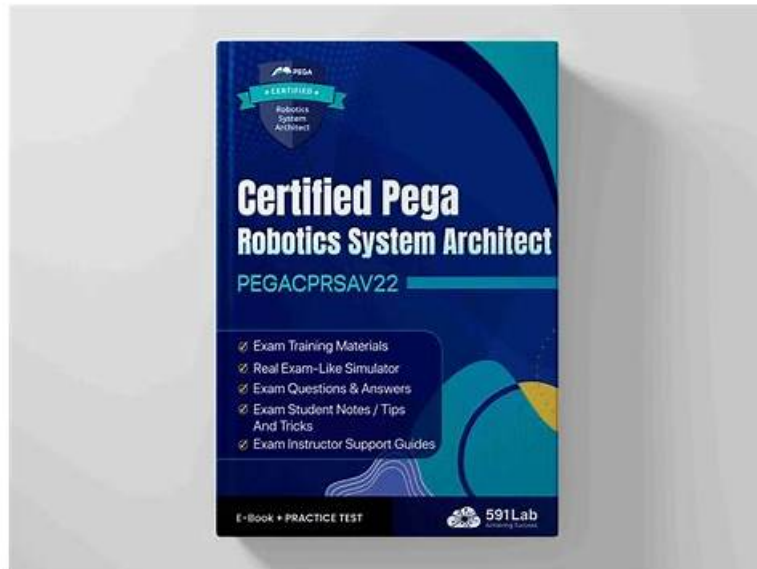


PEGACPRSA22V1 Schulungsangebot, PEGACPRSA22V1 Testing Engine, Certified Pega Robotics System Architect 22 Trainingsunterlagen



Fast2test ist eine Website, die den IT-Kandidaten die Schulungsunterlagen, die ganz speziell sind und den Kandidaten somit viel Zeit und Energie ersparen können, bietet. Unsere Prüfungsfragen und Antworten zur Pegasystems PEGACPRSA22V1 Zertifizierung sind den realen Themen sehr ähnlich. Mit Hilfe von den Simulationsprüfung von Fast2test können Sie ganz schnell die Pegasystems PEGACPRSA22V1 Prüfung 100% bestehen. Es ist doch wert, mit so wenig Zeit und Geld gute Resultate zu bekommen. Schicken Sie doch schnell die Schulungsunterlagen zur Pegasystems PEGACPRSA22V1 Prüfung von Fast2test in den Warenkorb.

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Fast2test ist eine Website, die den Traum vielen IT-Fachleuten erfüllen kann. Wenn Sie einen IT-Traum haben, dann wählen Sie doch Fast2test. Die Fragenkataloge zur Pegasystems PEGACPRSA22V1 Zertifizierungsprüfung von Fast2test sind von vielen IT-Fachleuten begehrt, die Ihnen helfen, die PEGACPRSA22V1 Zertifizierung zu bestehen und im Berufsleben befördert zu werden.

Um sich auf die PegaCPRSA22V1 -Zertifizierungsprüfung vorzubereiten, können Kandidaten eine Reihe von Ressourcen nutzen, einschließlich Online -Schulungskursen, Praxisprüfungen und Studienführer. Diese Ressourcen sollen Kandidaten helfen, ein tiefes Verständnis der Pega -Robotik -Plattform und ihrer Fähigkeiten zu entwickeln und ihnen das Wissen und die Fähigkeiten zu vermitteln, die für die Bestimmung der Prüfung erforderlich sind. Darüber hinaus können Kandidaten die Community -Foren und die Wissensbasis von Pega nutzen, um sich mit anderen Pega -Robotik -Fachleuten zu verbinden und Fragen zu stellen und Wissen auszutauschen.

Pegasystems Certified Pega Robotics System Architect 22 PEGACPRSA22V1 Prüfungsfragen mit Lösungen (Q65-Q70):

65. Frage

When performing application discovery, it is important that you _____ and _____ . (Choose two.)

- A. interrogate 100 percent of the controls in the application
- **B. write automations to accomplish the basic search functionality of the application**
- C. interrogate all controls required for the use case
- **D. utilize test methods to validate that you can interact with representatives of the controls in the use case**

Antwort: B,D

66. Frage

During application discovery, what three things must the developer notice about the application to help design the automation? (Choose three.)

- **A. How the application responds during use**
- B. How the automation responds to the process
- **C. How users interact with the applications**
- **D. How the application processes data**
- E. How the adapter process data

Antwort: A,C,D

Begründung:

Application discovery is an early technical validation step that involves collecting the information about applications in scope of a potential robotics use case. During discovery you need to find out application types (and if they are on applications support matrix for Pega Robotics), how they are launched, how they are used, and check accessibility and functionality of the controls through interrogation. Application discovery is necessary to ensure that robotics use case is viable and it doesn't have any technical constraints... or, if constraints exist, then what kind of workarounds will be necessary to ensure the use case is successful. The rationale for having application discovery as a best practice is that you don't want to find out half-way through coding an automation that a key control is not available or not performing the desired action.

