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# Nutanix Certified Professional - Multicloud Infrastructure (NCP-MCI) 7.5 Sample Questions (Q10-Q15):

**NEW QUESTION # 10**
Refer to Exhibit:



An administrator has been tasked with enabling LACP on an AHV cluster. In the exhibit, which option is the best to select for Bond Type when completing the task?

- A. Active-Active
- B. Active-Backup
- C. Active-Active with MAC Pinning
- D. No Uplink Bond

**Answer: A**

Explanation:
For AHV, when enabling LACP, Nutanix documentation specifies the Active-Active bond type, also described as balance-tcp. Nutanix explicitly ties LACP and link aggregation behavior to the Active-Active configuration and notes that this configuration sets LACP fallback to Active-Backup on AHV hosts. That makes C the correct bond type for an LACP-enabled design. ( Nutanix Portal ) It is also important to understand why Active-Active with MAC Pinning is wrong here. Nutanix documentation states that the MAC-pinning / balance-slb style must not be used with link aggregation protocols such as LACP. So even though both options sound like they distribute traffic, only one is compatible with LACP. Active-Backup provides redundancy, but not the LACP behavior being requested.
"No Uplink Bond" obviously does not meet the requirement. Even without the missing exhibit from the uploaded file, the Nutanix networking documentation makes the intended answer clear: Active-Active is the bond type used when enabling LACP on AHV. ( Nutanix Portal )

**NEW QUESTION # 11**
An administrator has noticed that a cluster consists of four Full-NVMe nodes. Which expansion path is supported?

- A. Two Mixed NVMe + HDD nodes with 60 TiB each
- B. One All NVMe node with 96 TiB RAW Capacity
- C. Two Mixed SSD + NVMe nodes with 60 TiB each
- D. One All SSD node with 96 TiB RAW Capacity

**Answer: B**

Explanation:
The uploaded answer key lists B, and that is the safest supported choice among the options because it preserves the cluster's all-NVMe storage profile rather than introducing mixed media tiers or an all-SSD design that changes the storage architecture. In Nutanix cluster expansion planning, keeping node media type aligned with the existing cluster profile is the normal supported design principle, especially when the existing cluster is already Full-NVMe. Nutanix storage documentation also emphasizes a single storage-pool-per- cluster model and consistent cluster design so that performance and capacity are optimized predictably across the

nodes.
The alternative answers introduce obvious design mismatches. Mixed NVMe+HDD or SSD+NVMe nodes would materially change latency and tier behavior, while adding an all-SSD node into a Full-NVMe cluster would also break architectural consistency. Although the exact public expansion-matrix wording was not surfaced in the search results, the answer set itself strongly points to the only media-aligned option: one All NVMe node with 96 TiB RAW capacity. So for an exam-prep answer aligned with Nutanix design logic and the provided key, B is the correct choice.

**NEW QUESTION # 12**
A company has recently purchased five new Nutanix clusters. The lab manager has been tasked with remotely deploying the Nutanix infrastructure in the most efficient way possible. Which tool would best help to accomplish this task?

- A. Standalone Foundation VM
- B. Foundation Central
- C. Phoenix ISO image
- D. Foundation for Windows/Mac

**Answer: B**

Explanation:
When the requirement is to deploy multiple remote clusters efficiently from a central point, Nutanix's intended tool is Foundation Central. Nutanix documentation describes Foundation Central as a way to manage several Foundation instances from a single pane of glass, allowing administrators to create clusters of remote nodes. That design matches the scenario perfectly: five newly purchased clusters, remote deployment, and a need for efficiency and centralized control. ( Nutanix Portal ) The other tools are more limited in scope. Foundation for Windows/Mac and a standalone Foundation VM are useful for imaging and cluster creation, but they do not provide the same centralized, multi-cluster orchestration model that Foundation Central provides. Phoenix ISO is a recovery or re-imaging tool and is not the normal answer for greenfield mass deployment. In short, this question is less about "which tool can build a cluster" and more about "which tool is purpose-built for remote, scaled deployment across many clusters." Nutanix positions Foundation Central exactly for that use case, so B is the best answer. ( Nutanix Portal )

**NEW QUESTION # 13**
The administrator observed the following NCC check in a cluster running VDI workloads:
ec_enablement_check:
Node XX.XX.XX.XX:
INFO: Consider enabling erasure coding on container SelfServiceContainer to get 26% space savings.
INFO: Consider enabling erasure coding on container default-container203943 to get 22% space savings.
What is the best course of action?

- A. Ignore the recommendation because this cluster does not have write once, ready many workloads.
- B. Enable erasure coding on both storage containers identified by this NCC check.
- C. Enable erasure coding on the SelfServiceContainer and leave it disabled on the default-container.
- D. Re-run the NCC check to ensure the recommendation is not intermittent.

**Answer: C**

Explanation:
Nutanix's NCC ec_enablement_check identifies containers where erasure coding could save space, but administrators still need to apply judgment based on workload behavior. In a VDI environment, user-created or self-service clone data may be a strong fit for EC, while the default container may host a wider mix of system, transient, or write-active workloads where capacity efficiency is not always the first priority. Since the recommendation is informational rather than mandatory, the best answer is to enable EC on the container that is the better fit and leave the more general default container unchanged. That makes D the most balanced answer.
This question is testing operational discretion. "Enable EC everywhere NCC mentions" is too simplistic.
Erasure coding is highly effective for suitable RF2/RF3 workloads, but the default container often ends up holding broad-purpose content that administrators may deliberately leave on non-EC settings depending on I
/O profile and design standards. The "SelfServiceContainer" is the more targeted candidate here, so D best reflects Nutanix-minded administration rather than blind automation.

**NEW QUESTION # 14**

The administrator noticed, in the past hour, a VM is showing:
CPU ready time > 5%
Memory swap rate > 0 Kbps
Host I/O Stargate CPU usage > 85%
What type of VM displays these characteristics?

- A. Constrained VM
- B. Inactive VM
- C. Bully VM
- D. Over-provisioned VM

**Answer: A**

Explanation:
Nutanix Intelligent Operations documentation for behavioral learning and VM right-sizing identifies several thresholds used to detect resource pressure, including CPU ready time > 5% and memory swap rate > 0 Kbps.
Those are direct indicators that the VM is experiencing contention rather than simply being oversized or idle.
A VM in that state is not comfortably provisioned; it is operating under resource pressure. Nutanix uses the term constrained VM for workloads that are lacking sufficient resources and therefore show signs of stress such as CPU wait, memory swapping, or storage-path pressure. That makes C the correct answer.
The high Host I/O Stargate CPU usage strengthens the case that this is an under-served or stressed workload rather than an inactive or over-provisioned one. An inactive VM would not show these pressure signals. An over-provisioned VM typically wastes allocated resources but does not struggle for them. A bully VM consumes disproportionate resources and affects others, but the threshold clues given in Nutanix right-sizing guidance map more directly to a VM that is constrained. Therefore the most accurate category for these observed characteristics is C. Constrained VM.

**NEW QUESTION # 15**
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