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Huawei H12-521_V1.0-ENU (HCIP-Intelligent Vision V1.0) Exam is a certification exam offered by Huawei Technologies Co. Ltd. H12-521_V1.0 exam is designed to test the candidate's knowledge and skills in the field of intelligent vision, including intelligent video analysis, intelligent video surveillance, and intelligent video management. H12-521_V1.0 exam is intended to validate the candidate's ability to design, deploy, and maintain intelligent vision solutions.

The HCIP-Intelligent Vision V1.0 Certification Exam covers a wide range of topics related to intelligent vision technologies, including image and video processing, pattern recognition, machine learning, and deep learning. H12-521_V1.0 Exam is designed to test the knowledge and skills of IT professionals in these areas, as well as their ability to design, deploy, and manage intelligent vision systems.

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Huawei H12-521_V1.0 Exam is intended for IT professionals who are interested in working with intelligent vision technologies. These professionals may include system administrators, network engineers, software developers, and others who are responsible for designing, deploying, and managing intelligent vision systems. H12-521_V1.0 Exam covers a wide range of topics related to intelligent vision technologies, including the design and deployment of intelligent vision systems, the use of various technologies to implement intelligent vision systems, and the management of intelligent vision systems.

Huawei HCIP-Intelligent Vision V1.0 Sample Questions (Q49-Q54):

NEW QUESTION # 49

The core of the license plate recognition technology is the segmentation of license plate characters. Which of the following technologies cannot be used to segment the license plate characters?

- A. Grayscale processing
- B. Vertical projection
- C. Key point detection
- D. Binary processing

Answer: C

NEW QUESTION # 50

During license plate recognition, the binary license plate image is horizontally projected along the Y axis to obtain the longest successive projection segment as the character area, and the successive horizontal black lines around the licence plate are filtered out. This method is called ().

- A. Horizontal projection
- B. Vertical projection
- C. Binary processing
- D. Direction division

Answer: A

Explanation:

The correct answer is C because the described method exactly matches the definition of horizontal projection used in license plate character area extraction. In license plate recognition, projection methods are commonly used to separate valid character regions from noise and borders. The material states that "Horizontal projection: The binary license plate image is horizontally projected along the Y axis to obtain the longest successive projection segment as the character area. Filter out horizontally successive black lines around the license plate." This wording is essentially identical to the question, so the method can be identified directly.

From an image-processing perspective, horizontal projection analyzes the pixel distribution across rows to locate the effective vertical range of the character band. This helps remove irrelevant black border lines above and below the plate characters. By contrast, vertical projection is mainly used later to segment individual characters because spaces naturally exist between them. Binary processing is a preprocessing step, not the named segmentation method here, and direction division is not the correct technical term in this context.

Therefore, the only correct choice is C. Horizontal projection .

NEW QUESTION # 51

Which of the following statements about shadow cameras camera cloning in the IVS are correct?

- A. Before using the backup function, you need to clone cameras whose data needs to be backed up to the backup destination server.
- B. You can view live video from shadow cameras on the platform in the backup domain.
- C. You can back up and view data of source cameras through shadow cameras.
- D. Shadow cameras are displayed on the device list of the device management, backup management, and recording playback tab pages of the iClient of the master server in the backup domain.

Answer: A,C,D

Explanation:

The correct answers are B, C, and D. The backup-related domain logic in the material shows that video backup is a structured platform function used to store and manage recordings from another domain or source set. The document states that users can "use the live video and recording backup function to back up recordings of a lower-level domain to MPUs of the local domain, domains of the same level, and upper-level domain" and also refers repeatedly to Video Backup Configuration as the operational process for this function. In practical IVS design, shadow cameras exist precisely to represent cloned source cameras on the backup destination side so backup and playback operations can be performed there.

That is why shadow cameras must be created before the backup function is used, making D correct. Because those cloned objects are used for backup and playback management, B and C are also correct. However, shadow cameras are not primarily created for normal real-time live-view service in the backup domain, so A is not accepted as a correct statement. Their main purpose is backup representation, management visibility, and playback-oriented access rather than ordinary live browsing.

NEW QUESTION # 52

The chips of the intelligent vision platform widely use the ARM architecture. ARM is characterized by a multi-core architecture and a simplified instruction set, but it is not as good as the X86 architecture in terms of achieving computational efficiency optimization.

- A. True
- B. False

Answer: A

NEW QUESTION # 53

Which of the following are the reasons for the color cast (such as yellowish) in the live image? (Multiple choice)

- A. Exposure is small and reasonable
- B. The camera does not switch back to color mode from day to night conversion mode
- C. The default parameters (brightness, contrast, aperture) are insufficient to adapt to the current scene
- D. Inaccurate white balance correction

Answer: B,C,D

NEW QUESTION # 54

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