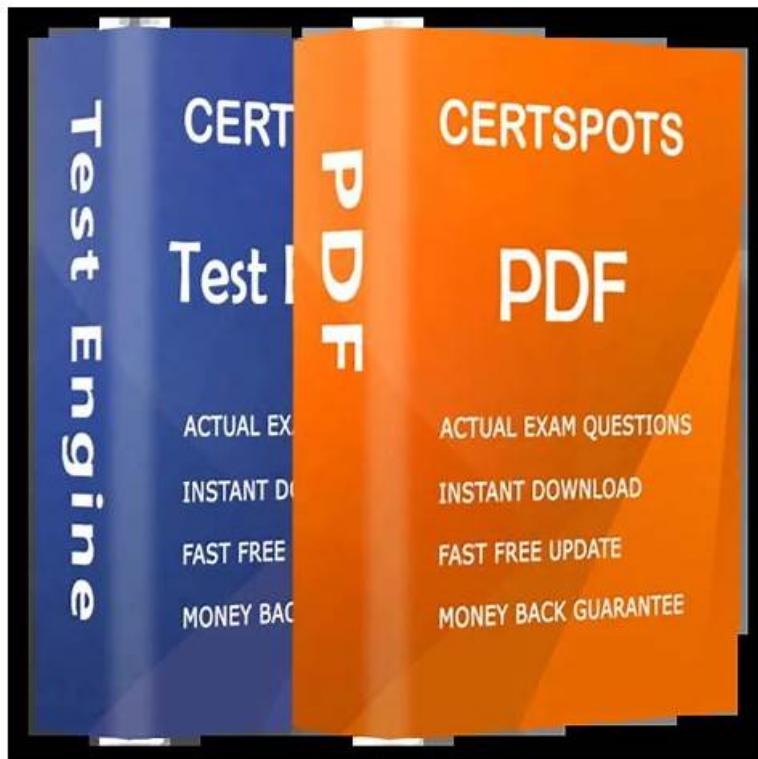# Valid PEGACPRSA22V1 Latest Exam Questions and High-Efficient PEGACPRSA22V1 Reliable Test Forum & Professional Certified Pega Robotics System Architect 22 Reliable Test Materials

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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q14-Q19):

NEW QUESTION # 14
You must configure an application to store encrypted login credentials in the user's local profile. You also need to automate the login using the encrypted credentials. How do you fulfill this requirement without creating an automation?

- A. Interrogate the target controls and create a script to perform the login functionality.
- B. Create a robot activity that performs the application login.
- C. Interrogate the target controls and set the necessary application credential properties.
- D. Set the necessary application credential properties before interrogating the target controls.

Answer: C

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
In Pega Robot Studio, the Credential Manager is designed to securely store user credentials (such as usernames and passwords) in an encrypted form within the user's local profile. When properly configured, Pega Robotics can automatically log in to target applications without creating a separate automation.
From the Pega Robotics System Design and Implementation Guide (Application Configuration and Credential Management section):
"When an application requires credential-based authentication, developers can configure the application's login controls during interrogation and assign the appropriate credential properties (Username and Password).
Once defined, credentials are stored securely in the user's local profile and automatically retrieved and decrypted during runtime to perform the login without explicit automation logic." Detailed Reasoning:
* During interrogation, the login controls (such as username and password fields) are identified and linked to the credential properties of the application object.
* Pega Robotics automatically handles the retrieval and secure decryption of credentials stored in the local user profile at runtime.
* This eliminates the need for any manual automation steps or scripts for logging in.
Option Analysis:
* A. Incorrect - Robot activities are server-executed tasks, not used for local application authentication.
* B. Incorrect - Credentials must be configured after interrogating target controls to map them correctly.
* C. Correct - Interrogating the login fields and setting the application credential properties allows Pega Robotics to securely manage and automate login automatically.
* D. Incorrect - Creating a script defeats the purpose of using the built-in credential manager.
Thus, Option C is the correct method for configuring automatic login using encrypted credentials.
Reference:Extracted from Pega Robotics System Design and Implementation Guide, Credential Manager and Application Authentication section (Pega Robotics 19.1 and later).

NEW QUESTION # 15
Which two of the following Tool Windows are used in Pega Robot Studio? (Choose two.)

- A. Object Explorer
- B. Solution Explorer
- C. Designer windows
- D. Menu toolbar

Answer: C,D

NEW QUESTION # 16
When you debug an automation, you have three function keys to use for navigating the breakpoints. Drag each navigation rule on the left to the box next to the correct function key on the right.

□

Answer:

Explanation:
Explanation:
□
When debugging automations in Pega Robot Studio, developers use specific function keys to control the flow of execution at breakpoints. Each key provides a distinct method for navigating through the automation logic during a debugging session.

According to the Pega Robotics System Design and Implementation Guide, section "Debugging Automations - Function Keys and Breakpoint Navigation":
"During debugging, Pega Robot Studio allows you to step through the automation's logic using three primary navigation commands:
* F10 (Step Over): Executes the current step and proceeds to the next event or data link, without stepping into nested automations or sub-events.
* F11 (Step Into): Executes the current step and enters any nested event link or sub-automation to debug internal logic.
* F5 (Continue): Continues running the automation until the next breakpoint is encountered." Detailed Reasoning:
* F10 - Step Over
* Moves to the next automation event or data link at the same level.
* Skips over nested or child automations while still executing them.
* F11 - Step Into
* Moves into the next automation event link or nested automation to debug its internal process.
* Useful when you need to analyze detailed event flow inside another automation.
* F5 - Continue
* Resumes automation execution at normal speed until it encounters the next breakpoint or finishes.
* Used to verify execution results after setting conditional breakpoints.
Final Correct Matching:
Navigation Rule
Function Key
Proceed to the next automation event or data link.
F10
Proceed to the next automation event link.
F11
Continue running the automation until the next breakpoint is reached.
F5
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Debugging Automations - Step Over, Step Into, and Continue Execution section (Pega Robotics 19.1 and later).

NEW QUESTION # 17
You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.
Why are you unable to interrogate the desired application controls?

- A. The StartOnProject property of the application is set to false.
- B. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- C. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- D. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.

Answer: D

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.
According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:
"The StartMethod property defines how Pega Robot Studio connects to or starts an application.
When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.
If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:
* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.
Option Analysis:

* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation.
Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration - StartMethod and Path Property Requirements section (Pega Robotics
19.1 and later).

NEW QUESTION # 18

A solution design document outlines several projects for the solution. You are assigned to the Loan Servicing project (LoanSvcPrj). The project uses the Interaction Framework function to communicate with the other projects.
Which three toolbox project items do you add to LoanSvcPrj? (Choose three.)

- A. Interaction Manager
- B. Message Manifest
- C. String Variable
- D. Activity
- E. Interaction.xml

Answer: C,D,E

NEW QUESTION # 19

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