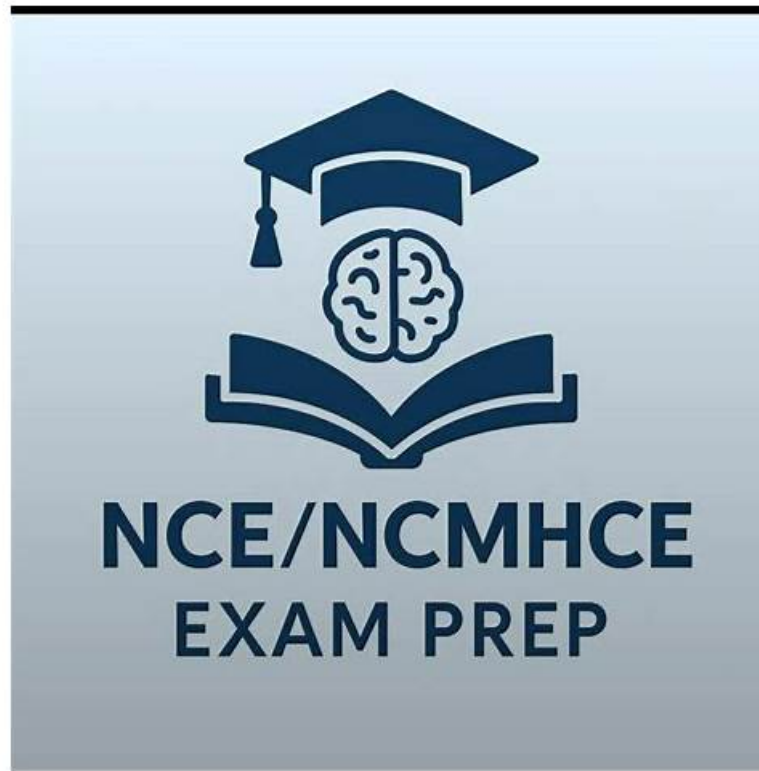


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## Associate NCP-MCI-7.5 Level Exam, Latest NCP-MCI-7.5 Version

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## Nutanix Certified Professional - Multicloud Infrastructure (NCP-MCI) 7.5 Sample Questions (Q91-Q96):

### NEW QUESTION # 91

A corporate security policy mandates strict protection against boot-level rootkits and requires the isolation of NTLM password hashes from the running operating system to prevent "pass-the-hash" attacks.

During the initial testing phase, the administrator deploys a test VM using the standard AHV creation workflow. While configuring the guest operating system, administrator attempts to enable Windows Defender Credential Guard via Group Policy. However, the feature fails to start, and the system logs indicate that the underlying virtualization platform does not meet the necessary hardware security requirements.

Which specific configuration change must the administrator apply to the VM to satisfy the security policy requirements?

- A. Enable Generation 2 firmware, check the VBS flag, and add a vTPM device.
- **B. Enable UEFI firmware, check the Secure Boot option, and add a Virtual Trusted Platform Module (vTPM) device.**
- C. Enable Legacy BIOS firmware, check the Secure Boot option, and add a vTPM device.
- D. Enable UEFI firmware, configure the disk controller to use the IDE bus, and add a vTPM device.

**Answer: B**

Explanation:

Nutanix AHV documentation for Windows Defender Credential Guard support states that the VM must be configured with UEFI and Secure Boot enabled, and Nutanix security guidance for vTPM explains that vTPM is used to protect Windows credentials and is part of the trusted platform features required by modern Windows security functions. Together, these requirements map directly to option D: enable UEFI firmware, enable Secure Boot, and add a vTPM device.

The other options each contain a flaw. IDE is not the correct secure-boot bus choice in these workflows, legacy BIOS does not satisfy the modern secure boot requirement, and "Generation 2 firmware" is Hyper-V- oriented wording rather than the standard AHV requirement stated in Nutanix docs. The policy in the question explicitly mentions rootkit resistance and credential isolation, both of which are tied to Secure Boot and TPM- backed trust. Therefore Nutanix's documented VM configuration that satisfies those requirements is exactly what is described in D.

### NEW QUESTION # 92

An administrator manages a Nutanix cluster with software data-at-rest encryption enabled using an external KMS. Several VMs are configured with vTPM to support Windows BitLocker encryption.

The administrator needs to perform a disaster recovery operation and restore the VMs on a different cluster.

During the recovery, the administrator discovers that the encryption key backup file is unavailable.

What is the expected outcome for the vTPM-enabled VMs?

- A. The VMs will fail to start because BitLocker will not prompt for the recovery key on first boot.
- B. The VMs will fail to start successfully because the external KMS provides the vTPM keys directly to the new cluster.
- **C. The VMs will fail to start because the vTPM keys cannot be recovered without the backup file.**
- D. The VMs will start successfully with a new vTPM device automatically attached during the restore process.

**Answer: C**

Explanation:

Nutanix security documentation is clear that vTPM data includes crucial encryption keys and that those keys must be protected through the Nutanix-supported mechanisms. Nutanix also states that encryption keys must be backed up, and third-party-style backup approaches do not protect vTPM device data correctly. If the required key backup material is missing during recovery, the restored environment cannot reconstruct the vTPM-backed trust context for those VMs. In practical terms, that means the VMs cannot be started successfully in the expected protected state because the vTPM keys cannot be recovered without the backup file. That makes D the best answer. ( Nutanix Portal ) This is why Nutanix treats vTPM-enabled workloads as a special class in protection and recovery planning.

