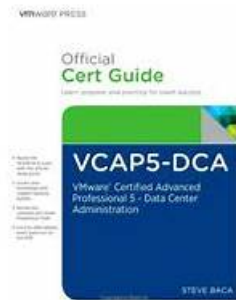


# Test DCA Guide - DCA Official Cert Guide



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To prepare for the Docker DCA exam, it is essential to have hands-on experience working with Docker. Docker provides a wealth of resources, including official documentation, training courses, and practice exams, to help individuals prepare for the exam. The official Docker documentation covers all the topics tested in the exam, and the training courses provide in-depth knowledge and practical experience in working with Docker. Practice exams are also available to help individuals familiarize themselves with the exam format and content.

Docker DCA Exam is a comprehensive exam that requires a significant amount of preparation. Candidates must have a strong understanding of Docker and must be able to apply their knowledge to real-world scenarios. DCA exam consists of 55 multiple-choice questions and has a time limit of 90 minutes. Candidates must attain a score of 65% or higher to pass the exam.

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## DCA Official Cert Guide | New DCA Exam Review

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## Docker Certified Associate (DCA) Exam Sample Questions (Q45-Q50):

### NEW QUESTION # 45

You want to provide a configuration file to a container at runtime. Does this set of Kubernetes tools and steps accomplish this?

Solution: Mount the configuration file directly into the appropriate pod and container using the `.spec.containers.configMounts` key.

- A. No
- B. Yes

**Answer: A**

Explanation:

The solution given is not a valid way to provide a configuration file to a container at runtime using Kubernetes tools and steps. The reason is that there is no such key as `.spec.containers.configMounts` in the `PodSpec`. The correct key to use is `.spec.containers.volumeMounts`, which specifies the volumes to mount into the container's filesystem<sup>1</sup>. To use a `ConfigMap` as a volume source, one needs to create a `ConfigMap` object that contains the configuration file as a key-value pair, and then reference it in the `.spec.volumes` section of the `PodSpec`<sup>2</sup>. A `ConfigMap` is a Kubernetes API object that lets you store configuration data for other objects to use<sup>3</sup>. For example, to provide a `nginx.conf` file to a `nginx` container, one can do the following steps:

\* Create a `ConfigMap` from the `nginx.conf` file:

```
kubectl create configmap nginx-config --from-file=nginx.conf
```

\* Create a Pod that mounts the `ConfigMap` as a volume and uses it as the configuration file for the `nginx` container:

```
apiVersion: v1
kind: Pod
metadata:
  name: nginx-pod
spec:
  containers:
  - name: nginx
    image: nginx
    volumeMounts:
    - name: config-volume
      mountPath: /etc/nginx/nginx.conf
      subPath: nginx.conf
  volumes:
  - name: config-volume
    configMap:
      name: nginx-config
```

References:

- \* [Configure a Pod to Use a Volume for Storage | Kubernetes](#)
- \* [Configure a Pod to Use a ConfigMap | Kubernetes](#)
- \* [ConfigMaps | Kubernetes](#)

### NEW QUESTION # 46

Does this command display all the pods in the cluster that are labeled as 'env: development'?

Solution: 'kubectl get pods --all-namespaces -I env=development'

- A. No
- B. Yes

**Answer: A**

Explanation:

The command 'kubectl get pods --all-namespaces -I env=development' does not display all the pods in the cluster that are labeled as 'env: development'. The reason is that the flag `-I` is not a valid option for `kubectl get pods`. The correct flag to use is `--selector` or `-l`, which allows you to filter pods by labels<sup>1</sup>. Labels are key-value pairs that can be attached to Kubernetes objects to identify,

group, or select them<sup>2</sup>. For example, to label a pod with env=development, one can run:

```
kubectl label pods my-pod env=development
```

To display all the pods that have the label env=development, one can run:

```
kubectl get pods --selector env=development
```

or

```
kubectl get pods -l env=development
```

The --all-namespaces flag can be used to list pods across all namespaces<sup>3</sup>. Therefore, the correct command to display all the pods in the cluster that are labeled as 'env: development' is:

```
kubectl get pods --all-namespaces --selector env=development
```

or

```
kubectl get pods --all-namespaces -l env=development
```

References:

- \* kubectl Cheat Sheet | Kubernetes
- \* Labels and Selectors | Kubernetes
- \* kubectl get | Kubernetes

### NEW QUESTION # 47

In the context of a swarm mode cluster, does this describe a node?

Solution: a physical machine participating in the swarm

- A. No
- **B. Yes**

**Answer: B**

Explanation:

Explanation

A physical machine participating in the swarm is a node in the context of a swarm mode cluster. A node is an instance of the Docker engine participating in the swarm. A node can be either a physical machine or a virtual machine. Nodes are either managers or workers. Managers maintain cluster state and manage cluster tasks.

Workers execute tasks assigned by managers. References:

<https://docs.docker.com/engine/swarm/key-concepts/#nodes-and-services>,

<https://docs.docker.com/engine/swarm/how-swarm-mode-works/nodes/>

### NEW QUESTION # 48

You created a new service named 'http\*' and discover it is not registering as healthy. Will this command enable you to view the list of historical tasks for this service?

Solution: 'docker inspect http'

- **A. No**
- B. Yes

**Answer: A**

Explanation:

The command docker inspect http will not enable you to view the list of historical tasks for the service. The docker inspect command returns low-level information on Docker objects, such as containers, images, networks, or volumes<sup>1</sup>. It does not work on services, which are higher-level objects that define the desired state of a set of tasks<sup>2</sup>. To view the list of historical tasks for a service, you need to use the docker service ps command, which shows the current and previous states of each task, as well as the node, error, and ports<sup>3</sup>. References:

\* docker inspect | Docker Docs

\* Services | Docker Docs

\* docker service ps | Docker Docs

### NEW QUESTION # 49

Seven managers are in a swarm cluster.

Is this how should they be distributed across three datacenters or availability zones?

Solution: 3-3-1

- A. No
- B. Yes

**Answer: A**

Explanation:

Explanation

= Distributing seven managers across three datacenters or availability zones as 3-3-1 is not the best way to ensure high availability and fault tolerance. This is because if one of the datacenters with three managers fails, the remaining four managers will not have a quorum to elect a leader and continue the swarm operations. A quorum is the minimum number of managers that must be available to maintain the swarm state, and it is calculated as  $(N/2) + 1$ , where N is the total number of managers<sup>1</sup>. For seven managers, the quorum is five, so losing three managers will cause the swarm to lose the quorum. A better way to distribute seven managers across three datacenters or availability zones is 2-2-3, which will allow the swarm to survive the failure of any one datacenter<sup>2</sup>. References:

\* Administer and maintain a swarm of Docker Engines

\* Distribute manager nodes across multiple AZ

## NEW QUESTION # 50

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