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Quiz Unparalleled NVIDIA - NCP-AII Valid Exam Objectives

The NVIDIA NCP-AII desktop practice exam software is customizable and suits the learning needs of candidates. A free demo of the NVIDIA AI Infrastructure (NCP-AII) desktop software is available for sampling purposes. You can change NCP-AII Practice Exam's conditions such as duration and the number of questions. This simulator creates a NVIDIA NCP-AII real exam environment that helps you to get familiar with the original test.

NVIDIA AI Infrastructure Sample Questions (Q278-Q283):

NEW QUESTION # 278

You encounter an error during the BlueField OS flashing process using 'bfboot: 'ERROR: Could not detect a BlueField device'. Which of the following steps is MOST likely to resolve the issue?

- A. Check the systems BIOS/UEFI to confirm that SR-IOV is enabled.
- B. Verify that the correct PCIe slot is being used. Some systems may have specific slots designated for SmartNICs.
- C. Install the Mellanox OFED drivers on the host system. These drivers are required for 'bfboot' to function correctly.
- D. **Ensure the BlueField device is powered on and properly connected to the host system via PCIe.**
- E. Update the 'bfboot' utility to the latest version. Older versions may have compatibility issues.

Answer: D

Explanation:

The most basic and common cause of this error is a physical connection issue. Ensuring the device is powered and connected is the first step. While other options might be relevant in specific scenarios, connectivity is the most probable cause.

NEW QUESTION # 279

You've flashed the BlueField OS to your SmartNIC, but you need to customize the kernel command line arguments (bootargs) to enable a specific feature. Where is the MOST appropriate place to modify these arguments for persistent changes that survive reboots?

- A. Passing it as an argument to bfboot during deployment.
- B. In the bootloader configuration file (e.g., extlinux.conf or grub.cfg) on the BlueField's flash memory.
- C. In the '/proc/cmdline' file. This allows immediate changes.
- D. Directly in the kernel image file itself using a hex editor.
- E. In the '/etc/default/grub' file on the BlueField OS, followed by updating the GRUB configuration.

Answer: B

Explanation:

The bootloader configuration file (extlinux.conf, grub.cfg, uEnv.txt depending on the system) is where boot arguments are persistently stored. Modifying the kernel image directly is highly discouraged and risky. '/etc/default/grub' is a common location on standard Linux systems, but not necessarily on the BlueField OS's boot environment. '/proc/cmdline' shows the currently used arguments, but modifying it doesn't persist changes across reboots. bfboot will only change the image during that flash, changes at the bootloader level persist after subsequent flashes.

NEW QUESTION # 280

Which of the following statements are correct regarding the use of NVIDIA GPUs with Docker containers?

- A. CUDA libraries are required inside the container if your application uses CODA.
- B. The 'nvidia-smi' command can only be run on the host machine, not inside a Docker container.
- C. The NVIDIA Container Toolkit allows you to run GPU-accelerated applications in Docker containers without modifying the container image.
- D. Using environment variables like 'CUDA VISIBLE DEVICES' within the container can influence which GPUs are accessible to the application.
- E. You must install NVIDIA drivers inside the Docker container to enable GPU support.

Answer: A,C,D

Explanation:

The NVIDIA Container Toolkit allows GPU-accelerated apps to run in Docker without altering the image. The host's drivers are leveraged. CUDA libraries are necessary inside the container if your app uses CUDA. is used to control GPU visibility within the container. Drivers are not needed inside the container because they're managed by the host (making B incorrect), and 'nvidia-smi' can be run inside containers if the NVIDIA Container Toolkit is properly set up (making C incorrect).

NEW QUESTION # 281

A user reports that their deep learning training job is crashing with a 'CUDA out of memory' error, even though 'nvidia-smi' shows plenty of free memory on the GPU. The job uses TensorFlow. What are the TWO most likely causes?

- A. TensorFlow is allocating memory on the CPU instead of the GPU.
- B. The system's swap space is full, preventing memory from being allocated.
- C. The CUDA VISIBLE DEVICES environment variable is not set correctly.
- D. TensorFlow is fragmenting GPU memory, making it difficult to allocate contiguous blocks.
- E. The TensorFlow version is incompatible with the installed NVIDIA driver.

Answer: C,D

Explanation:

'CUDA out of memory' errors, despite seemingly available GPU memory, often indicate memory fragmentation or improper GPU assignment. TensorFlow can fragment GPU memory, leading to allocation failures even if sufficient total memory is available. The

variable controls which GPUs TensorFlow can access. If it's not set or is set incorrectly, TensorFlow might be trying to allocate memory on a non-existent or unavailable GPU. While TensorFlow version incompatibilities can cause issues, they are less likely to directly manifest as 'CUDA out of memory' errors. TensorFlow typically prioritizes GPU memory allocation if configured correctly.

NEW QUESTION # 282

You are evaluating different parallel file systems for an AI training cluster. You need a file system that supports POSIX compliance and offers high bandwidth and low latency. Which of the following options are viable candidates?

- A. Ceph
- B. BeeGFS
- C. Lustre
- D. GlusterFS
- E. NFS

Answer: B,C

Explanation:

BeeGFS and Lustre are designed for high-performance computing and AI workloads, offering high bandwidth, low latency, and POSIX compliance. GlusterFS and Ceph are more general-purpose distributed file systems. NFS is generally not suitable for demanding AI workloads due to its performance limitations.

NEW QUESTION # 283

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