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Nutanix Certified Associate v6.10 Sample Questions (Q46-Q51):

NEW QUESTION # 46

What is the minimum number of nodes required in a cluster for enabling Erasure Coding?

- A. 0
- B. 1
- C. 2
- **D. 3**

Answer: D

Explanation:

The correct answer is C. 4

Erasure Coding (EC-X) in Nutanix is a data efficiency feature that replaces multiple replicas with parity data to reduce storage overhead while still protecting against failures. The minimum node requirement for enabling Erasure Coding is 4 nodes, due to the need to distribute data and parity across multiple failure domains.

Details:

* RF2 with EC-X requires at least 4 nodes.

* RF3 with EC-X requires at least 6 or 8 nodes, depending on configuration.

Prism UI Navigation Path:

Storage > Storage Containers > Enable EC-X

Official Reference:

* Nutanix Bible - Erasure Coding Section

* Nutanix Storage Admin Guide

* Excerpt: "A minimum of 4 nodes is required in a Nutanix cluster to enable Erasure Coding (EC-X) with RF2."

NEW QUESTION # 47

What is true when adding a storage-only node to the cluster?

- A. Nutanix Files must be deployed.
- **B. It must have the same hypervisor as the other nodes in the cluster.**
- C. It can have a different hypervisor than the other nodes in the cluster.
- D. Nutanix Objects must be deployed.

Answer: B

Explanation:

The correct answer is C. It must have the same hypervisor as the other nodes in the cluster.

When adding a storage-only (SO) node to a Nutanix cluster:

* It must run the same hypervisor as the existing nodes.

* The SO node does not host VMs but participates in the storage layer to increase capacity and performance.

* Nutanix currently does not support mixed hypervisors (e.g., combining AHV with ESXi) within the same cluster, even for storage-only nodes.

Clarifications:

* A & B: Neither Nutanix Files nor Objects are required for adding storage-only nodes.

* D: Cross-hypervisor configuration is unsupported at the cluster level.

Official Reference:

* Nutanix Hardware Administration Guide - Storage-Only Node Requirements

* Excerpt: "All nodes in a cluster, including storage-only nodes, must run the same hypervisor type."

NEW QUESTION # 48

An administrator of an AHV cluster needs to deploy a solution that will provide self-service network provisioning and overlapping IP addresses for true multi-tenant networking with VPCs.

Which product will satisfy this requirement?

- **A. Flow Virtual Networking**
- B. Nutanix Kubernetes Platform
- C. Nutanix Database Service
- D. Flow Network Security

Answer: A

Explanation:

The correct answer is D. Flow Virtual Networking (FVN).

Flow Virtual Networking (FVN) is a Nutanix solution that enables advanced network virtualization, including:

- * VPCs (Virtual Private Clouds)
- * Overlapping IP address spaces
- * Self-service network provisioning
- * Multi-tenancy support
- * Microsegmentation

FVN abstracts physical networking and allows tenants to manage isolated logical networks, providing cloud-like networking capabilities directly integrated with AHV.

Clarifications:

- * A. Nutanix Kubernetes Platform (NKP): Orchestrates containers; does not provide virtualized network infrastructure.
- * B. Flow Network Security: Focuses on microsegmentation and policy enforcement, not on VPC or L3 abstraction.
- * C. Nutanix Database Service (NDB): Manages DBaaS; not related to networking.

Official Reference:

- * Nutanix Flow Virtual Networking Tech Note
- * Nutanix Documentation Portal - Flow Virtual Networking
- * Excerpt: "Flow Virtual Networking provides VPCs, overlapping IPs, and self-service networking capabilities for secure multi-tenancy in Nutanix AHV clusters."

NEW QUESTION # 49

Which Nutanix Disaster Recovery component or feature provides the best Recovery Time Objective (RTO)?

- A. Async
- B. Availability Zone
- C. NearSync
- **D. Metro Availability**

Answer: D

Explanation:

Nutanix Metro Availability provides the best Recovery Time Objective (RTO) because it enables synchronous replication between two sites. In the event of a failure at one site, VMs can be instantly restarted on the other site with minimal disruption. This setup ensures zero data loss and near-instantaneous recovery.

- * A. Async: Provides high RPO (Recovery Point Objective) but has a longer RTO compared to synchronous replication methods.
- * B. Availability Zone: This term refers to a general site setup, not specific to recovery objectives.
- * C. Metro Availability: Correct, as it uses synchronous replication for near-zero RTO.
- * D. NearSync: Provides better RPO than Async but does not match the RTO of Metro Availability.

References:

Nutanix Data Protection and Disaster Recovery Guide.

Nutanix University Certification Content.

NEW QUESTION # 50

Which AOS component is responsible for monitoring and eliminating hotspots within the cluster?

- A. Chronos
- **B. Acropolis Dynamic Scheduling**
- C. Controller Virtual Machine
- D. Cerebro

Answer: B

Explanation:

The correct answer is B. Acropolis Dynamic Scheduling (ADS).

Acropolis Dynamic Scheduling (ADS) is a core component in Nutanix AOS responsible for:

- * Monitoring real-time resource utilization.
- * Identifying hotspots such as CPU/memory/storage contention.

* Automatically initiating VM migration (live) to balance workloads across hosts in the cluster.

Clarification of Other Options:

* A. Cerebro: Responsible for replication, snapshots, and consistency.

* C. Chronos: Manages scheduling of distributed tasks (not resource balancing).

* D. CVM: Hosts the AOS services but does not perform workload balancing.

Official Reference:

* Nutanix Bible - Acropolis Dynamic Scheduling

* Nutanix AOS Architecture Guide

* Excerpt: "ADS monitors resource utilization across the cluster and performs live VM migrations to mitigate hotspots and balance performance."

NEW QUESTION # 51

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