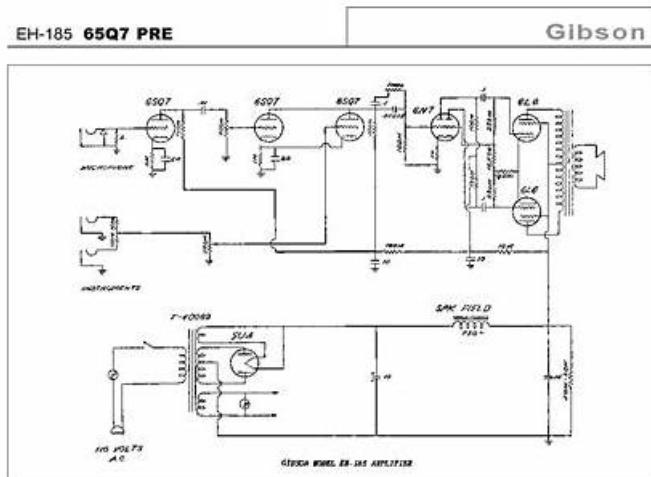


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## Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q81-Q86):

### NEW QUESTION # 81

As part of the initial development of a robotic project, you are using targeted step creation to interrogate a text input control. The system invokes the automation from a separate automation, and the value of the text input uses a value that is passed into the recorded automation.

In the Recording Steps list, move all of the options to the Ordered Recording Steps column and place them in the correct order.

**Answer:**

Explanation:

Explanation:

(Correct Order):

- \* Hover your pointer over the control.
- \* Click the Gear icon.
- \* Set the Action to Set Text.
- \* In the Value list, select Create New.
- \* Set the Value source to Input parameter.
- \* In the Name field, enter the name of the input parameter.
- \* Click Submit to save the input parameter.
- \* Click Save to save the step.

Targeted Step Creation is a Pega Robot Studio feature used to record automation steps directly by interacting with an interrogated control (for example, typing into a textbox). When the automation being recorded needs to receive data from another automation, an input parameter is configured as the value source for the recorded step.

According to the Pega Robotics System Design and Implementation Guide, section "Recording Steps and Configuring Input Parameters":

"When recording a targeted step for an input control:

- \* Hover over the target control and select the Gear icon to open the recording configuration.
- \* Choose the appropriate action (for example, Set Text for text boxes).
- \* Create a new value reference and select Input parameter as the value source.
- \* Assign a name to the input parameter that will be passed from the calling automation.
- \* Submit and save the step to finalize the recording."

Detailed Step Reasoning:

- \* Hover your pointer over the control.
- \* This initializes the control recognition in targeted step creation mode.
- \* Click the Gear icon.
- \* Opens the step configuration dialog for the selected control.
- \* Set the Action to Set Text.
- \* Defines the intended action for the control (entering text).
- \* In the Value list, select Create New.
- \* Creates a new value definition to assign data to the control.
- \* Set the Value source to Input parameter.
- \* Ensures that the value for the text input will come from an external automation that invokes this one.
- \* In the Name field, enter the name of the input parameter.
- \* Defines the name of the input variable so that it can be referenced when calling this automation.
- \* Click Submit to save the input parameter.
- \* Confirms and stores the parameter definition.
- \* Click Save to save the step.
- \* Finalizes the recorded step in the automation sequence.

Final Ordered Steps:

- \* Hover your pointer over the control.
- \* Click the Gear icon.
- \* Set the Action to Set Text.
- \* In the Value list, select Create New.
- \* Set the Value source to Input parameter.
- \* In the Name field, enter the name of the input parameter.
- \* Click Submit to save the input parameter.
- \* Click Save to save the step.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Recording Steps, Targeted Step Creation, and Input Parameter Configuration section (Pega Robotics 19.1 and later).

## NEW QUESTION # 82

When you debug an automation, you have three function keys to use for navigating the breakpoints. Drag each navigation rule on the left to the box next to the correct function key on the right.

