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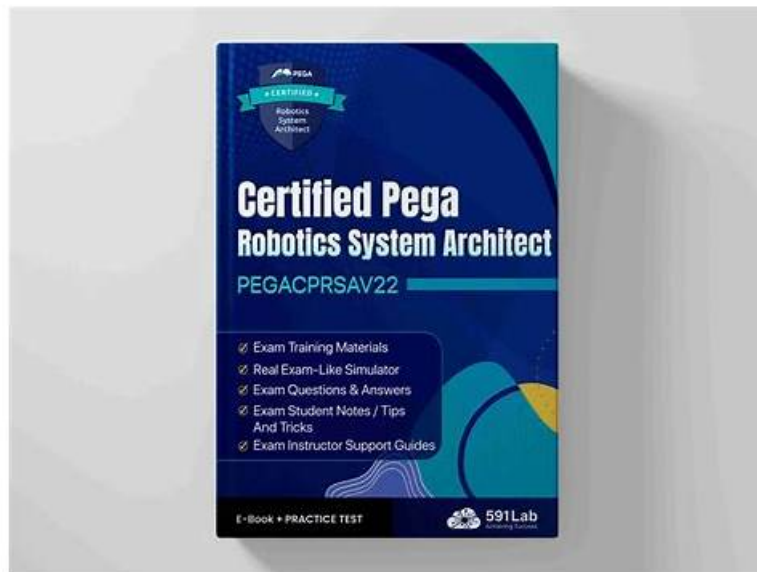
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Pegasystems PEGACPRSA22V1 exam is an essential certification test for professionals working with Pega's RPA tools. PEGACPRSA22V1 exam covers a range of topics related to RPA design and development, and passing it demonstrates a candidate's proficiency in the field. Certified Pega Robotics System Architect 22 certification is highly recommended for anyone who wants to validate their expertise in Pega's RPA tools and advance their career in this area.

The PEGACPRSA22V1 certification is ideal for individuals who are interested in pursuing a career in the field of robotic process automation (RPA) or those who are already working in the industry and want to enhance their knowledge and skills. Certified Pega Robotics System Architect 22 certification is recognized globally and is highly valued by employers, making it a valuable asset for anyone looking to advance their career in the RPA industry. Certified Pega Robotics System Architect 22 certification exam is available online and can be taken from anywhere in the world, making it accessible to individuals from different backgrounds and locations. Passing the PEGACPRSA22V1 Certification Exam demonstrates that the candidate has a thorough understanding of Pega Robotics and is capable of designing and implementing automation solutions using the platform.

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To prepare for the PEGACPRSA22V1 Certification Exam, candidates should have a solid understanding of Pega Robotics System Architect and its components. Candidates can prepare for the exam by attending training courses, reading study materials, and taking

practice exams. Pega offers a variety of training courses and materials to help candidates prepare for the exam. In addition, there are many online resources available that provide study materials and practice exams.

Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q28-Q33):

NEW QUESTION # 28
There are two basic types of automations: events and procedures.
Which three statements describe a procedure automation? (Choose three.)

- A. It contains an entry point and should contain at least one exit point.
- B. It performs business logic and may interact with applications.
- C. It may contain more than one starting block.
- D. It should return a string value for messaging.
- E. It is triggered by a user or application action.

Answer: A,C,D

NEW QUESTION # 29
Deploying a robotic project to Pega Robot Manager requires configuring the Pega server and credentials.
The server connectivity settings can be set up or adjusted in several ways.
Which three of the following options are methods to set up or adjust the Pega Server settings? (Choose Three)

- A. Edit the Change Server fields during the deployment process.
- B. Configure the server settings during the initial installation of Pega Robot Studio.
- C. Manually edit the PegaStudioConfig.xml file from the Tools menu in Pega Robot Studio.
- D. Edit the Server Connectivity settings in the Tools menu in Pega Robot Studio.
- E. Rerun the Pega Robot Studio installation and configure the server settings.

