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TestKingFree has assembled a brief yet concise study material that will aid you in acing the Nutanix Certified Professional - Business Continuity (NCP-BC) 7.5 (NCP-BC-7.5) exam on the first attempt. This prep material has been compiled under the expert guidance of 90,000 experienced Nutanix professionals from around the globe. TestKingFree offers the complete package that includes all exam questions conforming to the syllabus for passing the Nutanix Certified Professional - Business Continuity (NCP-BC) 7.5 (NCP-BC-7.5) exam certificate in the first try.

Nutanix Certified Professional - Business Continuity (NCP-BC) 7.5 Sample Questions (Q18-Q23):

NEW QUESTION # 18

An organization uses a Recovery Plan to protect a SQL Cluster that relies on Volume Groups (VGs). The VGs are configured with hypervisor attachments. The administrator executes a Planned Failover to migrate the SQL Cluster to the Recovery Site. The Failover task completes successfully, but the database administrators report that the database is offline. What is the possible cause of this issue?

- A. An administrator failed to configure mapping for the Storage Network in the Recovery Plan.
- B. VGs cannot be protected by Recovery Plans.
- C. VGs configured with hypervisor attachments do not reattach automatically after recovery.
- D. An administrator failed to configure Protection Domains replication.

Answer: C

Explanation:

Volume Groups (VGs) are used in Nutanix to provide block storage to virtual machines, often for high-performance applications like SQL Server. VGs can be attached to VMs in two ways: "In-guest" (using iSCSI initiators) or "Hypervisor-attached" (where the hypervisor handles the connection).

In a disaster recovery scenario managed by Recovery Plans, there is a technical distinction in how these attachments are handled. While Nutanix Disaster Recovery can replicate the data in the Volume Groups and recover the VM itself, VGs that are "hypervisor-attached" do not currently support automatic reattachment as part of the orchestration workflow in all AOS versions. When the failover completes, the VM powers on at the recovery site, but the VGs are not connected to the VM at the hypervisor level. This causes the application (SQL) to find its data disks missing, resulting in the database staying offline. To resolve this, the administrator must manually reattach the Volume Groups to the VM at the recovery site using the Prism interface or a script. This limitation highlights the need to verify specific application storage configurations during DR testing. For automated recovery of VGs, using "In-guest" iSCSI attachments is often preferred because the iSCSI initiator within the guest OS can re-establish the connection to the new cluster's Data Services IP once the network is active.

NEW QUESTION # 19

An organization is finalizing its Disaster Recovery (DR) plan. The primary objective is to balance cost- efficiency with a target RTO of under 15 minutes. Data currently resides in Object Storage, but the team is debating between a Zero Compute approach and a Pilot Light approach. Why would a Pilot Light infrastructure be selected over a Zero Compute model despite the higher "Moderate" cost?

- A. Eliminates the need for any Object Storage (S3/Blob) costs.
- B. Lowest cost option available for long-term idle infrastructure.
- C. **Faster recovery due to metadata and cluster already existing.**
- D. Only model that allows for a "Power-On" recovery trigger.

Answer: C

Explanation:

When designing disaster recovery to a cloud environment (such as NC2 on AWS or Azure), organizations must choose a compute model that aligns with their Recovery Time Objective (RTO). The "Zero Compute" model is the most cost-efficient because it stores only the data (snapshots) in low-cost Object Storage (S3 or Blob) and does not maintain a running cluster. However, the RTO for Zero Compute is high because, in a disaster, the organization must first deploy a new Nutanix cluster, configure it, and then begin the process of hydrating data from the Object Storage.

In contrast, the "Pilot Light" model involves keeping a minimal, active Nutanix cluster (e.g., 3 nodes) running at the recovery site. While this carries a moderate ongoing cost, it significantly reduces the RTO.

Because the cluster already exists, the management plane (Prism Central), the storage containers, and all metadata are already active. When a failover is triggered, the system only needs to power on the VMs or perform a small amount of data hydration. This allows the organization to meet aggressive RTO targets of under 15 minutes, which is generally impossible with the Zero Compute model. Pilot Light provides the "ready-to-go" infrastructure needed for mission-critical applications that cannot afford the multiple hours required to provision a fresh cluster from scratch during an emergency.

NEW QUESTION # 20

After a failover and stabilization of workloads at the recovery AZ, an administrator removes several VMs from the protection policy because they are no longer required. Which action should be performed as part of post-failover cleanup to prevent unnecessary storage consumption?

