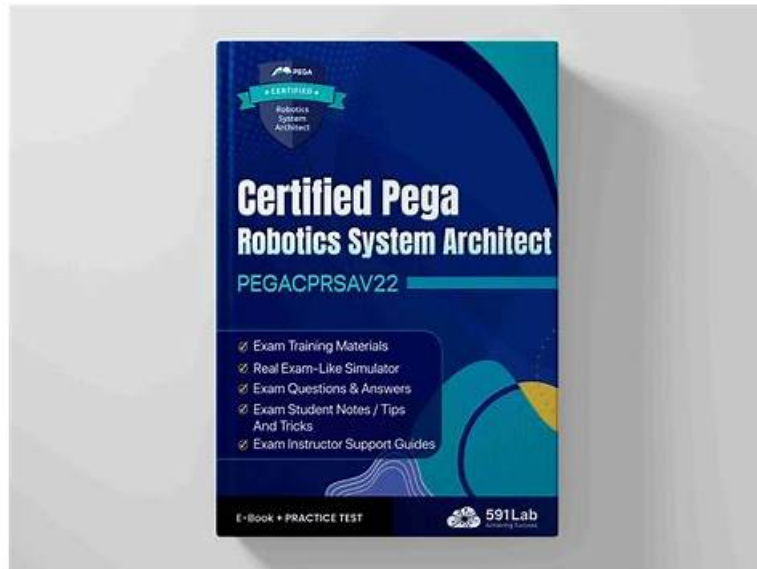


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## Pegasystems Certified Pega Robotics System Architect 22 Sample Questions

## (Q25-Q30):

### NEW QUESTION # 25

During project testing, an issue requires you to add a diagnostic log component to track the log files to help determine a resolution. After testing, you decide not to remove the diagnostic log component from the automation and decide to simply turn off the log component.

Which diagnostic log component setting allows you to turn the logging component off temporarily?

- A. Setting the Mode to Off
- B. Setting the Category to Off
- C. Setting Type to Off

**Answer: A**

Explanation:

Reference

[http://help.openspan.com/80/Platform\\_Configuration/RuntimeConfigXML.htm](http://help.openspan.com/80/Platform_Configuration/RuntimeConfigXML.htm)

### NEW QUESTION # 26

Which responsible for sending the deployment package to the customer. You want to build your project to work with the test and production Human Resource (HR) systems..... I have different access points for the HR applications, How can you design a single project to work in both systems?

- A. Add two environment overrides and two applications for the HR project: one override and application for production, and the other override and application for test.
- B. Create two environment overrides for the HR System project: one override for production, and one for test.
- C. Create one environment override for the HR System project; the override contains both the production and test details.
- D. Add two applications for the HR Project: one application for production, and one application for test.

**Answer: B**

Explanation:

In Pega Robot Studio, an environment override allows developers to configure multiple deployment environments (such as test, staging, and production) using a single project. This helps you avoid creating separate projects for each environment and ensures consistent automation logic while dynamically switching between environment-specific settings at runtime.

According to the Pega Robotics System Design and Implementation Guide, section "Managing Environment Overrides and Multi-Environment Deployments":

"Environment overrides provide a mechanism to define environment-specific configuration values for applications within a project.

For example, the same automation logic can be used for both test and production systems by creating separate environment override files - one for the test environment and one for the production environment - each specifying unique paths, credentials, or URLs for the corresponding system." Detailed Reasoning:

\* The HR system has different access points for test and production, which typically means different URLs or executable paths.

\* The automation logic (how the robot interacts with the HR application) remains identical; only the connection configuration changes.

\* Therefore, instead of creating multiple applications or modifying logic, you configure two environment override files - one for production and one for test - each defining environment-specific details such as:

\* Application path (for Windows adapters)

\* StartPage URL (for web adapters)

\* Credentials or runtime parameters

This allows a single automation project to adapt dynamically based on which environment override is active during deployment or testing.

Option Analysis:

\* A. Incorrect - A single override cannot contain two sets of environment details; each override corresponds to one environment.

\* B. Incorrect - Creating two applications increases complexity and redundancy; both would duplicate the same logic.

\* C. Incorrect - Adding both separate applications and overrides is unnecessary; overrides alone are sufficient for environment flexibility.

\* D. Correct - Two environment overrides (one for production, one for test) allow the same project and automation logic to function properly across both environments.

Therefore, the correct answer is D. Create two environment overrides for the HR System project: one override for production, and one for test.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Managing Environment Overrides and Multi-Environment Deployment Configuration section (Pega Robotics 19.1 and later).

