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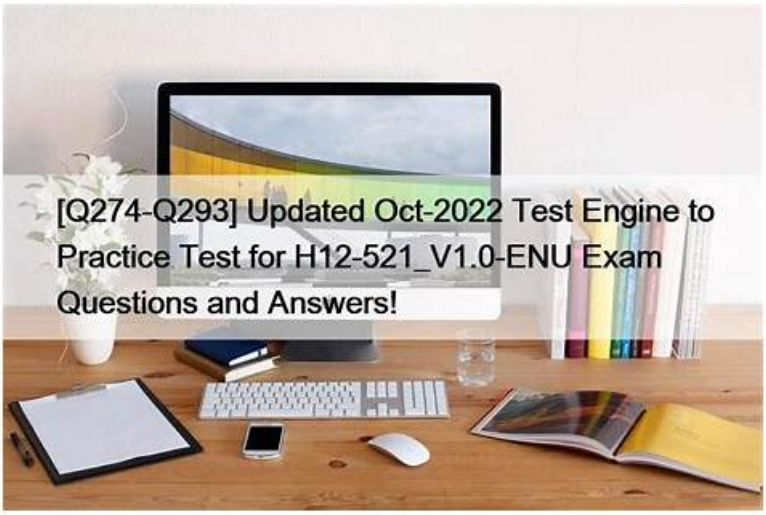

Our H12-521_V1.0-ENU training braindump is elaborately composed with major questions and answers. We are choosing the key from past materials to finish our H12-521_V1.0-ENU guide question. It only takes you 20 hours to 30 hours to do the practice. After your effective practice, you can master the examination point from the H12-521_V1.0-ENU Test Question. Then, you will have enough confidence to pass the H12-521_V1.0-ENU exam. What are you waiting for? Just come and buy our H12-521_V1.0-ENU exam questions!

Huawei H12-521_V1.0 certification exam is a comprehensive exam that covers a wide range of topics related to intelligent vision technology. It consists of 60 multiple-choice questions, which the candidates have to complete within 90 minutes. H12-521_V1.0-ENU Exam is available in both English and Chinese languages, and the candidates can choose the language they are most comfortable with.

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Users don't need to install any plugins or software to attempt the Huawei H12-521_V1.0-ENU practice exam. All operating systems support this format. The third and last format is HCIP-Intelligent Vision V1.0 H12-521_V1.0-ENU desktop software that can be used on Windows computers. The customers that have Windows laptops or computers can attempt the practice exam and prepare for it efficiently. These formats are in use by a lot of applicants currently and they are preparing for their best future on daily basis. Even the customers who have used it in the past for the preparation of Huawei H12-521_V1.0-ENU Certification Exam have rated our product as one of the best.

Huawei H12-521_V1.0 (HCIP-Intelligent Vision V1.0) Exam is a certification exam that validates the knowledge and skills of IT professionals in the field of intelligent vision technology. H12-521_V1.0-ENU exam is designed for individuals who have a strong understanding of intelligent vision solutions and are looking to enhance their knowledge in the field. H12-521_V1.0-ENU Exam covers a range of topics such as intelligent video analysis, intelligent video surveillance, and intelligent video processing.

Huawei HCIP-Intelligent Vision V1.0 Sample Questions (Q43-Q48):

NEW QUESTION # 43
In the central cloud platform solution, the data disk on Ocean Stor9000 is used to store structured and semi-structured data.

- A. False
- B. True

Answer: A

NEW QUESTION # 44
Gauss DB is widely used in video cloud platforms. Which of the following descriptions about Gauss DB OLTP are correct? (Multiple choice)

- A. Extreme performance
- B. Is a NoSQL database
- C. Simple and easy to use
- D. Safe and reliable

Answer: A,C,D

NEW QUESTION # 45
Which is the correct description of the SDC OS lightweight microservice governance framework?

- A. The purpose is to realize the management of third-party apps
- B. Mainly responsible for providing external interface services
- C. The framework is developed based on the Android kernel
- D. Realize service registration and discovery through file operations, and maintain inter-service communication

Answer: D

NEW QUESTION # 46
Which of the following reasons will not cause a large number of dropped calls has been registered in the camera platform? (Multiple choice)

- A. The account and password for camera access have expired
- B. There is a problem with the power supply line of the camera
- C. The network connecting the camera to the platform fails
- D. The time set by the camera is not synchronized with the time on the platform

Answer: A,D

NEW QUESTION # 47
The system determines whether an object crosses the tripwire based on which of the following criteria?

- A. Whether an object crosses the tripwire in the specified direction.
- B. Whether an object moves fast.
- C. Whether an object's movement trajectory intersects with the tripwire.
- D. Whether an object is moving.

Answer: C

Explanation:
The correct answer is C because tripwire crossing detection is fundamentally based on analyzing the movement trajectory of an object relative to a predefined virtual line. In intelligent vision systems, the object is first detected, then tracked frame by frame, and its centroid positions are recorded to form a trajectory. The material explains that "A movement trajectory consists of positions of the centroid of a moving object in individual frames" and also states that "To accurately predict whether an object is likely to cross the tripwire, features need to be extracted from the object... Dynamic features: trajectory, speed, and direction. Tripwire crossing detection mainly involves the extraction of dynamic features of an object." This means the decisive event is whether the tracked path intersects the configured tripwire. Speed alone does not determine crossing, and simply being in motion is insufficient. Direction can be an additional filtering condition in some deployments, but the actual crossing judgment is established through trajectory analysis. Therefore, the system concludes that an object has crossed the tripwire when its motion trajectory intersects the tripwire line, making C the most accurate answer.

NEW QUESTION # 48
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