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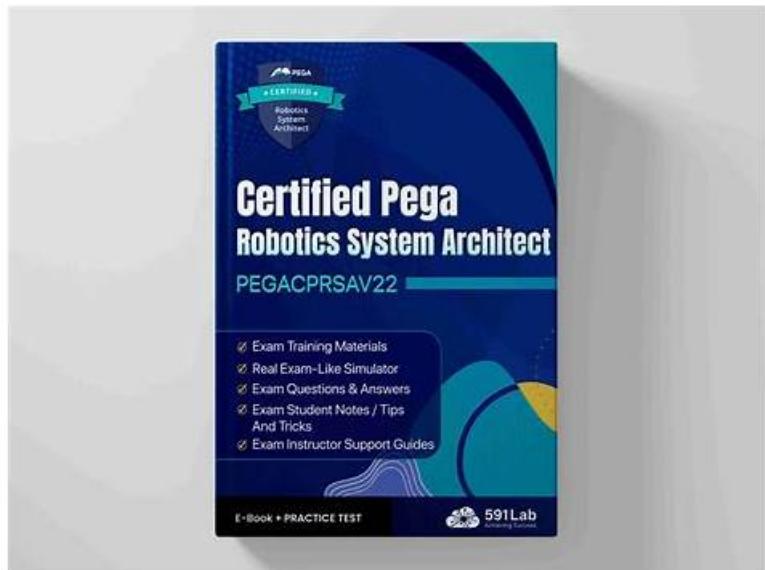
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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q90-Q95):

NEW QUESTION # 90
The project you are working on has two applications: BankerInsight and Pega Finance. You are working on the BankerInsight application method. Which three elements are not available to be used on the application method's design surface? (Choose Three)

- A. Automations that are not scoped within BankerInsight.
- B. Globals.
- C. BankerInsight controls.

- D. Pega Finance controls.
- E. External data sources.

Answer: A,B,D

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
"After adding the application method, Pega Robot Studio includes the application in the Palette. External elements are not available underneath the application, such as:
* Globals
* Other applications
* Automations that are not scoped within the application"
In other words: when you are working within an application method under a specific application (such as BankerInsight), you cannot include items from the global scope (Globals), you cannot include items from other applications (such as Pega Finance controls belong to a different application), nor can you include automations that are not scoped to the same application (automations outside BankerInsight).
Why each option is correct/incorrect:
* A. Automations that are not scoped within BankerInsight - Not available (Correct). According to the extract, "Automations that are not scoped within the application" are listed as external elements that cannot be used.
* B. BankerInsight controls - Available. Controls belonging to the same application are within scope, so you can use these.
* C. External data sources - The documentation snippet does not explicitly list "external data sources" as unavailable under the application method. So by the extract we cannot verify it as not available - thus we do not choose it.
* D. Pega Finance controls - Not available. These belong to a different application (Pega Finance), so they fall under "Other applications" which are external to the current application and so cannot be used.
* E. Globals - Not available. Explicitly listed in the documentation as external elements not available underneath the application.
If you like, I can check whether "External data sources" are allowed or not in that context and provide a more detailed explanation with additional reference pages.

NEW QUESTION # 91
You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.
Why are you unable to interrogate the desired application controls?

- A. The StartOnProject property of the application is set to false.
- B. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- C. The StartMethod on the application is set to Start, but the TargetPath property is undefined.
- D. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.

Answer: D

Explanation:
Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:
In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.
According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:
"The StartMethod property defines how Pega Robot Studio connects to or starts an application.
When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.
If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:
* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.
Option Analysis:

* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation.
Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.
Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration
- StartMethod and Path Property Requirements section (Pega Robotics
19.1 and later).

NEW QUESTION # 92
The Automation Playback window allows you to _____.

- A. open a log file and step through it as if you were running your solution in debug mode
- B. open a log file and debug any exceptions
- C. replay your last Runtime session where the applications are provided with the same account numbers automatically
- D. rerun the last automation that ran with the same values as inputs automatically entered

Answer: C

NEW QUESTION # 93
During project testing, an issue requires you to add a diagnostic log component to track the log files to help determine a resolution. After testing, you decide not to remove the diagnostic log component from the automation and decide to simply turn off the log component.
Which diagnostic log component setting allows you to turn the logging component off temporarily?

