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NVIDIA Generative AI Multimodal Sample Questions (Q115-Q120):

NEW QUESTION #115

Which of the following NVIDIA tools or SDKs can MOST effectively be utilized to profile and optimize the performance of a computationally intensive multimodal generative A1 model running on NVIDIA GPUs? (Select TWO)

- A. NVIDIA Nsight Systems for system-wide performance analysis.
- B. NVIDIA Omniverse for collaborative 3D workflows.
- C. NVIDIA Merlin for recommender systems.
- D. TensorRT for high-performance inference.
- E. CIJDA Toolkit for memory management.

Answer: A,D

Explanation:

Nsight Systems provides detailed system-wide performance analysis, allowing you to identify bottlenecks and optimize resource

utilization. TensorRT is a high-performance inference SDK that can significantly speed up model execution. While the CUDA Toolkit is essential for GPU programming, Nsight Systems is better for profiling. Omniverse and Merlin are relevant to other domains, not general performance optimization. Memory management is important, but Nsight provides profiling for this, better answering the question.

NEW QUESTION #116

You are working on a generative A1 model that creates descriptions of images. During experimentation, you notice the model consistently generates descriptions that are factually incorrect about objects in the image, despite the image quality being high. For example, it might describe a 'cat' as a 'dog'. What is the MOST critical step to address this issue?

- A. Apply image sharpening filters to the input images.
- B. Fine-tune the model using a smaller learning rate.
- C. Use a more complex model architecture.
- D. Implement a mechanism to verify the generated descriptions against an external knowledge base or object recognition system.
- E. Increase the training data size with more diverse images.

Answer: D

Explanation:

Factually incorrect descriptions indicate a lack of grounding in real-world knowledge. Verifying against an external knowledge base (B) directly addresses this issue. Increasing data size (A) might help, but it's not guaranteed. Fine-tuning (C) and increasing model complexity (D) might not solve the grounding problem. Image sharpening (E) is irrelevant to factual accuracy.

NEW QUESTION #117

Explain the role of Tensor Cores and mixed-precision training (e.g., using FP16 or bfloat16) in accelerating the training of large generative AI models.

- A. Tensor Cores are only useful for inference, not training.
- B. Tensor Cores perform specialized matrix multiplications optimized for lower-precision data types, enabling faster computation and reduced memory footprint.
- C. Mixed-precision training guarantees the same convergence behavior as full-precision training.
- D. Mixed-precision training allows using lower precision for forward and backward passes but keeps weights and gradients in higher precision to maintain stability.
- E. A and B.

Answer: E

Explanation:

Tensor Cores are designed to accelerate matrix multiplication, the core operation in deep learning, using lower precision data types. Mixed-precision training leverages this by using lower precision for the bulk of the computation, while maintaining higher precision for critical variables to avoid instability. Tensor Cores are used both for training and inference.

NEW QUESTION #118

You are building a multimodal application that takes an image and a short text description as input and generates a more detailed text description of the image. Which of the following model architectures is BEST suited for this task?

- A. A Generative Adversarial Network (GAN) with separate image and text encoders.
- B. A simple CNN followed by an LSTM.
- C. A Multilayer Perceptron (MLP) for both image and text.
- D. A Vision Transformer (ViT) for image encoding and a Transformer for text decoding.
- E. A Recurrent Neural Network (RNN) with attention mechanisms.

Answer: D

Explanation:

A Vision Transformer (ViT) excels at encoding image information, and a Transformer architecture is highly effective for text generation. The combination allows for effective processing of both modalities and generation of coherent, detailed text descriptions

based on the image content and initial text prompt. CNN+LSTM could work, but is generally less performant. RNNs struggle with long-range dependencies. GANs are not ideal for this specific text generation task. MLPs don't capture the sequential dependencies well.

NEW QUESTION #119

You're designing a multimodal A1 system for autonomous driving that integrates data from cameras (images), LiDAR (point clouds), radar (time-series), and GPS (geospatial). The system needs to make real-time decisions in complex urban environments. Which hardware and software components are crucial for achieving low latency and high accuracy in data processing and fusion?

- A. Sensor fusion algorithms optimized for GPU acceleration.
- B. All of the above.
- C. NVIDIA GPUs with CUDA for accelerated processing of image and point cloud data.
- D. High-bandwidth, low-latency communication interfaces (e.g., PCle Gen4/5) for data transfer between sensors and processing units.
- E. Real-time operating system (RTOS) for deterministic execution and minimal jitter.

Answer: B

Explanation:

All the options are critical for real-time performance. GPUs accelerate processing, high-bandwidth interfaces enable fast data transfer, RTOS ensures deterministic execution, and optimized sensor fusion algorithms maximize accuracy.

NEW QUESTION #120

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