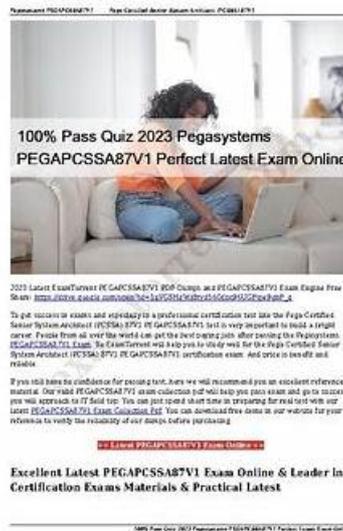


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### Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q52-Q57):

#### NEW QUESTION # 52

Pega Robotic Coding Standards suggest organization of project components. You have added the `_GC_CRM` project item to the `CRMPj`.

Which three components are recommended to be placed in the `_GC_CRM` project item? (Choose three.)

- A. `messageDialog`
- B. `ForLoop`
- C. `dateTimeUtils`
- D. `stringUtils`
- E. `Switch`

**Answer: A,C,D**

#### NEW QUESTION # 53

Which three of the following characterize automatic step creation? (Choose Three)

- A. Automatically used for applications that X-ray Vision does not support.
- B. **Automatically available for applications that X-ray Vision supports.**
- C. Usable at any time by clicking the Gear icon.
- D. **Displays a blue Gear icon.**
- E. **Available for previously interrogated application controls.**

**Answer: B,D,E**

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

Automatic Step Creation is a Pega Robot Studio feature that allows developers to automatically generate automation steps based on actions performed in an interrogated application. It leverages X-ray Vision for supported applications to intelligently detect UI elements and generate corresponding steps without requiring manual drag-and-drop logic creation.

According to the Pega Robotics System Design and Implementation Guide, section "Using Automatic Step Creation and X-ray Vision":

"Automatic Step Creation simplifies automation building by detecting user interactions in X-ray Vision- supported applications and automatically adding the equivalent automation steps to the design surface.

\* A blue gear icon indicates that automatic step creation is active and available.

\* Automatic step creation works with previously interrogated application controls.

\* The feature is automatically available for applications that X-ray Vision supports.

\* For applications not supported by X-ray Vision, developers must manually create steps using traditional interrogation." Detailed Reasoning:

Reasoning:

\* B. Displays a blue Gear icon.

\* Correct. When automatic step creation is active, the blue gear icon indicates the feature is enabled and ready to record actions.

\* D. Available for previously interrogated application controls.

\* Correct. Automatic step creation can only generate steps for controls that have already been interrogated, ensuring proper mapping between actions and UI elements.

\* E. Automatically available for applications that X-ray Vision supports.

\* Correct. The feature activates automatically in X-ray Vision-supported applications, which include modern UI frameworks like HTML5 and WPF.

Incorrect Options:

- \* A. Automatically used for applications that X-ray Vision does not support.
- \* Incorrect. It only works for applications supported by X-ray Vision.
- \* C. Usable at any time by clicking the Gear icon.
- \* Incorrect. The gear icon appears only when automatic step creation is available, not universally across all projects.

Final Correct answer: B, D, E

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Automatic Step Creation and X-ray Vision Integration section (Pega Robotics 19.1 and later).

#### NEW QUESTION # 54

A service request manager, who responds to 1000 active service tickets per week, receives a ticket for new account creation. This ticket has been marked as the highest priority and contains all the necessary details for an account creation.

The manager creates an activity and assigns all the context values with appropriate values.

Which two activity methods of the account creation ticket can be used to close the ticket within priority?

(Choose two.)

- A. StartAndWait
- B. StartNowAndWait
- C. StartNow
- D. Start

Answer: A,D

#### NEW QUESTION # 55

You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.

Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- B. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- C. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.
- D. The StartOnProject property of the application is set to false.

Answer: C

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.

According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:

"The StartMethod property defines how Pega Robot Studio connects to or starts an application.

When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.

If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:

- \* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
- \* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
- \* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
- \* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.

Option Analysis:

- \* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
- \* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
- \* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
- \* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation.

Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined. Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration - StartMethod and Path Property Requirements section (Pega Robotics 19.1 and later).

#### NEW QUESTION # 56

You have completed your development for the DisputeTransaction.peg file project. The enterprise installs the Pega Robot Runtime software on the agent's desktop.

The enterprise is ready to unit test your solution but wants the Runtime executable to automatically launch the new project. What do you configure to fulfill this request?

- A. Edit the setting in the PegaRuntimeConfig.xml by setting the value to the file location of the .peg file.
- B. Edit the setting in the DisputeTransaction.peg file by setting the value to the file location of the .peg file.
- C. Edit the setting in the PegaStudioConfig.xml by setting the value to the file location of the .peg file.
- D. Edit the setting in the CommonConfig.xml by setting the value to the file location of the .peg file.

**Answer: A**

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The PegaRuntimeConfig.xml file defines environment-specific configurations for the Pega Robot Runtime application.

To automatically launch a robotic solution (.peg file) when Runtime starts, you must configure the Startup Project path inside this XML file.

According to the Pega Robotics System Design and Implementation Guide, section "Configuring Pega Robot Runtime for Automatic Project Launch":

"To make Pega Robot Runtime automatically load and execute a robotic solution at startup, modify the PegaRuntimeConfig.xml file.

Within this file, specify the absolute path of the solution's .peg file under the <StartupProject> element.

When Pega Robot Runtime is launched, it reads this configuration and automatically opens the specified project." Detailed Reasoning:

\* A. PegaStudioConfig.xml - Incorrect. This file is specific to Robot Studio, not Runtime.

\* B. PegaRuntimeConfig.xml - Correct. The StartupProject element in this file defines which project (.peg file) to load automatically when Runtime starts.

\* C. CommonConfig.xml - Incorrect. Used for shared server and connection configurations, not for startup settings.

\* D. DisputeTransaction.peg - Incorrect. This file is a project package and does not contain configuration data.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Runtime Configuration and Project Auto-Launch Setup section (Pega Robotics 19.1 and later).

#### NEW QUESTION # 57

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