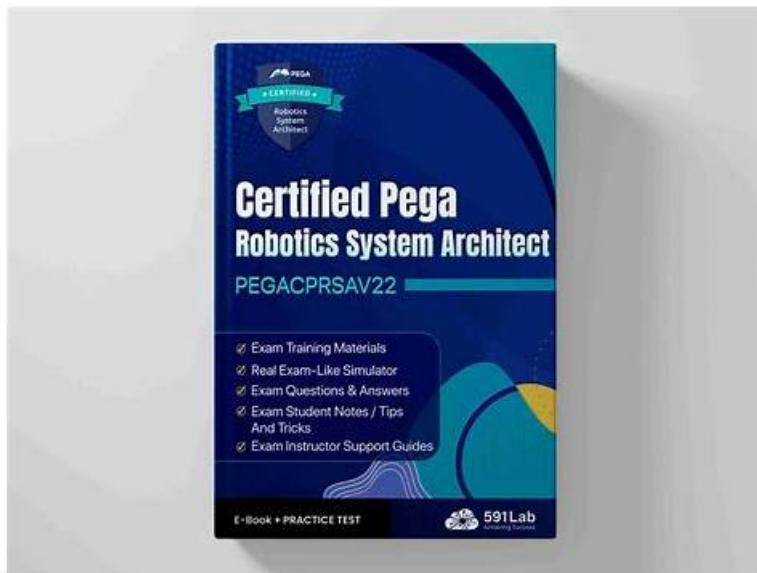


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## Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q99-Q104):

### NEW QUESTION # 99

While interrogating a web application, you discover a hidden menu item: AddressType. The AddressType menu item activates when the pointer hovers over the control, and the menu displays a drop-down list.

Which two options can you use to interrogate this hidden drop-down list control? (Choose Two)

- A. In the Interrogation Form dialog box, select HTML Table Editor.
- B. Use the Delay option on the Interrogation Form.

- C. On the Application tab, click the Virtual Controls tab.
- **D. On the Interrogation Form, select Select Element.**
- E. On the Web Controls tab, select the page, and then click List Web Controls.

**Answer: B,D**

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

During interrogation of web applications, developers often encounter dynamic or hidden controls - such as drop-down menus or hover-triggered lists - that do not immediately appear on the page.

To successfully interrogate these elements, Pega Robot Studio provides two essential tools:

- \* The Delay option on the Interrogation Form, which allows the developer time to trigger the hidden control before capture.
- \* The Select Element option, which enables precise selection of an element directly from the DOM, even if it is not immediately visible.

According to the Pega Robotics System Design and Implementation Guide, section "Interrogating Dynamic and Hidden Web Controls":

"When interrogating hidden or dynamically rendered controls:

- \* Use the Delay option on the Interrogation Form to give yourself time to hover over or activate a hidden control before Robot Studio attempts to capture it.
- \* Use the Select Element option to manually highlight and select a control from the web application's DOM, even when it is displayed only after an interaction such as mouse hover. These methods are particularly effective for controls that expand or render asynchronously, such as drop-down menus or tooltip-triggered elements." Detailed Step Reasoning:
- \* C. Use the Delay option on the Interrogation Form
- \* Correct.
- \* The Delay setting pauses the interrogation process for a specified number of seconds, allowing you to hover over the hidden element (e.g., AddressType menu) and make it visible before capture.
- \* Once the menu appears, Pega Robot Studio can detect and interrogate it.
- \* D. On the Interrogation Form, select Select Element.
- \* Correct.
- \* The Select Element tool allows manual selection of an element directly from the web page's HTML DOM structure.
- \* This is especially useful for hidden or dynamically rendered elements like the AddressType dropdown that may not be visible until hovered over.

Incorrect Options Explained:

- \* A. In the Interrogation Form dialog box, select HTML Table Editor.
- \* Incorrect.
- \* The HTML Table Editor is used to inspect and modify HTML table-based controls (grid or table structures), not dynamic menus.
- \* B. On the Web Controls tab, select the page, and then click List Web Controls.
- \* Incorrect.
- \* The List Web Controls option lists already recognized controls in the DOM but cannot reveal or capture hidden dynamic elements.
- \* E. On the Application tab, click the Virtual Controls tab.
- \* Incorrect.
- \* Virtual Controls are used for defining custom controls when the default adapter cannot identify one, not for capturing hidden menu elements.

