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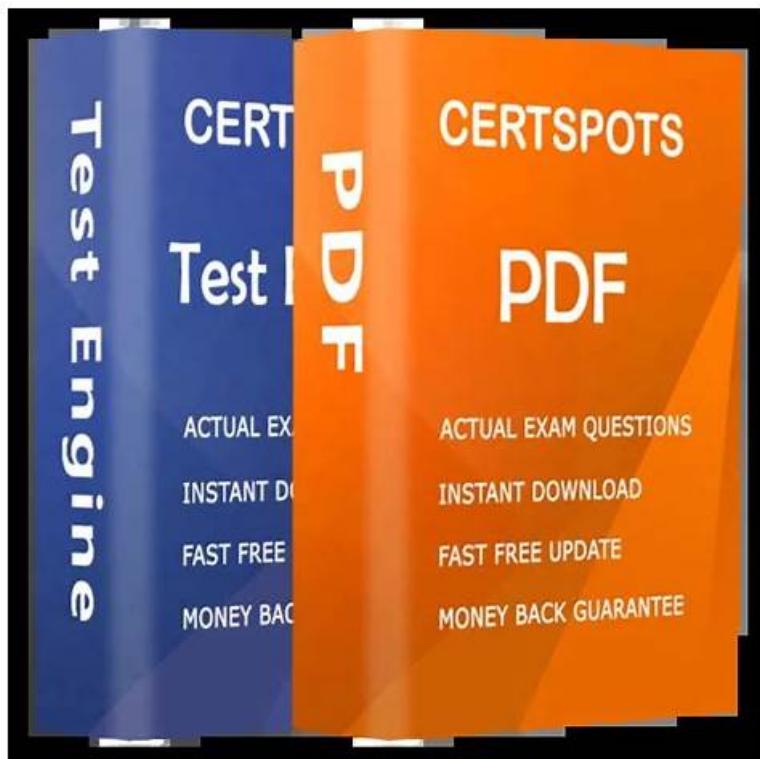
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The PEGACPRSA22V1 exam is a computer-based test that is available worldwide. PEGACPRSA22V1 exam consists of 60 multiple-choice questions that must be completed in 90 minutes. PEGACPRSA22V1 exam is designed to test the candidate's knowledge of Pega Robotics System Architect and their ability to apply that knowledge to real-world scenarios. PEGACPRSA22V1 Exam is available in multiple languages, including English, Japanese, and Spanish.

Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q72-Q77):

NEW QUESTION # 72
You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.
Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.
- B. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- C. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- D. The StartOnProject property of the application is set to false.

Answer: A

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.
According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:
"The StartMethod property defines how Pega Robot Studio connects to or starts an application.
When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.
If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:
* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.
Option Analysis:
* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation.
Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration
- StartMethod and Path Property Requirements section (Pega Robotics
19.1 and later).

NEW QUESTION # 73
our project for a customer service department contains a Windows form with a btnUpdateAccount button.
Users click btnUpdateAccount to automate the updates of other customer account systems at the end of the call. You create the UpdateAccount automation to ensure that the Windows form is still accessible after clicking the button.
Which option represents the UpdateAccount automation with this requirement?

- A.

- B.
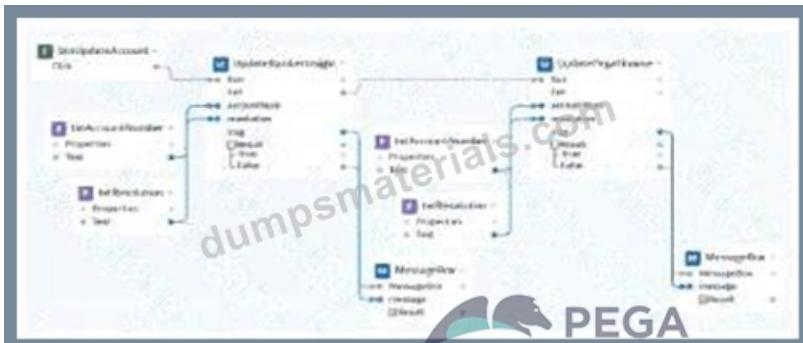
- C.

- D.

Answer: C

Explanation:
* Pega Robotics Studio - Automation Design Concepts (Events and UI Responsiveness)
"Automations started from a Windows Form Click event run on the UI thread. To keep the form responsive, long-running work should be started by calling other automations asynchronously. When an automation is executed synchronously, the UI thread is blocked until the call completes. Executing the child automation asynchronously allows users to continue interacting with the form."
* Pega Robotics Studio - Calling Automations (Run method)
"The Run method includes a synchronous parameter.
True - the caller waits for completion (blocks the UI).
False - the automation starts asynchronously and control returns immediately to the caller (UI remains available).
Default follows the project setting."
* Pega Robotics Studio - Windows Form Controls (Avoid self-triggering)
"Invoking PerformClick from within an automation that is already handling the button's click should be avoided. It re-triggers the button click and can lead to reentrancy or recursion and does not improve UI responsiveness."
* Pega Robotics Studio - Message Dialogs
"Displaying a MessageDialog during processing is modal and prevents interaction with the form until the dialog is closed. Use only for completion or error notifications, not while long-running work is executing." Why Option B is correct:
* Option B starts from the btnUpdateAccount.Click event (so no self-trigger via PerformClick).
* It launches the downstream automations (UpdateBankerInsight and UpdatePegasFinance) using Run with the synchronous parameter set to False (asynchronous), which keeps the Windows form responsive and accessible to the user while updates run.
* It does not introduce a modal MessageBox before or during the updates (dialogs are only used for completion/notification), so it

avoids blocking the UI.
Why the other options are not correct:
* Option A: Uses PerformClick on the button, which re-triggers the click and can lead to recursion without improving responsiveness.
* Option C: Inserts a MessageDialog during the middle of processing, which is modal and blocks the form.
* Option D: Calls the update automations synchronously (or leaves them at the blocking default), which holds the UI thread until completion and makes the form inaccessible during the run.

