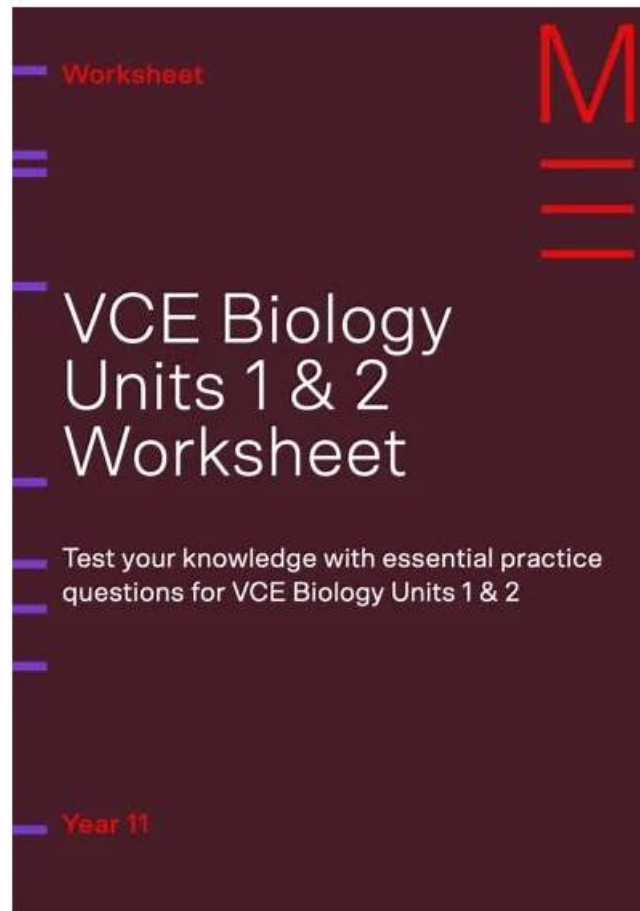


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Pegasystems Certified Pega Robotics System Architect 22 Sample Questions (Q70-Q75):

NEW QUESTION # 70

Unattended automations, when run, follow a basic process flow. Arrange the following steps in the order in which unattended automation topic processes a case.

The screenshot shows a drag-and-drop interface for arranging steps in a process flow. The steps are listed in a box on the left, and the right side shows the sequence of steps as they are arranged. The steps are:

- Performs the specified automation task.
- Sends the updated data, the assignment, and confirmation back to the case.
- Retrieves the next assignment from the queue.
- Obtains the case data that is associated with the assignment.
- Retrieves the assignment from the queue.

The Pega logo is visible at the bottom left, and navigation buttons (back, forward, up, down) are on the right.

Answer:

Explanation:

The screenshot shows the same drag-and-drop interface as the previous one, but with the steps arranged in the correct sequence. The steps are:

- Retrieves the assignment from the queue.
- Obtains the case data that is associated with the assignment.
- Performs the specified automation task.
- Sends the updated data, the assignment, and confirmation back to the case.
- Retrieves the next assignment from the queue.

The Pega logo is visible at the bottom left, and navigation buttons (back, forward, up, down) are on the right.

Explanation:

Retrieves the assignment from the queue.

Obtains the case data that is associated with the assignment.

Performs the specified automation task.

Sends the updated data, the assignment, and confirmation back to the case.

Retrieves the next assignment from the queue.

Unattended automations (also known as Robotic Process Automation (RPA)) are designed to work without human intervention.

These automations process assignments or cases that are queued by Pega Platform and retrieved by robots through the Pega Robot Manager service.

According to the Pega Robotics System Design and Implementation Guide, in the section "Unattended Automation Workflow and Queue Processing", the following sequence defines how an unattended robot processes a work item:

"1. The robot retrieves an assignment from the work queue managed by Pega Robot Manager.

2. The robot then requests the case data associated with the assignment, which contains the necessary contextual information.

3. The robot performs the defined automation tasks within the target applications using the case data as input.

4. Upon completion, the robot updates the case, returns the assignment results, and confirms the completion to Pega Platform.

5. The robot then retrieves the next available assignment from the queue to continue processing." Detailed Step Reasoning:

* Retrieves the assignment from the queue - The robot begins by pulling a new assignment from the Pega Platform work queue through the Robot Manager interface.

* Obtains the case data that is associated with the assignment - After assignment retrieval, the robot obtains the case data (for example, customer details or transaction info) from the platform.

* Performs the specified automation task - The robot executes the defined automation using the fetched data, interacting with the necessary enterprise applications.

* Sends the updated data, the assignment, and confirmation back to the case - Once the task is complete, the robot posts the results and completion confirmation back to Pega Platform.

* Retrieves the next assignment from the queue - The cycle repeats as the robot moves to the next queued case or assignment.

This structured loop ensures consistent, unattended case handling by robotic workers, maintaining synchronization between Pega Platform and the robotic runtime environment.

Final Correct Order:

- * Retrieves the assignment from the queue.
- * Obtains the case data that is associated with the assignment.
- * Performs the specified automation task.
- * Sends the updated data, the assignment, and confirmation back to the case.
- * Retrieves the next assignment from the queue.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Unattended Automations - Queue Processing and Workflow Lifecycle section (Pega Robotics 19.1 and later).

NEW QUESTION # 71

During application discovery, what three things must the developer notice about the application to help design the automation? (Choose three.)

