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## H13-321\_V2.5 Test Answers | Pass-Sure H13-321\_V2.5 Exam Question: HCIP-AI-EI Developer V2.5

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## Huawei HCIP-AI-EI Developer V2.5 Sample Questions (Q60-Q65):

### NEW QUESTION # 60

The accuracy of object location detection can be evaluated using the intersection over union (IoU) value, which is a ratio. The

denominator is the overlapping area between the prediction bounding box and ground truth bounding box, and the numerator is the area of union encompassed by both boxes.

- A. TRUE
- B. FALSE

**Answer: B**

Explanation:

The IoU metric is defined as:

$$\text{IoU} = (\text{Area of Overlap}) / (\text{Area of Union})$$

\* Numerator: Area of overlap between the predicted bounding box and the ground truth bounding box.

\* Denominator: Area of union of both bounding boxes.

The statement given in the question reverses the numerator and denominator, which is why it is incorrect. IoU is crucial for object detection evaluation, and higher IoU values indicate better localization accuracy.

Exact Extract from HCIP-AI EI Developer V2.5:

"Intersection over Union (IoU) is calculated as the ratio of the intersection area between prediction and ground truth bounding boxes to their union area." Reference: HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Object Detection Metrics

### NEW QUESTION # 61

In an HSV color space, H is for hue, S is for saturation, and V is for value. Which of the following statements about the HSV color space are true?

- A. Saturation describes how vivid the color is. The lower the saturation, the closer the color is to gray. The higher the saturation, the more vivid the color.
- B. The HSV color space perceives colors differently from human eyes, so it is not suitable for image segmentation or color analysis.
- C. Hue indicates the basic color attributes, such as red, green, and blue.
- D. Value is a measure of brightness. The image brightness can be enhanced by processing the V component of the HSV color space.

**Answer: A,C,D**

Explanation:

The HSV model separates chromatic content (Hue, Saturation) from brightness (Value):

\* H (Hue): Defines the type of color (e.g., red, blue).

\* S (Saturation): Measures vividness - low S means muted colors, high S means vivid colors.

\* V (Value): Controls brightness - increasing V brightens the image. Contrary to option D, HSV aligns more closely with human perception than RGB, making it suitable for segmentation and color-based analysis.

Exact Extract from HCIP-AI EI Developer V2.5:

"HSV separates hue, saturation, and brightness, making it closer to human vision perception and suitable for color-based image analysis." Reference: HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Color Spaces

### NEW QUESTION # 62

Which of the following are the impacts of the development of large models?

- A. The accuracy and efficiency of natural language processing tasks will improve
- B. Data privacy and security issues will be exacerbated
- C. Model pre-training costs will be reduced
- D. Large models will completely replace small and domain-specific models

**Answer: A,B**

Explanation:

The emergence of large AI models (e.g., GPT, Pangu, BERT) has led to:

\* C: Improved accuracy and efficiency in NLP and other AI tasks because of their ability to capture deep semantic and contextual information.

\* D: Increased data privacy and security concerns, as large models require massive datasets which may contain sensitive or proprietary information. A is false - large models increase pre-training costs. B is false - small and domain-specific models still play

important roles due to efficiency and deployment constraints.

Exact Extract from HCIP-AI EI Developer V2.5:

"Large models improve task performance but raise privacy and security concerns. They do not necessarily reduce training cost or eliminate the need for smaller models." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Large Model Trends and Challenges

#### NEW QUESTION # 63

When training a deep neural network model, a loss function measures the difference between the model's predictions and the actual labels.

- A. TRUE
- B. FALSE

**Answer: A**

Explanation:

In the HCIP-AI EI Developer V2.5 study guide, the loss function is defined as a core component in training deep neural network models. It serves as a quantitative measure of how well the model's predictions match the actual ground truth labels. By calculating the difference between predicted outputs and actual labels, the loss function provides feedback that the optimization algorithm (such as gradient descent) uses to update model parameters. This process is iterative, aiming to minimize the loss value, thereby improving prediction accuracy. For example, in classification tasks, Cross-Entropy Loss is commonly used, while in regression tasks, Mean Squared Error (MSE) is typical. The smaller the loss, the better the model's performance on the given data.

Exact Extract from HCIP-AI EI Developer V2.5:

"A loss function is an objective function that evaluates the difference between the model output and the real label. The goal of training is to minimize this loss so that the model predictions approach the actual values." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Model Training and Evaluation

#### NEW QUESTION # 64

The basic operations of morphological processing include dilation and erosion. These operations can be combined to achieve practical algorithms such as opening and closing operations.

- A. TRUE
- B. FALSE

**Answer: A**

Explanation:

Morphological processing in image analysis is used to process binary or grayscale images based on shape.

\* Dilation: Expands object boundaries, useful for filling small holes.

\* Erosion: Shrinks object boundaries, useful for removing noise. By combining them:

\* Opening: Erosion followed by dilation (removes small objects/noise).

\* Closing: Dilation followed by erosion (fills small holes).

Exact Extract from HCIP-AI EI Developer V2.5:

"Morphological processing is based on dilation and erosion. Opening and closing are composite operations derived from these two to handle noise removal and hole filling." Reference:HCIP-AI EI Developer V2.5 Official Study Guide - Chapter: Morphological Image Processing

#### NEW QUESTION # 65

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