- A. Setting the Mode to Off
- B. Setting the Category to Off
- C. Setting Type to Off

Answer: A

Explanation:
Reference
http://help.openspan.com/80/Platform_Configuration/RuntimeConfigXML.htm

NEW QUESTION # 94
Unattended automations, when run. follow a basic process flow. Arrange the following steps in the order in which unattended automation topic processes a case.

Answer:

Explanation:
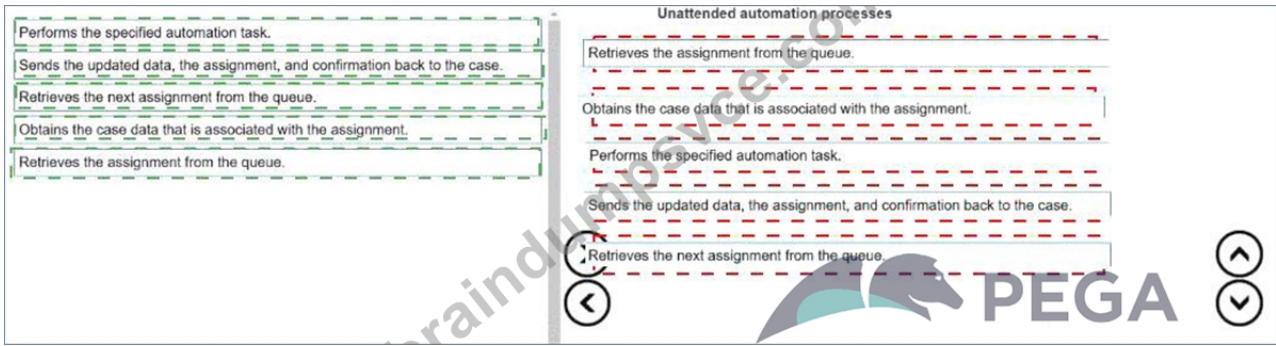
Explanation:

Retrieves the assignment from the queue.

Obtains the case data that is associated with the assignment.

Performs the specified automation task.

Sends the updated data, the assignment, and confirmation back to the case.

Retrieves the next assignment from the queue.

Unattended automations (also known as Robotic Process Automation (RPA)) are designed to work without human intervention. These automations process assignments or cases that are queued by Pega Platform and retrieved by robots through the Pega Robot Manager service.

According to the Pega Robotics System Design and Implementation Guide, in the section "Unattended Automation Workflow and Queue Processing", the following sequence defines how an unattended robot processes a work item:

"1. The robot retrieves an assignment from the work queue managed by Pega Robot Manager.

2. The robot then requests the case data associated with the assignment, which contains the necessary contextual information.

3. The robot performs the defined automation tasks within the target applications using the case data as input.

4. Upon completion, the robot updates the case, returns the assignment results, and confirms the completion to Pega Platform.

5. The robot then retrieves the next available assignment from the queue to continue processing." Detailed Step Reasoning:

* Retrieves the assignment from the queue - The robot begins by pulling a new assignment from the Pega Platform work queue through the Robot Manager interface.

* Obtains the case data that is associated with the assignment - After assignment retrieval, the robot obtains the case data (for example, customer details or transaction info) from the platform.

* Performs the specified automation task - The robot executes the defined automation using the fetched data, interacting with the necessary enterprise applications.

* Sends the updated data, the assignment, and confirmation back to the case - Once the task is complete, the robot posts the results and completion confirmation back to Pega Platform.

* Retrieves the next assignment from the queue - The cycle repeats as the robot moves to the next queued case or assignment.

This structured loop ensures consistent, unattended case handling by robotic workers, maintaining synchronization between Pega Platform and the robotic runtime environment.

Final Correct Order:

* Retrieves the assignment from the queue.

* Obtains the case data that is associated with the assignment.

* Performs the specified automation task.

* Sends the updated data, the assignment, and confirmation back to the case.

* Retrieves the next assignment from the queue.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Unattended Automations - Queue Processing and Workflow Lifecycle section (Pega Robotics 19.1 and later).

NEW QUESTION # 95

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