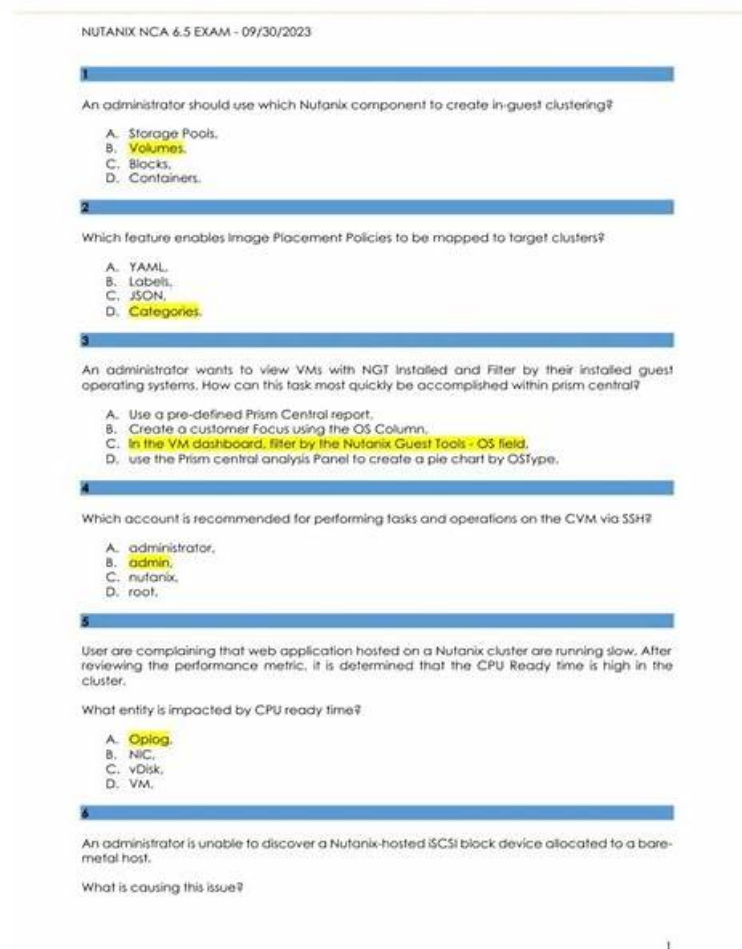


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Nutanix Certified Associate v6.10 Sample Questions (Q66-Q71):

NEW QUESTION # 66

An administrator is building a new Windows VM on a Nutanix AHV cluster. However, when the administrator tries to install the OS, no disks are listed as available.

What does the administrator need to do to resolve the issue?

- A. Mount and install the Nutanix Guest Tools.
- **B. Mount and install the VirtIO drivers.**
- C. Add a second disk to the VM.
- D. Enable Turbo Mode on the VM.

Answer: B

Explanation:

The correct answer is C. Mount and install the VirtIO drivers.

When installing Windows OS on a Nutanix AHV VM, the default virtual disk controller uses the VirtIO interface, which is not natively supported by Windows installation media. As a result, during the OS installation, the virtual disk will not appear unless the VirtIO drivers are manually provided.

Required Steps:

- * Attach the VirtIO ISO to the VM.
- * During the Windows installation, click "Load Driver".
- * Browse to the mounted VirtIO ISO and select the appropriate storage driver.
- * Once loaded, the installer will detect the virtual disk.

Clarifications:

- * A (Add a second disk): Irrelevant; the issue is driver recognition, not disk quantity.
- * B (Enable Turbo Mode): Related to performance, not disk detection.
- * D (Install Nutanix Guest Tools): Done after OS installation, not before or during.

Prism UI Navigation Path:

VM > Edit > CD-ROM > Mount ISO # Select VirtIO ISO

Official Reference:

- * Nutanix AHV Administration Guide - Creating Windows VMs
- * Nutanix KB #5967 - AHV: Windows Installation on VirtIO
- * Excerpt: "If the disk is not detected during Windows installation, the VirtIO ISO must be mounted and the appropriate storage controller driver manually installed."

NEW QUESTION # 67

How can an administrator work with Nutanix Support to recover a deleted VM, in its most up-to-date status, within a 24-hour period of the VM being deleted?

- **A. Use the Recycle Bin.**
- B. Use third party tools.
- C. Use Nutanix Recovery Plan.
- D. Use NC2 on AWS.

Answer: A

Explanation:

The correct answer is B. Use the Recycle Bin.

