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## Questions & Answers



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## NVIDIA Generative AI Multimodal Sample Questions (Q271-Q276):

### NEW QUESTION # 271

Which of the following are potential benefits of using multi-modal learning compared to single-modal learning? (Select all that apply)

- A. Reduced risk of overfitting to spurious correlations in a single modality.
- B. Guaranteed higher accuracy across all tasks.
- C. Increased computational complexity and data requirements.
- D. The ability to learn more comprehensive and nuanced representations.
- E. Improved robustness to noisy or incomplete data.

**Answer: A,D,E**

Explanation:

Multi-modal learning leverages the complementary information from different modalities to enhance performance. (A) It improves robustness because if one modality is noisy or missing, the others can still provide useful information. (B) It learns more comprehensive representations by integrating information across modalities. (D) It reduces overfitting by leveraging information from multiple sources. (C) is correct but not a benefit. (E) is incorrect as higher accuracy is not guaranteed, depending on data and task.

### NEW QUESTION # 272

Consider a scenario where you are developing a multimodal model for medical diagnosis using patient medical history (text), X-ray images, and ECG data (time-series). A significant portion of the ECG data is missing due to sensor malfunction. Which of the following approaches would be MOST effective in handling the missing data and ensuring accurate diagnosis?

- A. Employ a multimodal fusion technique that is robust to missing modalities, such as attention mechanisms that dynamically weight the available data sources.
- B. Combine imputation of missing ECG data with a robust multimodal fusion technique.
- C. Impute the missing ECG values using time-series imputation techniques (e.g., Kalman filtering or interpolation).
- D. Replace the missing ECG data with the average values from the entire dataset.
- E. Train a separate model using only the available medical history and X-ray images, ignoring the ECG data altogether.

**Answer: B**

Explanation:

Combining imputation with robust fusion is optimal. Imputation recovers some information from the missing data, while robust fusion ensures the model can still make accurate predictions even if the imputed data is not perfect. Ignoring the ECG data or simply replacing it with average values would likely lead to inaccurate diagnoses.

### NEW QUESTION # 273

Which prompt engineering technique is most likely to improve the coherence and visual quality of images generated by a text-to-image model when generating complex scenes with multiple objects and intricate details?

- A. Using only abstract and ambiguous language.
- B. Employing a negative prompt to specify elements to avoid.
- C. Using short, concise prompts with only a few keywords.
- D. Exclusively describing the background and neglecting foreground elements.
- E. Relying solely on the model's default style settings.

**Answer: B**

Explanation:

Employing a negative prompt allows you to explicitly instruct the model to avoid specific elements or artifacts that might degrade the visual quality of the generated image. This technique is particularly effective for complex scenes where you want to fine-tune the composition and appearance by preventing unwanted details or styles. Using shorter prompts or relying only on default styles is too general. Vague descriptions can lead to unpredictable outputs.

### NEW QUESTION # 274

You're building a multimodal model to generate captions for videos. You've noticed that your model struggles to capture temporal relationships and sequential dependencies in the video frames. Which of the following architectures or techniques would be BEST suited to address this?

- A. A 3D Convolutional Neural Network (3D CNN) that processes multiple frames as a volume.
- B. A standard Convolutional Neural Network (CNN) applied independently to each frame.
- C. A Multilayer Perceptron (MLP) trained on flattened video frames.
- **D. A combination of a CNN to extract features from individual frames, followed by a Recurrent Neural Network (RNN) like LSTM or GRU to model temporal dependencies between the extracted features.**
- E. Principal Component Analysis (PCA) to reduce dimensionality of each frame before feeding to the decoder

**Answer: D**

Explanation:

RNNs, specifically LSTMs and GRUs, are designed to handle sequential data and capture temporal relationships. Combining a CNN for feature extraction with an RNN allows the model to process individual frames and then model the dependencies between them. 3D CNNs can also capture temporal information, but can be computationally expensive. Other options don't explicitly address the temporal aspect.

### NEW QUESTION # 275

You are tasked with integrating a CLIP model into your application to generate images based on text descriptions. You want to ensure that the generated images closely reflect the nuances of the text prompt. Which prompt engineering technique is MOST suitable for achieving this?

- **A. Using negative prompts to explicitly exclude unwanted features or styles.**
- B. Using overly verbose and descriptive prompts to maximize detail.
- C. Using random prompts to explore the model's creative capabilities.
- D. Using prompts consisting only of keywords related to the desired image.
- E. Using short, concise prompts to minimize ambiguity.

**Answer: A**

Explanation:

Negative prompting is a powerful technique where you specify what you don't want in the generated image. This helps refine the output and steer the model away from undesirable artifacts or styles. For example, specifying "a futuristic city, but without flying cars".

### NEW QUESTION # 276

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