### Answer:

Explanation:

Explanation:

When debugging automations in Pega Robot Studio, developers use specific function keys to control the flow of execution at

breakpoints. Each key provides a distinct method for navigating through the automation logic during a debugging session. According to the Pega Robotics System Design and Implementation Guide, section "Debugging Automations - Function Keys and Breakpoint Navigation":

"During debugging, Pega Robot Studio allows you to step through the automation's logic using three primary navigation commands:  
\* F10 (Step Over): Executes the current step and proceeds to the next event or data link, without stepping into nested automations or sub-events.

\* F11 (Step Into): Executes the current step and enters any nested event link or sub-automation to debug internal logic.

\* F5 (Continue): Continues running the automation until the next breakpoint is encountered." Detailed Reasoning:

\* F10 - Step Over

\* Moves to the next automation event or data link at the same level.

\* Skips over nested or child automations while still executing them

\* F11 - Step Into

\* Moves into the next automation event link or nested automation to debug its internal process.

\* Useful when you need to analyze detailed event flow inside another automation.

\* F5 - Continue

\* Resumes automation execution at normal speed until it encounters the next breakpoint or finishes.

\* Used to verify execution results after setting conditional breakpoints.

Final Correct Matching:

Navigation Rule

Function Key

Proceed to the next automation event or data link.

F10

Proceed to the next automation event link.

F11

Continue running the automation until the next breakpoint is reached.

F5

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Debugging Automations - Step Over, Step Into, and Continue Execution section (Pega Robotics 19.1 and later).

### NEW QUESTION # 83

During application discovery, what three things must the developer notice about the application to help design the automation? (Choose three.)

- A. How the automation responds to the process
- B. How the application responds during use
- C. How users interact with the applications
- D. How the application processes data
- E. How the adapter process data

**Answer: B,C,D**

Explanation:

Application discovery is an early technical validation step that involves collecting the information about applications in scope of a potential robotics use case. During discovery you need to find out application types (and if they are on applications support matrix for Pega Robotics), how they are launched, how they are used, and check accessibility and functionality of the controls through interrogation. Application discovery is necessary to ensure that robotics use case is viable and it doesn't have any technical constraints... or, if constraints exist, then what kind of workarounds will be necessary to ensure the use case is successful. The rationale for having application discovery as a best practice is that you don't want to find out half-way through coding an automation that a key control is not available or not performing the desired action.

### NEW QUESTION # 84

When interrogating a Windows control, the drag and drop Default interrogation method does not work. You decide to use the Create Control option to interrogate the control.

From the Interrogation Steps list, move all of the options to the Ordered Interrogation Steps column and place them in the correct order.

□

**Answer:**

Explanation:

### NEW QUESTION # 85

When interrogating an application in a Chrome or Edge browser without X-ray Vision enabled, Pega Robot Studio uses only three match rules to uniquely identify the control. Which three match rules does Pega Robot Studio use when interrogating Chrome or Edge? (Choose Three)

- A. Property Value match rule
- B. Native Control match rule
- C. Web Control Children match rule
- D. Attribute Value match rule
- E. Element Path match rule
- F. Control Children match rule

Answer: A,D,E

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

According to the Pega Robotics Interrogation and Matching Engine Documentation:

"When you interrogate controls in a web application using Chrome or Edge browsers without X-ray Vision, Pega Robot Studio utilizes a simplified set of match rules because these browsers do not expose a full DOM structure with automation identifiers." The documentation specifies:

"In non-X-ray Vision interrogation mode, the following three match rules are applied automatically to identify a control:

\* Attribute Value Match Rule - Matches a control by its defined attribute (such as 'id', 'name', or 'class').

\* Property Value Match Rule - Matches the control based on its property values exposed during interrogation (for example, 'InnerText' or 'TagName').

\* Element Path Match Rule - Matches the control by its relative position in the DOM hierarchy." It also states:

"Without X-ray Vision, browser-specific identifiers and deep hierarchical context are not available; therefore, only the Attribute Value, Property Value, and Element Path rules are utilized for Chrome and Edge interrogation." References (Exact Extract Source):

\* Pega Robotics Studio User Guide - Web Adapter and Match Rules Section

\* Pega Academy - Robotics System Architect Course (Interrogation in Web Applications)

\* Pega Robotics Help - Interrogation with and without X-ray Vision

Final Verified answer: B, C, F

### NEW QUESTION # 86

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