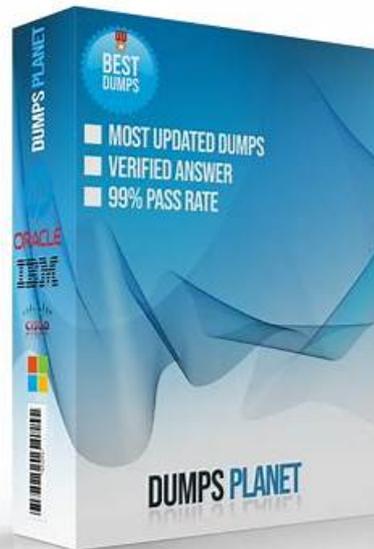


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Pure Storage Portworx-Enterprise-Professional Exam Syllabus Topics:

Topic	Details
Topic 1	<ul style="list-style-type: none"> • Business Continuity: This domain measures the skills of Disaster Recovery Planners and IT Continuity Managers in implementing backup, recovery, and failover strategies. It ensures candidates understand how to sustain business operations and data availability using Portworx features.
Topic 2	<ul style="list-style-type: none"> • Deploy and Install: This domain targets DevOps Engineers and Infrastructure Specialists and focuses on deploying and installing Portworx storage solutions. It includes configuring and setting up storage clusters to support containerized applications reliably and securely.
Topic 3	<ul style="list-style-type: none"> • Operations and Administration: This section of the exam measures the skills of Storage Administrators and Kubernetes Operators and covers managing cluster operations and administering container storage environments using Portworx. Candidates demonstrate the ability to efficiently manage and operate storage clusters in production environments.
Topic 4	<ul style="list-style-type: none"> • Observability and Troubleshooting: This section assesses the expertise of Support Engineers and System Administrators in monitoring storage deployments and troubleshooting issues. Candidates learn to use observability tools and techniques to maintain system health and resolve performance problems effectively.

Topic 5	<ul style="list-style-type: none">• Security: This section focuses on Security Engineers and Compliance Officers responsible for enforcing security measures in container storage environments. Topics include managing encryption, access control, and compliance policies to protect stored data.
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Pure Storage Pure Certified Portworx Enterprise Professional (PEP) Exam Sample Questions (Q11-Q16):

NEW QUESTION # 11

What command can be used to list all Autopilot rule objects in all namespaces in a Portworx cluster?

- A. `kubectl describe autopilotrules`
- B. `pxctl list autopilotrules`
- C. `kubectl get autopilotruleobjects --all-namespaces`

Answer: B

Explanation:

Comprehensive and Detailed Explanation From Exact Extract:

The command `pxctl list autopilotrules` is used to list all Autopilot rule objects across namespaces within a Portworx cluster. Autopilot rules define automated policies for storage operations like scaling and volume migration. This CLI command queries the Portworx control plane to retrieve and display all configured Autopilot rules, regardless of the Kubernetes namespace they reside in. Using `kubectl` commands alone is insufficient because Autopilot rules are managed internally by Portworx and may not correspond directly to Kubernetes resources. Official Portworx CLI documentation confirms `pxctl list autopilotrules` as the primary command for comprehensive Autopilot rule enumeration, enabling administrators to audit and manage storage automation policies efficiently **【Pure Storage Portworx Autopilot Guide source】** .

NEW QUESTION # 12

What Portworx tool should be used to check the health of the storage cluster?

- A. `pxctl`
- B. `helm`
- C. `kubectl`

Answer: A

Explanation:

Comprehensive and Detailed Explanation From Exact Extract:

The `pxctl` command-line interface is the primary tool for managing and monitoring Portworx clusters. It provides detailed health information, including node status, volume health, storage pools, and alerts. Running commands like `pxctl status` or `pxctl cluster status` offers real-time visibility into the cluster's operational state. While `kubectl` manages Kubernetes resources and `helm` handles package deployment, neither provides the specialized insight into Portworx storage internals that `pxctl` delivers. Portworx operational best practices emphasize using `pxctl` for health checks, troubleshooting, and maintenance tasks to ensure cluster reliability and performance **【Pure Storage Portworx CLI Guide source】** .

NEW QUESTION # 13

What are the three severity levels for Portworx alerts?

- A. INFO, WARNING, CRITICAL
- B. INFO, WARNING, ERROR
- C. INFO, WARNING, ALARM

Answer: A

Explanation:

Comprehensive and Detailed Explanation From Exact Extract:

Portworx classifies alerts into three main severity levels to help administrators prioritize response actions. These levels are INFO, WARNING, and CRITICAL. INFO alerts provide informational messages about non-critical events, such as configuration changes or normal operational milestones. WARNING alerts indicate potential issues that could impact performance or availability if left unaddressed, such as increased latency or approaching capacity limits. CRITICAL alerts signal severe problems requiring immediate attention, such as node failures or data corruption risks. This severity categorization supports effective alert management and escalation policies, allowing operational teams to focus on high-impact issues first. The Portworx observability and alerting guide explains these levels in detail and recommends integrating alerts with external monitoring systems for centralized management **【Pure Storage Portworx Alerting Guide source】** .

NEW QUESTION # 14

A cluster administrator wants to define an Autopilot rule for Portworx.

What are the 4 main parts of an Autopilot rule?

- A. Replica, I/O profile, Secure, Placement Strategy
- B. Enforcement, Match Expressions, Topology Key and Weight
- C. Selector, Namespace Selector, Conditions and Actions

Answer: C

Explanation:

Comprehensive and Detailed Explanation From Exact Extract:

An Autopilot rule in Portworx consists of four main parts: Selector, Namespace Selector, Conditions, and Actions. The Selector defines the set of volumes or pods the rule applies to, often using labels. Namespace Selector further narrows the scope to specific Kubernetes namespaces, allowing targeted policy application. Conditions specify triggers or thresholds such as capacity utilization, I/O metrics, or time-based schedules. When conditions are met, the Actions section defines automated responses such as volume expansion, migration, or alerting. This modular rule design enables flexible, policy-driven automation for storage management, helping maintain cluster health and performance without manual intervention. The Portworx Autopilot documentation provides detailed schema and examples, emphasizing these components as foundational for dynamic, autonomous cluster operation **【Pure Storage Portworx Autopilot Guide source】** .

NEW QUESTION # 15

An infrastructure admin wants to restrict installing Portworx on two nodes.

What label does the node need to have?

- A. px/service=stop
- B. px/storage-node=false
- C. px/enabled=false

Answer: C

Explanation:

Comprehensive and Detailed Explanation From Exact Extract:

Portworx uses node labeling as a mechanism to control on which Kubernetes nodes Portworx is installed and allowed to operate. To restrict Portworx installation on specific nodes, those nodes should be labeled with px/enabled=false. This label tells the Portworx Operator or installation scripts to exclude these nodes from Portworx deployment, preventing Portworx daemons from running there. This feature is useful for reserving nodes for non-storage workloads or avoiding unsupported hardware. Labels like px/service=stop or px/storage-node=false are not recognized by Portworx as controls for installation exclusion. The official Portworx deployment and node labeling documentation specify px/enabled=false as the standard method for controlling node

participation in the storage cluster, offering administrators fine-grained control over cluster topology and resource allocation **【 Pure Storage Portworx Deployment Guide source】** .

NEW QUESTION # 16

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