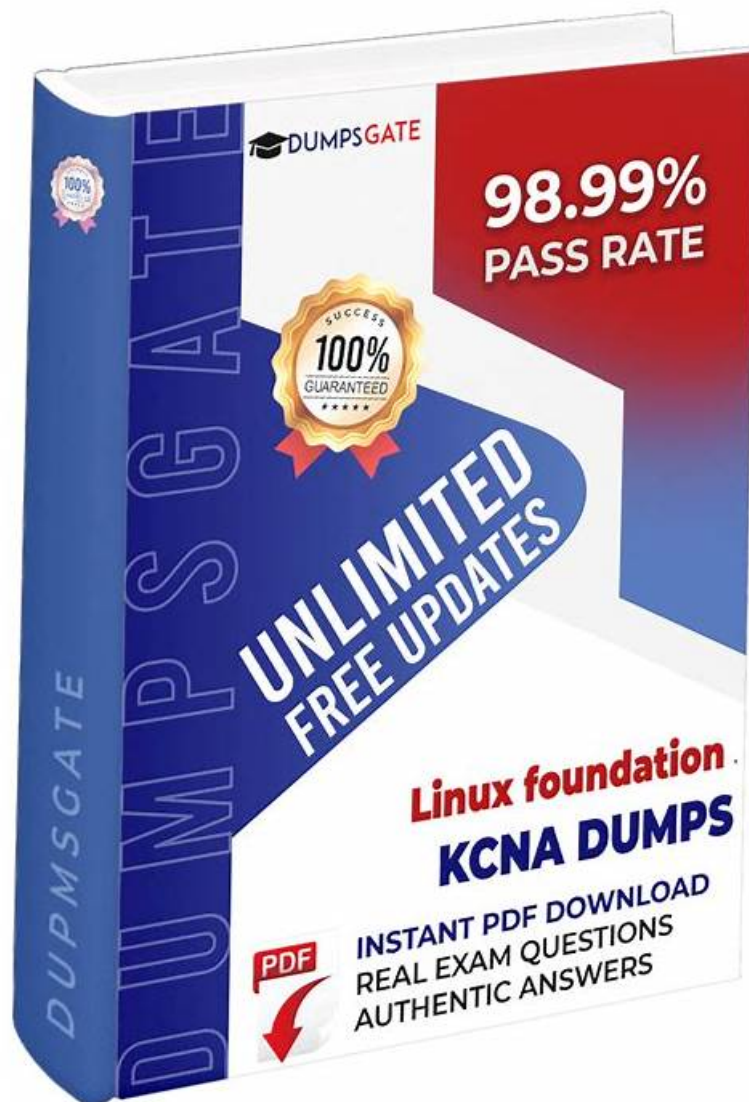


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Linux Foundation Kubernetes and Cloud Native Associate Sample Questions (Q12-Q17):

NEW QUESTION # 12

How does dynamic storage provisioning work?

- A. An administrator creates a PersistentVolume and includes the name of the PersistentVolume in their Pod YAML definition file.
- **B. A user requests dynamically provisioned storage by including an existing StorageClass in their PersistentVolumeClaim.**
- C. An administrator creates a StorageClass and includes it in their Pod YAML definition file without creating a PersistentVolumeClaim.
- D. A Pod requests dynamically provisioned storage by including a StorageClass and the Pod name in their PersistentVolumeClaim.

Answer: B

Explanation:

Dynamic provisioning is the Kubernetes mechanism where storage is created on-demand when a user creates a PersistentVolumeClaim (PVC) that references a StorageClass, so A is correct. In this model, the user does not need to pre-create a PersistentVolume (PV). Instead, the StorageClass points to a provisioner (typically a CSI driver) that knows how to create a volume in the underlying storage system (cloud disk, SAN, NAS, etc.). When the PVC is created with storageClassName: <class>, Kubernetes triggers the provisioner to create a new volume and then binds the resulting PV to that PVC.