The Recycle Bin feature in Nutanix enables soft deletion of VMs, where the deleted VM is retained in a non-visible state for 24 hours by default before being purged. During this retention window:

- * Nutanix Support can assist in recovering the VM in its most up-to-date state.
- * No snapshots or backups are required for this recovery mechanism.
- * The Recycle Bin is enabled by default in recent AOS versions.

UI Path (for visibility):

This functionality is internal and requires Support engagement for recovery.

Clarification:

- * A (Nutanix Recovery Plan):Used with NearSync or Async DR; does not recover recently deleted VMs automatically.
- * C (NC2 on AWS):Disaster recovery infrastructure, not applicable to local deleted VM recovery.
- * D (Third-party tools):Irrelevant to Nutanix native functionality.

Official Reference:

- * Nutanix Administration Guide - VM Recovery using Recycle Bin
- * Excerpt: "Deleted VMs can be recovered by Nutanix Support within 24 hours using the Recycle Bin soft-delete capability."

NEW QUESTION # 68

An administrator wants to create a storage container for an application that has built-in redundancy. What should the administrator do?

- A. RF1 is enabled by default in a storage container.
- B. Create an RF1 storage container and enable RF1.
- C. Enable RF1 and create an RF1 storage container.
- **D. Create an RF1 storage container.**

Answer: D

Explanation:

The correct answer is B. Create an RF1 storage container.

In Nutanix architecture, Replication Factor (RF) is set at the storage container level to optimize redundancy and performance for specific workloads. When an application has its own internal redundancy, such as database clustering or distributed file systems, the administrator may choose to reduce Nutanix's redundancy to RF1, which stores only one copy of data in the cluster. This reduces overhead and maximizes usable capacity, but is not fault-tolerant at the Nutanix level.

Key clarifications:

- * RF1 is not enabled by default. Nutanix clusters default to RF2 or RF3 depending on the configuration and number of nodes.
- * RF1 must be explicitly set when creating a storage container.
- * There is no separate "enable RF1" setting outside of selecting RF1 at container creation; once selected, it applies directly.

Prism UI Navigation Path:

Storage > Storage Containers > Create Storage Container > Data Redundancy Level # Select "RF1" Official Reference:

- * Nutanix Bible - Storage Layer and RF Explanation
 - * Nutanix Storage Administration Guide - "Creating Containers with Specific Replication Factor"
 - * Excerpt: "RF1 is typically used for workloads with native redundancy. It must be selected explicitly during container creation."
- Conclusion: Only option B accurately reflects this process.

NEW QUESTION # 69

Which Nutanix Disaster Recovery component or feature provides the best Recovery Time Objective (RTO)?

- A. Availability Zone
- B. Async
- C. NearSync
- **D. Metro Availability**

Answer: D

Explanation:

Nutanix Metro Availability provides the best Recovery Time Objective (RTO) because it enables synchronous replication between two sites. In the event of a failure at one site, VMs can be instantly restarted on the other site with minimal disruption. This setup ensures zero data loss and near-instantaneous recovery.

- * A. Async: Provides high RPO (Recovery Point Objective) but has a longer RTO compared to synchronous replication methods.
- * B. Availability Zone: This term refers to a general site setup, not specific to recovery objectives.
- * C. Metro Availability: Correct, as it uses synchronous replication for near-zero RTO.
- * D. NearSync: Provides better RPO than Async but does not match the RTO of Metro Availability.

References:

Nutanix Data Protection and Disaster Recovery Guide.
Nutanix University Certification Content.

NEW QUESTION # 70

An administrator receives the alert:
What is the most likely cause?

- A. Another node in this cluster is already in maintenance mode.
- B. This node in the cluster may not have enough resources available.
- **C. Other nodes in the cluster may not have enough resource available.**
- D. This node in the cluster is already in maintenance mode.

Answer: C

Explanation:

When a Nutanix cluster alert occurs, indicating maintenance mode issues, the most likely cause is that another node in the cluster is already in maintenance mode. Nutanix clusters enforce restrictions to prevent more than one node from entering maintenance mode simultaneously. This ensures the cluster can maintain resiliency and availability, adhering to the redundancy factor (RF) policy. If another node is already in maintenance mode, the cluster cannot afford to have additional nodes enter maintenance without compromising data and service availability.

:

Nutanix Cluster Best Practices Documentation - Maintenance Mode.
Nutanix Alerts and Events Guide, accessible via Prism UI.

NEW QUESTION # 71

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