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Exam : **JN0-452**

Title : Juniper Mist AI Wireless,
Specialist
(JNCIS-MistAI-Wireless)

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Juniper Mist AI Wireless, Specialist (JNCIS-MistAI-Wireless) Sample Questions (Q56-Q61):

NEW QUESTION # 56

A retail company is planning to deploy asset tags to track shopping carts. The goal is to get real-time location data with zonal accuracy (3-5 meters).

Which two Mist technologies are primarily used to determine the location of these BLE asset tags? (Choose 2.)

- A. The vBLE antenna array in the APs to determine the direction of the tag's signal.
- B. The client's mobile SDK, which must be installed on the asset tag.
- C. The MAC address of the asset tag.
- D. The GPS coordinates transmitted by the asset tag.
- E. The Received Signal Strength Indicator (RSSI) of the tag's signal as heard by multiple APs.

Answer: A,E

NEW QUESTION # 57

A network administrator is troubleshooting a connectivity issue where a client device can associate with an AP but fails the 802.1X authentication process. The administrator initiates a packet capture on the Mist dashboard.

The capture file shows EAP-Request/Identity frames from the AP and EAP-Response/Identity frames from the client, but it is followed by an EAP-Failure message from the AP.

What is the most likely cause of this failure?

- A. The DHCP server is not responding.
- B. The client is using an incorrect pre-shared key.
- C. The RADIUS server is actively rejecting the client's identity (username).
- D. The AP's Ethernet port has a duplex mismatch with the switch.

Answer: C

NEW QUESTION # 58

Which Juniper AP is used to augment BLE coverage?

- A. AP242
- B. AP343
- C. AP12
- D. BT111

Answer: D

Explanation:

In the Juniper Mist AI product portfolio, the BT11 is a specialized, enterprise-grade access point designed exclusively for Bluetooth Low Energy (BLE).⁴ Unlike the other access points in the Juniper Mist family (such as the AP12, AP24, and AP34), the BT11 does not contain Wi-Fi radios.⁵ Its sole purpose is to provide high-accuracy, enterprise-grade location-based services (LBS) by leveraging Juniper's patented 16-element virtual BLE (vBLE) antenna array.⁶ The primary use case for the BT11 is to augment BLE coverage in environments where Wi-Fi connectivity is already established by other APs, but the density of those APs is insufficient for precise location services.

For applications like turn-by-turn wayfinding or asset tracking, the RF requirements for BLE are often more stringent than those for Wi-Fi. A facility might have enough Wi-Fi APs to provide data coverage, but may have "location holes" where the BLE signals are too sparse for 1-3 meter accuracy. By deploying BT11 units in these gaps, administrators can extend the reach of the location engine without the expense of adding full-featured Wi-Fi radios where additional capacity is not needed.⁷ The BT11 communicates directly with the Mist Cloud to manage virtual beacons, which eliminate the need for physical, battery-powered beacons and manual calibration.⁸ Because it runs on Power over Ethernet (PoE) and integrates seamlessly with the Mist AI engine, it provides a scalable

and cost-effective way to ensure continuous, high-fidelity BLE coverage across a campus, hospital, or retail floor.

NEW QUESTION # 59

Regarding roaming, which device determines when it is time to connect to another AP?

- A. the gateway router
- B. the current AP
- C. the primary AP
- **D. the client device**

Answer: D

Explanation:

According to the Cisco Catalyst 9800 Series Wireless Controller Software Configuration Guide¹, roaming is the process of moving a wireless client device from one AP to another while maintaining network connectivity. The client device determines when it is time to connect to another AP based on its own roaming algorithm and criteria.

References: https://www.cisco.com/c/en/us/td/docs/wireless/controller/9800/17-2/config-guide/b_wl_17_2_cg/roaming.html

NEW QUESTION # 60

Which real-time location system component takes the coordinates of a tracked device and applies a location-aware triggered action to a client?

- A. location sensor
- B. Juniper Mist Edge
- C. Marvis Minis
- **D. location system**

Answer: D

Explanation:

In the architecture of a Mist AI Real-Time Location System (RTLS), the process of moving from raw signal data to an actionable event involves several distinct layers. To understand why the location system is the correct answer, we must examine how Mist processes Location-Based Services (LBS).

The workflow begins with location sensors (typically Mist Access Points). These sensors collect raw Bluetooth Low Energy (BLE) or Wi-Fi signals (RSS measurements) from tracked assets or mobile devices.

These raw data points are then transmitted to the cloud-based Mist AI engine. The location system (often referred to as the Location Engine within the Mist Cloud) is the specific functional component responsible for calculating the precise X/Y coordinates of the device using machine learning and trilateration algorithms.

However, its role does not end at mere coordinate calculation. The Mist location system is designed to be "context-aware." Once the coordinates are established, the system maps these coordinates against defined zones, virtual beacons (vBeacons), or geofences configured in the Mist dashboard. When a device's coordinates intersect with a predefined boundary, the location system triggers a location-aware action. This could include sending a webhook to a third-party application, pushing a proximity notification to a mobile SDK client, or recording a "visit" in the analytics engine.

While Juniper Mist Edge handles data plane tunneling and Marvis Minis acts as a digital twin for network simulation, they do not manage the coordinate-to-action logic. The location system is the intelligence that bridges the gap between spatial data and business logic, ensuring that the right client receives the right trigger based on their physical presence within a venue.

NEW QUESTION # 61

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