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1. Refer to the exhibit.



2. Which expected operations during node addition when the new node has a different AOS version?

- The entire cluster is upgraded to the latest one-click release.
- The node is added and a separate upgrade operation must be performed.**
- The addition fails and forces the administrator to image using standalone Foundation.

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Nutanix Certified Professional - Business Continuity (NCP-BC) 7.5 Sample Questions (Q32-Q37):

NEW QUESTION # 32

During a Test Failover, how can an administrator ensure that test VMs do not disrupt production?

- A. By using an isolated network
- B. By changing MAC addresses
- C. By powering off production VMs
- D. By reconfiguring VMs IP addresses

Answer: A

Explanation:

The primary purpose of a Test Failover is to validate the recovery process in a non-disruptive manner. When a VM is recovered from a snapshot during a test, it retains its original configuration, including its IP address and hostname. If this test VM were to be powered on on the same network as the live production VM, it would immediately cause a duplicate IP address conflict and potentially disrupt production services or trigger security alerts.

To prevent this disruption, Nutanix Recovery Plans allow administrators to map the production network to a "Test Network" at the recovery site. This test network is typically an "Isolated" VLAN or overlay network that has no physical or logical route back to the production environment. By using an isolated network (Option A), the test VMs can boot up, run their internal services, and even communicate with other test VMs (if placed on the same isolated segment) without any risk of interfering with real users or databases. This allows the infrastructure team to verify that the "Recovered" state is functional while the "Primary" state continues to serve the business, fulfilling the core requirement of non-disruptive testing.

NEW QUESTION # 33

An administrator wants to protect the snapshots created on the cluster. Only authorized users should be allowed to modify or delete the snapshots on the cluster. How can the administrator harden the security of the snapshots?

- A. Configure CVM and AHV hardening.
- B. Configure a backup user with admin privileges.
- C. Configure Approval policy for snapshots.
- D. Configure cluster lockdown and use SSH keys.

Answer: C

Explanation:

Hardening a Nutanix cluster for Business Continuity involves implementing security controls that protect recovery data from unauthorized destruction. In many modern cyberattacks, specifically ransomware, the goal is not just to encrypt production data but also to delete the snapshots and backups that would allow for recovery. To satisfy the requirement that only authorized modifications occur, the administrator must move beyond simple Role-Based Access Control (RBAC) and implement an "Approval Policy". The Approval Policy feature in Prism Central forces a secondary layer of validation for sensitive operations like snapshot deletion. When a user tries to delete a recovery point, the Nutanix orchestration engine captures the request and holds it in a "Pending" state. The request must be reviewed and approved by a designated person with approval authority. This ensures that even if an administrator's account is compromised, the attacker cannot immediately wipe out the snapshots needed to restore the environment. This "multi-person control" is a recognized security best practice for protecting mission-critical data. While cluster lockdown (Option C) prevents unauthorized SSH access, it does not manage the logical management of data through the Prism UI. An Approval Policy provides the specific "modification and deletion" control requested, ensuring that the cluster's recovery points remain a reliable "source of truth" following a security incident or administrative error.

NEW QUESTION # 34

An administrator finds replications for Marketing VMs are failing to replicate. After doing some digging the administrator was able to find the following:

- * Connectivity was confirmed on ports 2020 and 2009 between the clusters
- * All other VMs are replicating successfully
- * Cluster wide storage has plenty of remaining space
- * No firewall exists between the sites
- * Marketing VMs are running Windows, successful VMs are running Linux

What could be causing the Marketing VMs to fail replications?

- A. Marketing VMs are replicating to a container with zero free space.
- B. Marketing VMs are replicating using Async instead of NearSync.
- C. Linux VMs are replicating using Async instead of NearSync.
- **D. Linux VMs are set up with a container mapping on the remote site.**

Answer: D

Explanation:

In a complex BCDR environment, replication failures that affect only a specific subset of virtual machines- while others on the same cluster succeed-usually point to a configuration mismatch rather than a general network or storage issue. Since the ports (2009 and 2020) are confirmed open and storage is available, the transport layer is functional. The fact that Linux VMs are succeeding while Windows (Marketing) VMs are failing suggests that the two groups may be mapped to different destination storage containers. In Nutanix replication, if a container mapping is explicitly set for one set of entities (the Linux VMs) but not for another (the Marketing VMs), the second group might be defaulting to a destination container that is either missing, misconfigured, or has restricted permissions. This specific scenario implies that the successful Linux VMs are benefiting from a correctly configured container mapping on the remote site, whereas the Marketing VMs are likely attempting to replicate to a location where mapping is invalid or non-existent. Troubleshooting this requires an administrator to verify the Prism Central container mapping settings to ensure that the storage targets for all protected categories are reachable and correctly associated with the destination storage pool.

NEW QUESTION # 35

A financial institution is designing a disaster recovery solution for a business-critical application that requires a zero recovery point objective (RPO). The infrastructure team decides to implement Nutanix Metro Availability between two physical data centers (DC-Alpha and DC-Beta) interconnected by a dedicated dark fiber. What is the maximum possible network latency on this link for this configuration to function correctly?

- **A. 5 ms**
- B. 10 ms
- C. 20 ms
- D. 100 ms

Answer: A

Explanation:

Nutanix Metro Availability is a continuous availability solution designed to survive a site failure with zero data loss (Zero RPO). Because it operates on a synchronous replication model, every write performed by a virtual machine must be acknowledged by both the local and the remote clusters before the write is confirmed to the application. This process introduces a "latency penalty" equal to the network Round Trip Time (RTT) between the sites.

To maintain acceptable application performance and ensure cluster stability, Nutanix enforces a strict latency limit of 5 ms RTT between the primary and secondary clusters. If the latency exceeds this 5 ms threshold, the time spent waiting for remote acknowledgments would cause severe performance degradation for high-I/O workloads, such as the SQL or Oracle databases common in financial institutions. Furthermore, high latency increases the risk of the synchronous link being "broken" during periods of high data churn. While the Witness VM (used for tie-breaking) can tolerate much higher latency (up to 200 ms), the data-path link must remain under 5 ms to satisfy the technical requirements of the Metro Availability feature and the performance expectations of Tier-1 business-critical applications.

NEW QUESTION # 36

How does Nutanix Disaster Recovery automatically handle Container Mapping if a storage container with the same name does not exist at the recovery Nutanix cluster?

- A. The initial replication fails and generates a critical alert requiring manual mapping in Prism Central.
- B. The data is temporarily kept in the SSD tier of the remote site pending intervention.
- C. The recovery points replicate to a random storage container at the recovery Nutanix cluster.
- **D. The system automatically creates a new Storage Container with the same name on the remote site.**

Answer: D

Explanation:

Storage Container mapping is a fundamental requirement for successful replication between Nutanix clusters, as it defines where the replicated recovery point data will reside on the destination cluster. In the early versions of Nutanix Disaster Recovery, administrators had to manually map source containers to destination containers to ensure the replication stream had a valid landing zone. However, to simplify the deployment of BCDR solutions and reduce manual configuration errors, modern Nutanix Disaster Recovery behavior has been enhanced. If the system detects that a VM is protected but no manual container mapping has been established in Prism Central, it will proactively check the recovery site for a container with the same name as the source. If that container does not exist, the orchestrator will automatically create a new storage container with the identical name on the remote cluster to allow replication to proceed without interruption. This automation ensures that "out-of-the-box" protection policies can function immediately even if the recovery site hasn't been fully pre-provisioned with storage structures. This behavior prevents replication from failing due to minor administrative oversights and maintains the integrity of the data protection schedule.

NEW QUESTION # 37

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