NEW QUESTION # 74

You are designing an attended project for a banking customer. This project requires you to import new customers from a text file to a lookup table.
Which steps do you take to gain access to the ImportDelimitedFile method of the lookup table within an automation?

* A. Open the Globals tab, filter for the ImportDelimitedFile method, and then drag it to the design surface.
* B. Drag the lookup table from the Globals section of the Palette to the automation surface to open the Select action window, and then filter for the ImportDelimitedFile method.
* C. Select the ImportDelimitedFile method in a design form of the user interface to open the Select action window.
* D. Drag the lookup table from the Locals section of the Palette to the automation surface to open the Select action window, and then filter for the ImportDelimitedFile method.

Answer: B

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
The Lookup Table is a global component in Pega Robot Studio that can be accessed from multiple automations within a project.
To use its methods-such as ImportDelimitedFile, FindRecord, or AddRecord-you must drag the lookup table instance from the Globals section to the automation surface.
According to the Pega Robotics System Design and Implementation Guide, section "Using Lookup Tables in Automations":
"Lookup tables are global components that store data used across automations.
To call lookup table methods, drag the table from the Globals section of the Palette to the automation design surface.
The Select Action dialog box will open, allowing you to filter and select from available methods such as ImportDelimitedFile, FindRecord, and ClearTable." Detailed Reasoning:
* A. Select the ImportDelimitedFile method in a design form... - Incorrect. The lookup table is not part of the UI form.
* B. Drag the lookup table from the Locals section... - Incorrect. Lookup tables exist under Globals, not Locals.
* C. Open the Globals tab and filter... - Incorrect. You must drag the component onto the automation surface to expose its methods.
* D. Drag the lookup table from the Globals section... - Correct. This exposes the ImportDelimitedFile method through the Select Action dialog.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Lookup Tables and Global Data Components section (Pega Robotics 19.1 and later).

NEW QUESTION # 75

When interrogating an application in a Chrome or Edge browser without X-ray Vision enabled, Pega Robot Studio uses only three match rules to uniquely identify the control. Which three match rules does Pega Robot Studio use when interrogating Chrome or Edge? (Choose Three)

* A. Native Control match rule
* B. Attribute Value match rule
* C. Control Children match rule
* D. Element Path match rule
* E. Web Control Children match rule
* F. Property Value match rule

Answer: B,D,F

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
According to the Pega Robotics Interrogation and Matching Engine Documentation:
"When you interrogate controls in a web application using Chrome or Edge browsers without X-ray Vision, Pega Robot Studio

utilizes a simplified set of match rules because these browsers do not expose a full DOM structure with automation identifiers." The documentation specifies:

"In non-X-ray Vision interrogation mode, the following three match rules are applied automatically to identify a control:

* Attribute Value Match Rule - Matches a control by its defined attribute (such as 'id', 'name', or 'class').

* Property Value Match Rule - Matches the control based on its property values exposed during interrogation (for example, 'InnerText' or 'TagName').

* Element Path Match Rule - Matches the control by its relative position in the DOM hierarchy." It also states:

"Without X-ray Vision, browser-specific identifiers and deep hierarchical context are not available; therefore, only the Attribute Value, Property Value, and Element Path rules are utilized for Chrome and Edge interrogation." References (Exact Extract Source):

* Pega Robotics Studio User Guide - Web Adapter and Match Rules Section

* Pega Academy - Robotics System Architect Course (Interrogation in Web Applications)

* Pega Robotics Help - Interrogation with and without X-ray Vision

Final Verified answer: B, C, F

NEW QUESTION # 76

You can adjust how users interact with a robotics project on their desktops. Which file stores the settings that control user functions and desktop robotic access?

- A. PegaConfig.xml
- B. PegaRuntimeConfig.xml
- C. CommonConfig.xml
- D. PegaStudioConfig.xml

Answer: B

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The PegaRuntimeConfig.xml file contains configuration settings that control how users interact with Pega Robot Runtime on their desktops.

These settings define parameters such as:

* Robot tray icon visibility

* Notification preferences

* Runtime startup behavior

* Access permissions for attended automation

According to the Pega Robotics System Design and Implementation Guide, section "Runtime Configuration Settings":

"The PegaRuntimeConfig.xml file defines user interaction settings and behavior of Pega Robot Runtime on end-user desktops.

It specifies configurations related to user access, tray icon visibility, notification pop-ups, and desktop automation permissions."

Detailed Reasoning:

* A. PegaConfig.xml - Not a valid configuration file in Pega Robotics.

* B. CommonConfig.xml - Used for shared system-wide connectivity and Robot Manager settings.

* C. PegaStudioConfig.xml - Stores configuration data for Pega Robot Studio (developer-specific).

* D. PegaRuntimeConfig.xml - Correct. Defines desktop-level user interaction and Runtime behavior.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Runtime Configuration File Overview section (Pega Robotics 19.1 and later).

NEW QUESTION # 77

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