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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q46-Q51):

NEW QUESTION # 46

The following Context variables are defined in the Interaction.xml of the solution.

- An automation creates an interaction and later sets the following values for Procedures and HasBeenPaid.
- When the agent finishes the call, an automation clears the context variables using ClearContext.
- What is the state of the HasBeenPaid variable at this point?

- A. The value of HasBeenPaid is now False.
- B. The value of HasBeenPaid is now null.
- C. The value of HasBeenPaid is now True.

Answer: A

NEW QUESTION # 47

You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.

Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.
- B. The StartOnProject property of the application is set to false.
- C. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- D. The StartMethod on the application is set to Start, but the TargetPath property is undefined.

Answer: A

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.

According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:

"The StartMethod property defines how Pega Robot Studio connects to or starts an application.

When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.

If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:

* The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.

* For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).

* If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.

* As a result, the bullseye tool will not function because no valid application handle is established for interrogation.

Option Analysis:

* A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.

* B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.

* C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.

* D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation. Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration

- StartMethod and Path Property Requirements section (Pega Robotics 19.1 and later).

NEW QUESTION # 48

You are designing an attended project for a banking customer. This project requires you to add new customers from an application to a combo box in a custom user surface.

Which steps do you take to gain access to the methods of the combo box items within an automation?

- A. Select the combo box in a design form of the user interface to open the Select action window.
- B. Select the combo box in the Palette tab of an automation, and then filter for the method that you want to access in the properties grid.
- **C. Drag the combo box to the automation surface to open the Select action dialog box, and then filter for the method that you want to access.**
- D. Open the Globals tab, filter for the method that you want to access, and then drag the method to the design surface.

Answer: C

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

When working with UI controls such as combo boxes in a custom user interface (Windows form or User Interaction form), you can expose their methods and events by dragging the control from the Palette or Object Explorer to the automation design surface.

According to the Pega Robotics System Design and Implementation Guide, section "Accessing Control Methods and Properties in Automations":

"To access a control's methods or events in an automation, drag the control (such as a combo box or text box) from the Object Explorer or Palette to the automation surface.

The Select Action dialog box appears, allowing you to filter and choose the specific method or event (for example, AddItem, RemoveItem, or Clear)." Detailed Reasoning:

- * A. Drag the combo box to the automation surface... - Correct. This opens the Select Action dialog, exposing all available methods and events for that control.
- * B. Open the Globals tab... - Incorrect. The combo box methods are not global; they belong to a specific UI form.
- * C. Select the combo box in a design form... - Incorrect. This action edits UI layout, not automation logic.
- * D. Select the combo box in the Palette tab... - Incorrect. The properties grid shows attributes, not callable methods.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Using Control Methods and Events in Automations section (Pega Robotics 19.1 and later).

NEW QUESTION # 49

The business requirement states the solution should update and save the address to all applicable applications in the solution. The interaction configuration file is already configured with the SaveAddress activity. You are now ready to add an Activity component to a project using standard naming conventions.

Which option meets the requirement for configuring the Activity component?

□

- A. Exhibit D
- B. Exhibit B
- **C. Exhibit A**
- D. Exhibit C

Answer: C

NEW QUESTION # 50

The business requirements states that the login automation creates a Success or Failed response when attempting to log in to the finance application. If a failure occurs, the automation should pass a message code with the Message Manifest before exiting the automation.

Which image represents the exit logic?

□

- A. Exhibit D
- B. Exhibit B

- C. Exhibit C
- D. Exhibit A

Answer: C

NEW QUESTION # 51

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