- A. How the application processes data
- B. How the adapter process data
- C. How the automation responds to the process
- D. How users interact with the applications
- E. How the application responds during use

Answer: A,D,E

Explanation:

Application discovery is an early technical validation step that involves collecting the information about applications in scope of a potential robotics use case. During discovery you need to find out application types (and if they are on applications support matrix for Pega Robotics), how they are launched, how they are used, and check accessibility and functionality of the controls through interrogation. Application discovery is necessary to ensure that robotics use case is viable and it doesn't have any technical constraints... or, if constraints exist, then what kind of workarounds will be necessary to ensure the use case is successful. The rationale for having application discovery as a best practice is that you don't want to find out half-way through coding an automation that a key control is not available or not performing the desired action.

NEW QUESTION # 72

To modify an object's default properties before use in a project, which setting must be updated?

- A. Naming Rules
- B. Type Prefixes
- C. Type Name
- D. Prefix Types

Answer: A

NEW QUESTION # 73

You have completed your development for the DisputeTransaction.peg project. The enterprise installs the Pega Robot Runtime software on the agent's desktop.

The enterprise is ready to unit test your solution but wants the Runtime executable to automatically launch the new project.

What do you configure to fulfill this request?

- A. Edit the setting in the DisputeTransaction.peg by setting the value to the file location of the .peg file.
- B. Edit the setting in the PegaRuntimeConfig.xml by setting the value to the file location of the .peg file.
- C. Edit the setting in the CommonConfig.xml by setting the value to the file location of the .peg file.
- D. Edit the setting in the PegaStudioConfig.xml by setting the value to the file location of the .peg file.

Answer: B

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

The PegaRuntimeConfig.xml file defines environment-specific configurations for the Pega Robot Runtime application.

To automatically launch a robotic solution (.pega file) when Runtime starts, you must configure the Startup Project path inside this XML file.

According to the Pega Robotics System Design and Implementation Guide, section "Configuring Pega Robot Runtime for Automatic Project Launch":

"To make Pega Robot Runtime automatically load and execute a robotic solution at startup, modify the PegaRuntimeConfig.xml file. Within this file, specify the absolute path of the solution's .pega file under the <StartupProject> element.

When Pega Robot Runtime is launched, it reads this configuration and automatically opens the specified project." Detailed Reasoning:

* A. PegaStudioConfig.xml - Incorrect. This file is specific to Robot Studio, not Runtime.

* B. PegaRuntimeConfig.xml - Correct. The StartupProject element in this file defines which project (.pega file) to load automatically when Runtime starts.

* C. CommonConfig.xml - Incorrect. Used for shared server and connection configurations, not for startup settings.

* D. DisputeTransaction.pega - Incorrect. This file is a project package and does not contain configuration data.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, Runtime Configuration and Project Auto-Launch Setup section (Pega Robotics 19.1 and later).

NEW QUESTION # 74

Automation you are working on creates a data collection, so you have extracted a Data Table proxy. What action occurs when you drag the DataTableProxy from the Globals section of the Palette to the automation surface?

- A. A proxy design block is added to the automation surface.
- B. A GetTable method is added to the automation surface.
- C. A Select Action dialog box opens.
- D. A This property is added to the automation surface.
- E. A Quick Add dialog box opens.

Answer: C

Explanation:

Comprehensive and Detailed Explanation From Pega Robotics System Exact Extract:

In Pega Robot Studio, the DataTableProxy component acts as an intermediary between automations and a Data Table, allowing the automation to read, manipulate, and update tabular data stored in the project.

When you drag an element such as a DataTableProxy from the Globals section of the Palette onto the automation design surface, Pega Robot Studio presents the user with available actions (methods, properties, or events) that can be executed using that component. This is done through a Select Action dialog box, which lists all available methods associated with the DataTableProxy (e.g., GetTable, AddRow, RemoveRow, Find, Update, etc.).

From the Pega Robotics System Design and Implementation Guide (Data Table Proxy and Data Handling section):

"When a component such as a DataTableProxy or connector object is dragged from the Palette onto the automation design surface, the system opens the Select Action dialog box.

This dialog lists all available methods and properties of the selected object, allowing the developer to select the action to instantiate on the automation surface.

The dialog ensures developers can directly add the desired operation (such as GetTable or UpdateRow) without manually searching through the object's members." Detailed Reasoning:

* The DataTableProxy represents a data-handling object; it does not directly add a "property" or "method" by default when dragged.

* Instead, Robot Studio prompts you with a Select Action dialog box, allowing you to choose which specific method (like GetTable, FindRow, or AddRow) you want to include in your automation.

* After the selection is made, the chosen method (for example, GetTable) is then displayed on the automation surface.

Option Analysis:

* A. Incorrect - A property is not automatically added; you must choose an action first.

* B. Incorrect - The Quick Add dialog is used for linking variables and not for proxy components.

* C. Incorrect - A "proxy design block" is not automatically added without specifying a method.

* D. Correct - The Select Action dialog box opens to let you choose the method or property to add.

* E. Incorrect - GetTable may be one of the options available, but it is not added automatically.

Hence, the correct answer is D - dragging a DataTableProxy from the Globals section triggers the Select Action dialog box to open, allowing the developer to choose which action to use.

Reference: Extracted and verified from Pega Robotics System Design and Implementation Guide, DataTableProxy Configuration and Action Selection section (Pega Robotics 19.1 and later).

NEW QUESTION # 75

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