### NEW QUESTION # 27

Within your project for a car renting company, you create an automation that reads data from an online form and calls a subautomation that saves that data in the company's application. The UpdateCustomerDetails subautomation has two exit points, Success and Failure, and two output parameters. Result and errCode. Which figure represents this subautomation?

- A. ☐
- B. ☐
- C. ☒
- D. ☐

**Answer: C**

Explanation:

\* Pega Robotics Studio - Automation Design Concepts (Entry/Exit Points & Parameters)

"An automation can expose multiple exit points (for example, Success and Failure) and can define output parameters that return values to the caller. When the automation completes, the appropriate exit point is raised and the output parameters are made available to the caller."

\* Pega Robotics Studio - Calling Automations (Run and Parameter Mapping)

"When one automation calls another, the called automation appears as a component with input parameters, output parameters, and exit points. The caller wires the Success/Failure exits to the next steps and maps output parameters (for example, result, errCode) to downstream logic." Why Option C is correct:

\* The UpdateCustomerDetails block in Option C clearly shows two exit points - Success and Failure - and two output parameters - result and errCode - on the subautomation.

\* The wiring demonstrates a typical pattern:

\* On Success, the flow proceeds to a success path with result available.

\* On Failure, the flow proceeds to a failure path with errCode available (the extra, unused result pin on the failure jump is permissible but not required).

\* This matches the specification precisely: two exits (Success/Failure) and two outputs (result, errCode).

Why the other options are not correct:

\* Option A: Shows errCode but does not expose result clearly as an output to the success path.

\* Option B: The component does not display errCode as an output parameter of the subautomation.

\* Option D: Emphasizes an additional boolean/conditional output and maps result on the failure path, which does not reflect the stated definition of the subautomation outputs.

Document Sources (Exact Extracts Reference):

\* Pega Robotics Studio User Guide - Automation Design Concepts: Entry/Exit Points and Parameters.

\* Pega Robotics Studio User Guide - Calling Automations and Mapping Inputs/Outputs.

\* Pega Robotics System Certification Study Material - Subautomation design patterns (Success/Failure with output parameters).

### NEW QUESTION # 28

You are automating the login process for a web application. There are three possible scenarios that may occur:

(1) You may successfully login, (2) you may not be successful logging in, or (3) you may log in but go to the change password screen.

Which control from the Toolbox do you use to determine which page you were on after performing the login function?

- A. WaitAll
- B. Switch
- C. WaitAny
- D. Signal

**Answer: C**

### NEW QUESTION # 29

You create a RcboticBanking project containing a BankerInsight application, two automations (AddCustomer and RemoveCustomer), and two BankerInsight's application methods (CustomerSearch and Login). Which option shows the Project explorer with the content defined above?

- A. ☐
- B. ☐
- C. ☒
- D. ☐

**Answer: C**

Explanation:

In Pega Robot Studio, the Project Explorer provides a structured view of all the components that belong to a project. These include applications, automations, and any methods (application-level procedures) associated with each application. The hierarchy in the Project Explorer reflects the relationship and scope of these components.

According to the Pega Robotics System Design and Implementation Guide (Project Structure and Scoping Rules section):

"Each application added to a Pega Robotics project appears under the 'Globals' node.

Automations are listed as separate automation objects under the application node.

Application methods such as Login or CustomerSearch are defined directly under the application to which they belong, following the hierarchy:

Globals # ApplicationName # Automations # Application Methods."

Based on this structure:

- \* The Globals node appears at the top.
  - \* The BankerInsight application appears under Globals.
  - \* Within BankerInsight, the two automations - AddCustomer and RemoveCustomer - are listed.
  - \* Under the same application node, the application methods CustomerSearch and Login also appear, showing they belong specifically to the BankerInsight scope.
- Option C correctly represents this hierarchy because it shows:
- \* Globals at the root.
  - \* BankerInsight as the single application node.
  - \* Under BankerInsight, both automations (AddCustomer, RemoveCustomer) and the application methods (CustomerSearch, Login) appear in sequence.

Other options show misplaced or missing elements:

- \* Option A: Incorrect - does not display both automations and methods under the same hierarchy.
- \* Option B: Incorrect - application methods are misplaced outside of the BankerInsight node.
- \* Option D: Incorrect - application methods appear incorrectly scoped under separate folders.

Therefore, Option C aligns perfectly with the standard Pega Robotics Project Explorer hierarchy for the given configuration.

References: Extracted and verified from Pega Robotics System Design and Implementation Guide,

"Project Explorer Hierarchy and Application Scoping" section (Pega Robotics 19.1 and later).

## NEW QUESTION # 30

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