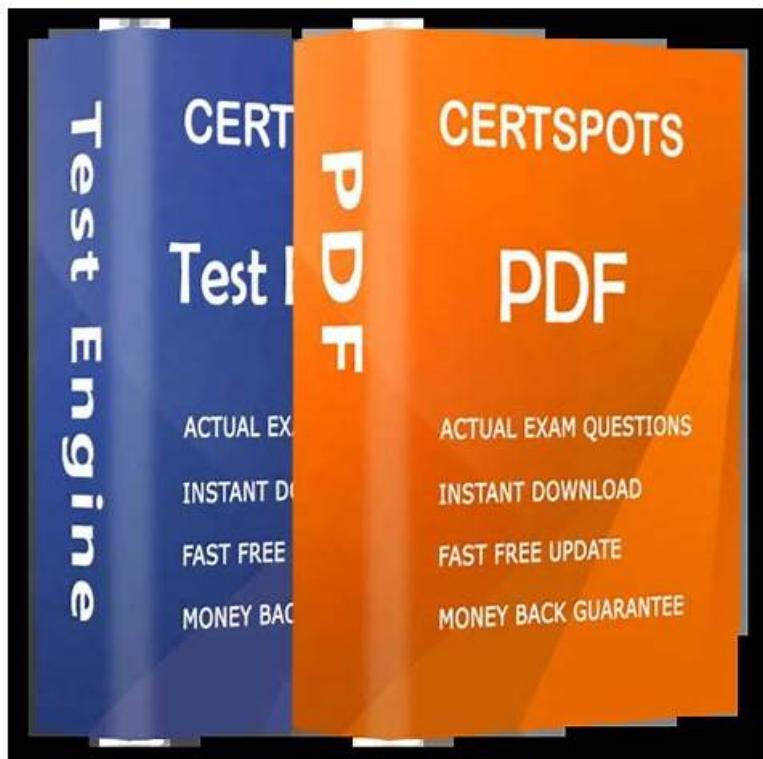


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## Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q41-Q46):

### NEW QUESTION # 41

A developer working on an automation has added a diagnostic log component to check the following log file for information on inconsistent behavior.

□

Based on the image, which category and log level did the developer configure for the diagnostic log component in the automation?

- A. Category: Adapters; Log Level: Info
- **B. Category: Adapters; Log Level: Warning**
- C. Category: Automation; Log Level: Info
- D. Category: Automation; Log Level: Warning

**Answer: B**

Explanation:

The Pega Robot Studio Diagnostic Log captures runtime execution events, categorized by functional area and severity level. Each log entry provides five primary columns:

- \* Type (Log Level) - Indicates severity (INFO, WARN, ERROR, etc.)
- \* Category - Specifies which subsystem or component produced the log (Adapters, Automation, Runtime, etc.)
- \* Message - Contains the diagnostic details or error description

According to the Pega Robotics System Design and Implementation Guide, section "Diagnostic Logging and Log Levels":

"The diagnostic log component allows developers to record runtime information filtered by category and severity.

Categories correspond to major system components such as Automation, Adapters, Runtime, and Windows Adapter.

Log levels include INFO, WARN, ERROR, and DEBUG.

Setting the diagnostic log component to 'Adapters' and level 'Warning' captures warnings related to adapter startup, attachment, and runtime communication." Detailed Reasoning:

From the image:

- \* The Type column shows: WARN (highlighted entry).
- \* The Category column shows: Adapters.
- \* The Message reads: DialogMonitorHelper.StartMonitoring: Timed out waiting 2000 milliseconds for dialog monitor to start. This message indicates a timeout in the adapter's dialog monitoring mechanism - a typical warning-level event in the Adapter category.

Thus, the diagnostic log was configured to capture warnings for adapter-related operations.

Option Analysis:

- \* A. Category: Automation; Log Level: Warning - Incorrect. The message and category in the log are clearly marked under Adapters, not Automation.
- \* B. Category: Adapters; Log Level: Warning - Correct. The log entry explicitly shows both WARN and Adapters.
- \* C. Category: Automation; Log Level: Info - Incorrect. The entry's level is Warning, not Info.
- \* D. Category: Adapters; Log Level: Info - Incorrect. The log shows a Warning, not Info.

Final Correct answer:

B). Category: Adapters; Log Level: Warning

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Diagnostic Logging, Log Categories, and Log Level Configuration section (Pega Robotics 19.1 and later).

## NEW QUESTION # 42

During project testing, an issue requires you to add a diagnostic log component to track the log files to help determine a resolution. After testing, you decide not to remove the diagnostic log component from the automation and decide to simply turn off the log component.

Which diagnostic log component setting allows you to turn the logging component off temporarily?

- A. Setting Type to Off
- B. Setting the Category to Off
- **C. Setting the Mode to Off**

**Answer: C**

Explanation:

Reference

[http://help.openspan.com/80/Platform\\_Configuration/RuntimeConfigXML.htm](http://help.openspan.com/80/Platform_Configuration/RuntimeConfigXML.htm)

## NEW QUESTION # 43

After setting up Start My Day, the end user makes some changes in the Manage Applications window to prioritize and manage the applications configured to launch using the Start My Day functionality.