This is why option B is incorrect: you do not put a StorageClass "in the Pod YAML" to request provisioning. Pods reference PVCs, not StorageClasses directly. Option C is incorrect because the PVC does not need the Pod name; binding is done via the PVC itself. Option D describes static provisioning: an admin pre-creates PVs and users claim them by creating PVCs that match the PV (capacity, access modes, selectors). Static provisioning can work, but it is not dynamic provisioning.

Under the hood, the StorageClass can define parameters like volume type, replication, encryption, and binding behavior (e.g., volumeBindingMode: WaitForFirstConsumer to delay provisioning until the Pod is scheduled, ensuring the volume is created in the correct zone). Reclaim policies (Delete/Retain) define what happens to the underlying volume after the PVC is deleted.

In cloud-native operations, dynamic provisioning is preferred because it improves developer self-service, reduces manual admin work, and makes scaling stateful workloads easier and faster. The essence is: PVC + StorageClass → automatic PV creation and binding.

NEW QUESTION # 13

Your application requires a specific storage class for its persistent data.

a. How do you configure this storage class within your deployment YAML?

- A. Specify the storage class name directly within the 'spec.template.spec.containers[0].volumeMounts[0].name' field of the deployment.
- B. Specify the storage class name within the 'spec.template.spec.containers[0].volumeMounts[0].storageClassName' field of the deployment.
- C. None of the above
- D. Specify the storage class name within the field of the deployment.

- E. Create a separate PersistentVolumeClaim (PVC) with the desired storage class and reference the PVC in the deployment's name' field.

Answer: E

Explanation:

The correct approach is to create a separate PersistentVolumeClaim (PVC) that specifies the desired storage class and reference the PVC in the deployments 'spec.template.spec.containers[0].volumeMounts[0].name' field. This ensures the PVC is automatically bound to a PV with the correct storage class. Specifying the storage class name directly within the deployment or the volumeMounts section is not the standard practice for defining storage requirements.

NEW QUESTION # 14

What kind of limitation cgroups allows?

- A. Prioritization
- B. Accounting
- C. Control
- D. Server cpu and memory
- E. None of the options
- F. Resource limiting

Answer: A,B,C,F

NEW QUESTION # 15

You're running a web application on Kubernetes that experiences occasional traffic spikes. Which of the following strategies is most suitable for managing costs during these spikes without compromising performance?

- A. Configure a resource quota for the web application's namespace to limit its resource usage.
- B. Use a horizontal pod autoscaler (HPA) with metrics based on CPU and memory utilization.
- C. Manually scale the deployment up during traffic spikes and down afterward.
- D. Implement a caching layer in front of the web application to reduce the load on the backend servers.
- E. Utilize serverless functions to handle the peak traffic load, automatically scaling as needed.

Answer: B,D

Explanation:

For web applications with unpredictable traffic patterns, dynamic scaling and load optimization are crucial for cost management. Horizontal Pod Autoscaler (HPA) with CPU and memory utilization metrics automatically scales the deployment up and down based on actual load, effectively managing resources during spikes. Implementing a caching layer reduces load on the backend servers, further reducing resource consumption and costs. Manually scaling is inefficient, and resource quotas don't address the dynamic nature of traffic spikes. While serverless functions offer scaling, they might not be suitable for all web application components.

NEW QUESTION # 16

Which kubectl command is useful for collecting information about any type of resource that is active in a Kubernetes cluster?

- A. describe
- B. explain
- C. list
- D. expose

Answer: A

Explanation:

The correct answer is A (describe), used as `kubectl describe <resource> <name>`. `kubectl describe` is a troubleshooting-focused command that provides a rich, human-readable view of a specific live object in the cluster, including key fields, status, and-crucially- Events related to that object. This makes it extremely useful for "collecting information" about almost any active resource: Pods, Deployments, Nodes, Services, PersistentVolumeClaims, and more. `kubectl get` (not listed) is typically used for listing objects and their summary fields, but `kubectl describe` goes deeper: for a Pod it will

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