Final Correct answer:

C). Use the Delay option on the Interrogation Form  
 D). On the Interrogation Form, select Select Element.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Interrogating Dynamic, Hidden, and Hover-Activated Controls section (Pega Robotics 19.1 and later).

## NEW QUESTION # 100

When developing automations and robotic projects for use with Pega applications, there are recommended design specifics and considerations for the developer. Of the options below, which three are recommended developer considerations? (Choose Three)

- **A. Ensure data formats agree between the automation and the Pega application.**
- B. Use an unlimited number of transferable data items.
- C. Run automations synchronously.
- **D. Set valid completion status.**
- **E. Match the Pega automation identifier with the robot activity component name.**
- F. Design an automation to complete multiple tasks.

## Answer: A,D,E

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

When building robotic automations intended for integration with Pega Platform (through Robotic Desktop Automation (RDA) or Robotic Process Automation (RPA)), Pega Systems outlines a set of best practices to ensure reliable execution, data consistency, and seamless communication between the automation and Pega case workflows.

According to the Pega Robotics System Design and Implementation Guide, in the section "Developing Robot Activities for Pega Integration", the following recommendations are provided:

"When developing automations intended for execution by Pega applications, adhere to the following guidelines:

- \* Always return a valid completion status from the automation to indicate success or failure to the calling Pega activity.
- \* Ensure that the data exchanged between Pega Platform and the automation matches in both type and format to prevent runtime errors or data transformation issues.
- \* The activity name in Pega Platform (as specified in the robotic automation name field) must exactly match the name defined in the Robot Activity component in Robot Studio to establish a valid invocation link." Detailed Reasoning:
- \* A. Set valid completion status.
- \* Correct. Each automation that is invoked from Pega must return a valid completion status (e.g., Success, Fail, Completed, Error). This status is sent back through the Robot Activity response data transform.
- \* This ensures that the Pega case or data page correctly interprets the automation's result and can take subsequent actions (e.g., proceed, retry, or raise an exception).
- \* D. Ensure data formats agree between the automation and the Pega application.
- \* Correct. The data types and structure between Pega and the robotic automation must align (for example, string-to-string, integer-to-integer, JSON format consistency).
- \* Mismatched or unstructured data results in serialization errors when passing data through the RDA bridge.

\* E. Match the Pega automation identifier with the robot activity component name.

\* Correct. The Robotic Automation Name specified in the Pega data page or case configuration (e.g., FETCH\_SCORE) must exactly match the ActivityName property defined in the Robot Studio's Robot Activity component.

\* This linkage ensures that the correct automation is triggered when the case executes the RDA call.

Incorrect Options:

- \* B. Design an automation to complete multiple tasks.
- \* Not recommended. Pega advises building modular automations, where each automation performs a single defined task to simplify debugging and improve reuse.
- \* C. Use an unlimited number of transferable data items.
- \* Not recommended. The number of data items passed between Pega and Robotics should be limited to those necessary for the task, as excessive data transfers can degrade performance.
- \* F. Run automations synchronously.
- \* Not required. RDA automations typically run asynchronously, returning results through callback mechanisms to avoid blocking the user interface.

Therefore, the three recommended developer considerations are:

A). Set valid completion status

D). Ensure data formats agree between the automation and the Pega application E). Match the Pega automation identifier with the robot activity component name Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Developing and Configuring Robot Activities for Pega Integration section (Pega Robotics 19.1 and later).

## NEW QUESTION # 101

Which responsible for sending the deployment package to the customer. You want to build your project to work with the test and production Human Resource (HR) systems..... I have different access points for the HR applications, How can you design a single project to work in both systems?

- A. Add two applications for the HR Project: one application for production, and one application for test.
- B. **Create two environment overrides for the HR System project: one override for production, and one for test.**
- C. Add two environment overrides and two applications for the HR project: one override and application for production, and the other override and application for test.
- D. Create one environment override for the HR System project; the override contains both the production and test details.

## Answer: B

Explanation:

In Pega Robot Studio, an environment override allows developers to configure multiple deployment environments (such as test, staging, and production) using a single project. This helps you avoid creating separate projects for each environment and ensures

consistent automation logic while dynamically switching between environment-specific settings at runtime.

According to the Pega Robotics System Design and Implementation Guide, section "Managing Environment Overrides and Multi-Environment Deployments":

"Environment overrides provide a mechanism to define environment-specific configuration values for applications within a project. For example, the same automation logic can be used for both test and production systems by creating separate environment override files - one for the test environment and one for the production environment - each specifying unique paths, credentials, or URLs for the corresponding system." Detailed Reasoning:

\* The HR system has different access points for test and production, which typically means different URLs or executable paths.