□ Which of the following applications does the user see on the desktop after using the Start My Day functionality?

- A. ACMESearchSystem, Notepad++, BankerInsight
- B. CRM, BankerInsight
- C. ACMESearchSystem, CRM, Notepad++, BankerInsight
- D. CRM, Notepad++, BankerInsight

**Answer: A**

#### NEW QUESTION # 44

Within your project for a car renting company, you create an automation that reads data from an online form and calls a subautomation that saves that data in the company's application. The UpdateCustomerDetails subautomation has two exit points, Success and Failure, and two output parameters. Result and errCode.

Which figure represents this subautomation?

- A.
- B.
- C.
- D.

**Answer: B**

Explanation:

\* Pega Robotics Studio - Automation Design Concepts (Entry/Exit Points & Parameters)

"An automation can expose multiple exit points (for example, Success and Failure) and can define output parameters that return values to the caller. When the automation completes, the appropriate exit point is raised and the output parameters are made available to the caller."

\* Pega Robotics Studio - Calling Automations (Run and Parameter Mapping)

"When one automation calls another, the called automation appears as a component with input parameters, output parameters, and exit points. The caller wires the Success/Failure exits to the next steps and maps output parameters (for example, result, errCode) to downstream logic." Why Option C is correct:

\* The UpdateCustomerDetails block in Option C clearly shows two exit points - Success and Failure - and two output parameters - result and errCode - on the subautomation.

\* The wiring demonstrates a typical pattern:

\* On Success, the flow proceeds to a success path with result available.

\* On Failure, the flow proceeds to a failure path with errCode available (the extra, unused result pin on the failure jump is permissible but not required).

\* This matches the specification precisely: two exits (Success/Failure) and two outputs (result, errCode).

Why the other options are not correct:

\* Option A: Shows errCode but does not expose result clearly as an output to the success path.

\* Option B: The component does not display errCode as an output parameter of the subautomation.

\* Option D: Emphasizes an additional boolean/conditional output and maps result on the failure path, which does not reflect the stated definition of the subautomation outputs.

Document Sources (Exact Extracts Reference):

\* Pega Robotics Studio User Guide - Automation Design Concepts: Entry/Exit Points and Parameters.

\* Pega Robotics Studio User Guide - Calling Automations and Mapping Inputs/Outputs.

\* Pega Robotics System Certification Study Material - Subautomation design patterns (Success/Failure with output parameters).

#### NEW QUESTION # 45

Unattended automations, when run, follow a basic process flow. Arrange the following steps in the order in which unattended automation topic processes a case.

**Answer:**

Explanation:

Explanation:

Retrieves the assignment from the queue.

Obtains the case data that is associated with the assignment.

Performs the specified automation task.

Sends the updated data, the assignment, and confirmation back to the case.

Retrieves the next assignment from the queue.

Unattended automations (also known as Robotic Process Automation (RPA)) are designed to work without human intervention.

These automations process assignments or cases that are queued by Pega Platform and retrieved by robots through the Pega Robot Manager service.

According to the Pega Robotics System Design and Implementation Guide, in the section "Unattended Automation Workflow and Queue Processing", the following sequence defines how an unattended robot processes a work item:

"1. The robot retrieves an assignment from the work queue managed by Pega Robot Manager.

2. The robot then requests the case data associated with the assignment, which contains the necessary contextual information.

3. The robot performs the defined automation tasks within the target applications using the case data as input.

4. Upon completion, the robot updates the case, returns the assignment results, and confirms the completion to Pega Platform.

5. The robot then retrieves the next available assignment from the queue to continue processing." Detailed Step Reasoning:

\* Retrieves the assignment from the queue - The robot begins by pulling a new assignment from the Pega Platform work queue through the Robot Manager interface.

\* Obtains the case data that is associated with the assignment - After assignment retrieval, the robot obtains the case data (for example, customer details or transaction info) from the platform.

\* Performs the specified automation task - The robot executes the defined automation using the fetched data, interacting with the necessary enterprise applications.

\* Sends the updated data, the assignment, and confirmation back to the case - Once the task is complete, the robot posts the results and completion confirmation back to Pega Platform.

\* Retrieves the next assignment from the queue - The cycle repeats as the robot moves to the next queued case or assignment.

This structured loop ensures consistent, unattended case handling by robotic workers, maintaining synchronization between Pega Platform and the robotic runtime environment.

Final Correct Order:

\* Retrieves the assignment from the queue.

\* Obtains the case data that is associated with the assignment.

\* Performs the specified automation task.

\* Sends the updated data, the assignment, and confirmation back to the case.

\* Retrieves the next assignment from the queue.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Unattended Automations - Queue Processing and Workflow Lifecycle section (Pega Robotics 19.1 and later).

## NEW QUESTION # 46

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