The issue is not that a new blank vTPM can simply be attached during restore, and it is not that the external KMS alone automatically recreates the VM's vTPM identity. The trust chain depends on the protected key material. Without that backup information, Windows BitLocker and other vTPM-dependent security features cannot be restored to their original usable state. So even though the environment uses an external KMS for software encryption, the Nutanix-documented principle still applies: without the necessary key backup, the vTPM-enabled VMs cannot be recovered successfully, which is exactly what option D states. ( Nutanix Portal )

### NEW QUESTION # 93

A company has recently purchased five new Nutanix clusters. The lab manager has been tasked with remotely deploying the Nutanix infrastructure in the most efficient way possible. Which tool would best help to accomplish this task?

- **A. Foundation Central**
- B. Foundation for Windows/Mac
- C. Phoenix ISO image
- D. Standalone Foundation VM

**Answer: A**

Explanation:

When the requirement is to deploy multiple remote clusters efficiently from a central point, Nutanix's intended tool is Foundation Central. Nutanix documentation describes Foundation Central as a way to manage several Foundation instances from a single pane of glass, allowing administrators to create clusters of remote nodes. That design matches the scenario perfectly: five newly purchased clusters, remote deployment, and a need for efficiency and centralized control. (Nutanix Portal) The other tools are more limited in scope. Foundation for Windows/Mac and a standalone Foundation VM are useful for imaging and cluster creation, but they do not provide the same centralized, multi-cluster orchestration model that Foundation Central provides. Phoenix ISO is a recovery or re-imaging tool and is not the normal answer for greenfield mass deployment. In short, this question is less about "which tool can build a cluster" and more about "which tool is purpose-built for remote, scaled deployment across many clusters." Nutanix positions Foundation Central exactly for that use case, so B is the best answer. (Nutanix Portal)

#### NEW QUESTION # 94

An administrator needs to protect a group of mission-critical virtual machines.

The business requirements are:

- \* Recovery Point Objective (RPO) must be set to 5 minutes.
- \* New mission critical VMs should be automatically protected.

Which data protection type supports this configuration?

- A. Protection Domain with NearSync replication
- B. Protection Policy with Asynchronous replication
- **C. Protection Policy with NearSync replication**
- D. Protection Domain with Asynchronous replication

**Answer: C**

Explanation:

A required RPO of 5 minutes immediately points to NearSync replication, because Nutanix documents NearSync protection policies as supporting recovery points in 1-15 minute intervals. The second requirement-automatically protect new mission-critical VMs-points to a Protection Policy approach in Prism Central, because protection policies can use categories and policy-based assignment to scale protection dynamically as new matching VMs are added. Combining those two requirements makes Protection Policy with NearSync replication the correct answer. (Nutanix) Protection Domains can support NearSync in older or alternate workflows, but the phrase "new mission critical VMs should be automatically protected" is the clue that pushes this question toward policy-based protection rather than manually maintained membership. Asynchronous replication also fails the first requirement because its RPO target is not the 5-minute class represented by NearSync. Nutanix's modern DR design encourages policy-driven protection for scalable, category-based administration. Therefore B is the best fit for both the RPO and automatic-inclusion requirements. (Nutanix)

#### NEW QUESTION # 95

Due to user complaints of slow VM performance, an administrator is reviewing performance metrics on their Nutanix cluster and executes `iostat` on a Controller VM (CVM).

The following output is captured:

```
#TIMESTAMP 1768953673 : 01/21/2026 12:01:13 AM
avg-cpu: %user %nice %system %iowait %steal %idle
2.32 0.09 7.53 83.20 0.00 6.86
```

Based on this output, which statement most accurately describes the current state of the CVM?

- A. The CVM is suffering from excessive network throughput congestion, resulting in a high percentage of CPU cycles being dedicated to interrupt processing.
- **B. The CVM is likely waiting on disk I/O operations to complete, suggesting a potential bottleneck in the storage subsystem or underlying physical drives.**
- C. The CVM is experiencing significant CPU contention from the hypervisor, as indicated by the discrepancy between low user percentage and high system overhead.
- D. The CVM is under heavy computational load from Nutanix services, as evidenced by the high percentage of active processing cycles currently in use.

**Answer: B**

Explanation:

The decisive metric in the `iostat` output is `%iowait = 83.20`. In Linux performance interpretation, such a high `iowait` value means the

CPU is spending most of its time waiting for disk I/O operations to complete rather than actively executing user or system work. On a Nutanix CVM, that strongly suggests the storage path is the bottleneck at that moment, whether due to backend disk saturation, contention, or broader storage subsystem latency. Since user CPU and steal are both low, the issue is not primarily compute pressure or hypervisor scheduling contention. Therefore, A is the most accurate description. ( Nutanix ) This is a classic Nutanix troubleshooting interpretation question. If the output had shown high %steal, then hypervisor contention would be a stronger candidate. If %system and %user were both very high, compute load from services would be more likely. But with the overwhelming majority of time in iowait, the signal points toward delayed storage completion. In operational terms, the next steps would usually involve checking CVM disk metrics, Stargate performance, storage latency, and possibly the health of the underlying drives. The evidence in the output supports a storage wait condition, which is exactly what option A says. ( Nutanix )

## NEW QUESTION # 96

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