\* The automation logic (how the robot interacts with the HR application) remains identical; only the connection configuration changes.

\* Therefore, instead of creating multiple applications or modifying logic, you configure two environment override files - one for production and one for test - each defining environment-specific details such as:

\* Application path (for Windows adapters)

\* StartPage URL (for web adapters)

\* Credentials or runtime parameters

This allows a single automation project to adapt dynamically based on which environment override is active during deployment or testing.

Option Analysis:

\* A. Incorrect - A single override cannot contain two sets of environment details; each override corresponds to one environment.

\* B. Incorrect - Creating two applications increases complexity and redundancy; both would duplicate the same logic.

\* C. Incorrect - Adding both separate applications and overrides is unnecessary; overrides alone are sufficient for environment flexibility.

\* D. Correct - Two environment overrides (one for production, one for test) allow the same project and automation logic to function properly across both environments.

Therefore, the correct answer is D. Create two environment overrides for the HR System project: one override for production, and one for test.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Managing Environment Overrides and Multi-Environment Deployment Configuration section (Pega Robotics 19.1 and later).

## NEW QUESTION # 102

Which two of the following tasks are not suitable for Pega Robotic Automation? (Choose Two)

- A. Complex processes that require human decision management.
- B. Processes that require access to multiple windows or applications.
- C. Rules-driven processes that users cannot easily perform in Pega Platform.
- D. Repetitive tasks that require manual work.
- E. Rarely occurring processes such as sending annual reports.

Answer: A,E

Explanation:

Comprehensive and Detailed Explanation from Pega Robotics System (Exact Extract & Context):

According to the Pega Robotics Automation Design and Implementation Guide:

"Robotic Automation is best suited for rule-based, repetitive, and structured tasks that do not require subjective judgment or complex decision-making." The guide further clarifies:

"Tasks that involve human decision-making, subjective evaluation, or business judgment are not suitable for automation through RPA, as these require contextual understanding and cognitive reasoning." It also specifies:

"Processes that occur infrequently, such as quarterly or annual events, are not ideal candidates for automation due to low execution frequency and limited ROI from automation development and maintenance." Therefore:

\* Option A: Complex processes that require human decision management - # Not suitable, as they depend on human reasoning.

\* Option D: Rarely occurring processes such as sending annual reports - # Not suitable, since they do not provide sufficient automation value or frequency.

\* Options B, C, and E describe processes that are well-suited for Pega Robotics (they are repetitive, multi-application, or rules-driven).

Document References (Exact Extracts Source)

\* Pega Robotics Automation Design and Implementation Guide - Identifying Suitable Tasks for Automation

\* Pega Robotic Process Automation Studio Training Material - Process Selection and ROI Criteria

\* Pega Certified Robotics System Architect Study Guide - Automation Best Practices Section Final Verified answer: A and D

### NEW QUESTION # 103

You can adjust how users interact with a robotics project on their desktops. Which file stores the settings that control user functions and desktop robotic access?

- A. CommonConfig.xml
- B. PegaStudioConfig.xml
- C. PegaConfig.xml
- D. **PegaRuntimeConfig.xml**

#### Answer: D

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The PegaRuntimeConfig.xml file contains configuration settings that control how users interact with Pega Robot Runtime on their desktops.

These settings define parameters such as:

- \* Robot tray icon visibility
- \* Notification preferences
- \* Runtime startup behavior
- \* Access permissions for attended automation

According to the Pega Robotics System Design and Implementation Guide, section "Runtime Configuration Settings":

"The PegaRuntimeConfig.xml file defines user interaction settings and behavior of Pega Robot Runtime on end-user desktops.

It specifies configurations related to user access, tray icon visibility, notification pop-ups, and desktop automation permissions."

Detailed Reasoning:

- \* A. PegaConfig.xml - Not a valid configuration file in Pega Robotics.
- \* B. CommonConfig.xml - Used for shared system-wide connectivity and Robot Manager settings.
- \* C. PegaStudioConfig.xml - Stores configuration data for Pega Robot Studio (developer-specific).
- \* D. **PegaRuntimeConfig.xml** - Correct. Defines desktop-level user interaction and Runtime behavior.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Runtime Configuration File Overview section (Pega Robotics 19.1 and later).

### NEW QUESTION # 104

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