- A. Disable Nearsync replication.
- B. Recreate the recovery plan.
- C. Delete the associated recovery points.
- D. **Reconfigure the replication schedule.**

Answer: D

Explanation:

Post-failover cleanup is a vital operational step to ensure that the environment remains optimized and that resources are not being wasted on workloads that are no longer part of the production environment. When virtual machines are removed from a Protection Policy after a failover, the orchestration engine stops creating new recovery points for them; however, the existing schedule metadata and historical snapshots may still consume space on both the primary and recovery clusters. Reconfiguring the replication schedule (Option B) is the specific task that refreshes the policy's state and forces the system to re-evaluate the storage requirements for the remaining entities. This action ensures that the background cleanup processes (managed by Cerebro and Curator) can properly identify and purge the snapshots associated with the removed VMs once their retention period has passed. Failing to reconfigure the schedule or the associated protection policy can leave "orphaned" snapshots in the storage tier, leading to a steady increase in storage utilization over time. By reconfiguring the schedule, the administrator confirms the new steady-state of the DR environment,

ensuring that storage is only consumed by the active, required workloads.

NEW QUESTION # 21

How does Nutanix Disaster Recovery automatically handle Container Mapping if a storage container with the same name does not exist at the recovery Nutanix cluster?

- A. The data is temporarily kept in the SSD tier of the remote site pending intervention.
- B. The recovery points replicate to a random storage container at the recovery Nutanix cluster.
- C. The system automatically creates a new Storage Container with the same name on the remote site.
- D. The initial replication fails and generates a critical alert requiring manual mapping in Prism Central.

Answer: C

Explanation:

Storage Container mapping is a fundamental requirement for successful replication between Nutanix clusters, as it defines where the replicated recovery point data will reside on the destination cluster. In the early versions of Nutanix Disaster Recovery, administrators had to manually map source containers to destination containers to ensure the replication stream had a valid landing zone. However, to simplify the deployment of BCDR solutions and reduce manual configuration errors, modern Nutanix Disaster Recovery behavior has been enhanced. If the system detects that a VM is protected but no manual container mapping has been established in Prism Central, it will proactively check the recovery site for a container with the same name as the source. If that container does not exist, the orchestrator will automatically create a new storage container with the identical name on the remote cluster to allow replication to proceed without interruption. This automation ensures that "out-of-the-box" protection policies can function immediately even if the recovery site hasn't been fully pre-provisioned with storage structures. This behavior prevents replication from failing due to minor administrative oversights and maintains the integrity of the data protection schedule.

NEW QUESTION # 22

An administrator finds replications for Marketing VMs are failing to replicate. After doing some digging the administrator was able to find the following:

- * Connectivity was confirmed on ports 2020 and 2009 between the clusters
- * All other VMs are replicating successfully
- * Cluster wide storage has plenty of remaining space
- * No firewall exists between the sites
- * Marketing VMs are running Windows, successful VMs are running Linux

What could be causing the Marketing VMs to fail replications?

- A. Linux VMs are set up with a container mapping on the remote site.
- B. Linux VMs are replicating using Async instead of NearSync.
- C. Marketing VMs are replicating to a container with zero free space.
- D. Marketing VMs are replicating using Async instead of NearSync.

Answer: A

Explanation:

In a complex BCDR environment, replication failures that affect only a specific subset of virtual machines- while others on the same cluster succeed-usually point to a configuration mismatch rather than a general network or storage issue. Since the ports (2009 and 2020) are confirmed open and storage is available, the transport layer is functional. The fact that Linux VMs are succeeding while Windows (Marketing) VMs are failing suggests that the two groups may be mapped to different destination storage containers. In Nutanix replication, if a container mapping is explicitly set for one set of entities (the Linux VMs) but not for another (the Marketing VMs), the second group might be defaulting to a destination container that is either missing, misconfigured, or has restricted permissions. This specific scenario implies that the successful Linux VMs are benefiting from a correctly configured container mapping on the remote site, whereas the Marketing VMs are likely attempting to replicate to a location where mapping is invalid or non-existent. Troubleshooting this requires an administrator to verify the Prism Central container mapping settings to ensure that the storage targets for all protected categories are reachable and correctly associated with the destination storage pool.

NEW QUESTION # 23

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