Answer: A,B,D

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
Pega Robot Studio provides multiple ways to configure or modify Pega Server connectivity settings used for Robot Manager deployment. These settings define the server URL, operator credentials, and authentication method.
According to the Pega Robotics System Design and Implementation Guide, section "Configuring Pega Server Connectivity":
"Server connectivity settings can be specified in multiple ways within Pega Robot Studio:
* During the initial installation process, when prompted to enter Robot Manager URL and credentials.
* By navigating to the Tools # Options # Server Connectivity menu to edit or test server details.
* By adjusting the Change Server fields that appear during the deployment process to override existing configurations.Manual editing of XML files is not recommended for changing server connectivity settings." Detailed Reasoning:
* A. Edit the Change Server fields during the deployment process - Correct. The deployment wizard allows adjusting or overriding existing server settings.
* B. Configure the server settings during the initial installation of Pega Robot Studio - Correct. The installation wizard prompts for server setup.
* C. Rerun the Pega Robot Studio installation and configure the server settings - Not necessary unless reinstallation is required.
* D. Manually edit the PegaStudioConfig.xml file - Not recommended or supported for changing connectivity.
* E. Edit the Server Connectivity settings in the Tools menu in Pega Robot Studio - Correct. This is the standard interface to modify or test connection settings.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Server Connectivity and Deployment Configuration section (Pega Robotics 19.1 and later).

NEW QUESTION # 30
You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.
Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.
- B. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- C. The StartOnProject property of the application is set to false.
- D. The StartMethod on the application is set to Start, but the TargetPath property is undefined.

Answer: A

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application.
When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.
According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:
"The StartMethod property defines how Pega Robot Studio connects to or starts an application.
When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.
If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:
* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.
Option Analysis:
* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation.
Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration - StartMethod and Path Property Requirements section (Pega Robotics
19.1 and later).

NEW QUESTION # 31
Based on the following image of a data model for a case, and assuming all records are relevant records, which property is not a scalar property that you cannot use to import export data with a robot activity?

- A. pyID
- B. Transactions
- C. AmountOfTransactionToDispute
- D. TransactionAmount

Answer: B

Explanation:
In Pega Platform, data objects used for integration with robot activities (whether attended or unattended) must be scalar properties -

that is, single-value fields such as Text, Decimal, Date, Boolean, etc. Scalar properties represent discrete, individual data elements that can be directly serialized and passed between Pega Platform and Pega Robot Studio automations.

According to the Pega Robotics System Design and Implementation Guide, section "Data Mapping Between Robot Activities and Pega Case Data":

"Robot activities can import and export data values only for scalar properties.

Scalar properties represent single data items, while complex or list structures (such as Page Lists or Page Groups) cannot be directly transferred.

Complex data types must be iterated or flattened before being used in a robot activity." In the image provided, the data model includes several scalar properties (e.g., AmountOfTransactionToDispute

, pyID, TransactionAmount) and one list-type property - Transactions, defined as a List of records.

Detailed Reasoning:

* A. AmountOfTransactionToDispute - Scalar property of type Decimal. Can be imported/exported by robot activities.

* B. pyID - Scalar property of type Text (single line). Can be used in robot activity data mapping.

* C. Transactions - Non-scalar property defined as a List of records.

* This represents a collection (a Page List) rather than a single field.

* Robot activities cannot directly import or export this type; it must be handled via iteration or transformation before use.

* D. TransactionAmount - Scalar property of type Decimal. Can be imported/exported normally.

Therefore, Transactions is the only non-scalar property in the model and cannot be directly imported or exported to or from a robot activity.

Final Correct answer: C. Transactions

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Data Mapping Between Pega Platform and Robot Activities - Scalar vs. Complex Properties section (Pega Robotics 19.1 and later).

NEW QUESTION # 32

Which two of the following Tool Windows are used in Pega Robot Studio? (Choose two.)

- A. Designer windows
- B. Object Explorer
- C. Menu toolbar
- D. Solution Explorer

Answer: A,C

NEW QUESTION # 33

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