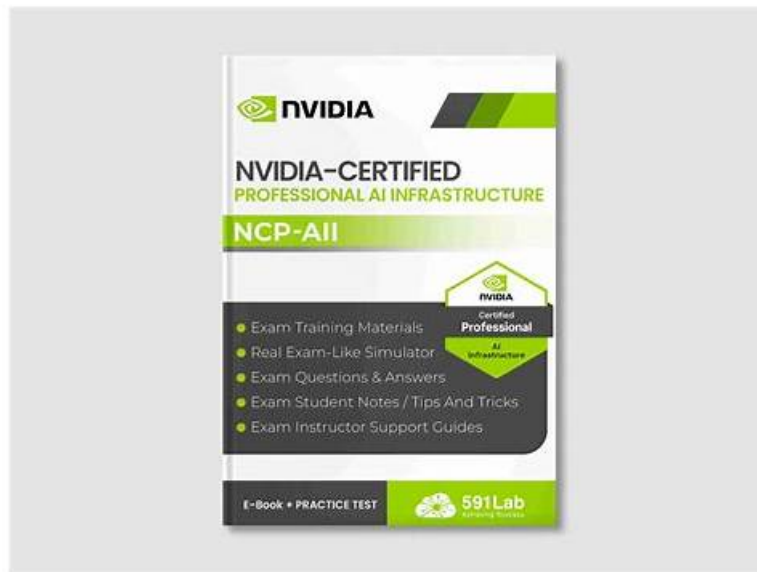


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NVIDIA AI Infrastructure Sample Questions (Q100-Q105):

NEW QUESTION # 100

You have a BlueField-2 DPU running Ubuntu. After upgrading the MLNX OFED drivers, the DPU fails to boot properly. You are presented with a GRUB prompt. Which sequence of commands is most likely to help you boot into a working kernel?

- A.

```
set root=(hd0,gpt2)
linux /boot/vmlinuz-old root=/dev/sda2 ro
initrd /boot/initrd.img-old
boot
```

- B.

```
set root=(hd0,gpt2)
linux /boot/vmlinuz-$(uname -r) root=/dev/sda2 ro
initrd /boot/initrd.img-$(uname -r)
boot
```
- C.

```
set root=(hd0,gpt2)
linux /boot/vmlinuz-$(uname -r) root=/dev/nvme0n1p2 ro
initrd /boot/initrd.img-$(uname -r)
boot
```
- D.

```
set root=(hd0,gpt2)
normal
boot
```
- E.

```
set root=(hd0,gpt2)
linux /vmlinuz root=/dev/sda2 ro
initrd /initrd.img
boot
```

Answer: A

Explanation:

When a boot fails after a driver upgrade, it's often because the new kernel/initrd is faulty. The most likely solution is to boot into the previous, known-good kernel. Option C attempts this by specifying '-old' in the kernel and initrd filenames, attempting to load the older, hopefully functional, kernel. It assumes the root partition is /dev/sda2 but is booting an older kernel. Option A uses '\$(uname -r)' which likely resolves to the problematic kernel that caused the failure. Option B lacks version information and may also load a broken kernel. Option D uses /dev/nvme0n1p2, which might be incorrect for the root partition on the BlueField. Option E will try to load grub normally, which might fail again.

NEW QUESTION # 101

You are tasked with installing the latest NVIDIA driver on a server running Ubuntu 22.04 for A1 workloads. You have downloaded the driver package 'NVIDIA-Linux-x86_64-535.104.05.run'. Before installation, what is the most critical step to ensure a smooth process, assuming secure boot is enabled?

- A. Install the driver using 'apt install nvidia-driver-535' and let the system handle Secure Boot automatically.
- B. Simply run the '.run' file using 'sudo ./NVIDIA-Linux-x86_64-535.104.05.run'.
- C. Ensure the 'nouveau' driver is blacklisted by adding 'blacklist nouveau' to 'etc/modprobe.d/blacklist-nouveau.conf'.
- D. Disable Secure Boot in the BIOS before installing the driver.
- E. Create a DKMS module and sign the driver with a machine owner key (MOK) for Secure Boot compatibility.

Answer: C,E

Explanation:

Secure Boot requires kernel modules to be signed. Directly running the '.run' file or disabling Secure Boot are generally not recommended. DKMS and MOK signing allows the driver to be validated by the system. Blacklisting nouveau ensures that it won't conflict with the NVIDIA driver. Installing via apt doesn't guarantee Secure Boot compatibility without further steps, so the best approach involves DKMS/MOK and blacklisting.

NEW QUESTION # 102

Which of the following is a primary benefit of using a CLOS network topology (e.g., Spine-Leaf) in a data center?

- A. Improved scalability and bandwidth utilization
- B. Enhanced security
- C. Increased network diameter
- D. Simplified network management
- E. Reduced capital expenditure (CAPEX)

Answer: A

Explanation:

CLOS networks like Spine-Leaf provide excellent scalability due to their non-blocking architecture, allowing for increased bandwidth utilization and easy expansion. CAPEX might be higher due to more switches. The network diameter can be larger compared to traditional topologies. While CLOS networks can be managed effectively, the management complexity can be higher. Security benefits are not a primary characteristic of the CLOS topology itself.

NEW QUESTION # 103

You want to limit the GPU memory available to a specific Docker container running a deep learning model. Which of the following 'docker run' commands using the NVIDIA Container Toolkit is the most appropriate?

- A. `docker run -gpus all -memory 4g my-image`
- **B. `docker run -gpus 'device=GPU-UUID:memory=4g' my-image`**
- C. `docker run -gpus device=0 --memory 4g my-image`
- D. `docker run -gpus all,memory=4g my-image`
- E. `docker run -gpus 'device=0:memory=4g' my-image`

Answer: B

Explanation:

The correct syntax to limit GPU memory for a Docker container using the NVIDIA Container Toolkit involves specifying the GPU device using its UUID and then setting the memory limit. '`docker run --gpus "'device=GPU-UUID:memory=4g'" my-image`' is the correct way to achieve this. The others are syntactically incorrect or do not utilize the intended functionality. You need to find the GPU UUID using 'nvidia-smi' and replace 'GPU-UUID' with it.

NEW QUESTION # 104

You are using NVIDIA Spectrum-X switches in your AI infrastructure. You observe high latency between two GPU servers during a large distributed training job. After analyzing the switch telemetry, you suspect a suboptimal routing path is contributing to the problem. Which of the following methods offers the MOST granular control for influencing traffic flow within the Spectrum-X fabric to mitigate this?

- A. Disable IPv6 to simplify routing decisions.
- **B. Implement Adaptive Routing (AR) or Dynamic Load Balancing (DLB) features available on the Spectrum-X switches to dynamically adjust paths based on network conditions.**
- C. Adjust the Equal-Cost Multi-Path (ECMP) hashing algorithm globally on all switches.
- D. Manually configure static routes on the Spectrum-X switches to force traffic between the GPU servers along a specific path.
- E. Configure QOS (Quality of Service) policies to prioritize traffic from the high-latency GPU servers.

Answer: B

Explanation:

Adaptive Routing (AR) and Dynamic Load Balancing (DLB) are features specifically designed to dynamically adjust paths based on real-time network conditions in Spectrum-X. This provides the most granular and automated way to respond to congestion and optimize traffic flow compared to static routing or global ECMP adjustments. QOS prioritizes, but doesn't change the chosen path.

NEW QUESTION # 105

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