIP-AI EI Developer V2.5:

"In HSV color space, saturation (S) describes the vividness of colors. Increasing the S value enhances saturation, making colors more intense, while decreasing it makes them closer to gray." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Image Processing Basics

### NEW QUESTION # 66

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