67. Frage

You interrogated a web application. All controls and objects matched, and the automations worked as coded. During the pilot, the solution failed on the web application. The IT department had released a new version of the web application. Upon review of the new version, you determined that the web page hierarchy changed. Which interrogation option do you use to correct the solution?

- A. Default
- B. Debug Matching
- **C. Replace Control**
- D. Select Element

Antwort: C

Begründung:

References:

68. Frage

You are designing an attended project for a banking customer. This project requires you to import new customers from a text file to a lookup table.

Which steps do you take to gain access to the ImportDelimitedFile method of the lookup table within an automation?

- **A. Drag the lookup table from the Globals section of the Palette to the automation surface to open the Select action window, and then filter for the ImportDelimitedFile method.**
- B. Open the Globals tab, filter for the ImportDelimitedFile method, and then drag it to the design surface.
- C. Select the ImportDelimitedFile method in a design form of the user interface to open the Select action window.
- D. Drag the lookup table from the Locals section of the Palette to the automation surface to open the Select action window, and then filter for the ImportDelimitedFile method.

Antwort: A

Begründung:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The Lookup Table is a global component in Pega Robot Studio that can be accessed from multiple automations within a project. To use its methods-such as ImportDelimitedFile, FindRecord, or AddRecord-you must drag the lookup table instance from the Globals section to the automation surface.

According to the Pega Robotics System Design and Implementation Guide, section "Using Lookup Tables in Automations":

"Lookup tables are global components that store data used across automations.

To call lookup table methods, drag the table from the Globals section of the Palette to the automation design surface.

The Select Action dialog box will open, allowing you to filter and select from available methods such as ImportDelimitedFile, FindRecord, and ClearTable." Detailed Reasoning:

- * A. Select the ImportDelimitedFile method in a design form... - Incorrect. The lookup table is not part of the UI form.
- * B. Drag the lookup table from the Locals section... - Incorrect. Lookup tables exist under Globals, not Locals.
- * C. Open the Globals tab and filter... - Incorrect. You must drag the component onto the automation surface to expose its methods.
- * D. Drag the lookup table from the Globals section... - Correct. This exposes the ImportDelimitedFile method through the Select Action dialog.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Lookup Tables and Global Data Components section (Pega Robotics 19.1 and later).

69. Frage

You are assigned to develop a set of activities by using a popular HR application. The application loads automatically after you start interrogation from Pega Robot Studio, but you notice that you are unable to use the bullseye on the Robot Studio Interrogation Form to drag and drop over the desired controls.

Why are you unable to interrogate the desired application controls?

- A. The StartMethod on the application is set to StartAndWait, but the TargetPath property is undefined.
- **B. The StartMethod on the application is set to MonitorAll, but the Path property is undefined.**
- C. The StartOnProject property of the application is set to false.
- D. The StartMethod on the application is set to Start, but the TargetPath property is undefined.

Antwort: B

Begründung:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

In Pega Robot Studio, the StartMethod and Path properties determine how an adapter attaches to or launches a target application. When interrogating applications, these configurations must be correctly defined for Robot Studio to recognize and interact with the application's user interface elements.

According to the Pega Robotics System Design and Implementation Guide, in the section "Application Adapter Properties and Interrogation Settings", it states:

"The StartMethod property defines how Pega Robot Studio connects to or starts an application.

When using the 'MonitorAll' method, Robot Studio does not start the application automatically; instead, it waits for an existing instance of the application to be detected at runtime.

If the 'Path' property is undefined when using MonitorAll, the adapter has no reference to locate or attach to the running process, preventing interrogation of controls." Detailed Reasoning:

- * The MonitorAll StartMethod is typically used to attach to an already running application rather than launching a new instance.
- * For this to function correctly, Robot Studio needs to know which process to monitor, and that is determined by the Path property (the executable location of the target application).
- * If the Path property is missing or left undefined, Robot Studio cannot identify which process to monitor, even though the application may appear to launch.
- * As a result, the bullseye tool will not function because no valid application handle is established for interrogation.

Option Analysis:

- * A. Incorrect - StartAndWait requires both the executable and window parameters, but the symptom here points specifically to an undefined Path under MonitorAll.
- * B. Incorrect - StartOnProject determines whether the app launches with the project, not whether it can be interrogated.
- * C. Incorrect - Start with undefined TargetPath would prevent the app from launching, but the question states the app does load.
- * D. Correct - Using MonitorAll without a defined Path prevents Robot Studio from attaching to the process, disabling interrogation. Therefore, the correct answer is D - the StartMethod on the application is set to MonitorAll, but the Path property is undefined.

Reference:Extracted and verified from Pega Robotics System Design and Implementation Guide, Application Adapter Configuration

- StartMethod and Path Property Requirements section (Pega Robotics 19.1 and later).

70. Frage

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