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## 2025 NVIDIA High Pass-Rate NCA-GENL: Reliable Study NVIDIA Generative AI LLMs Questions

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### NVIDIA Generative AI LLMs Sample Questions (Q60-Q65):

#### NEW QUESTION # 60

When designing an experiment to compare the performance of two LLMs on a question-answering task, which statistical test is most appropriate to determine if the difference in their accuracy is significant, assuming the data follows a normal distribution?

- A. Mann-Whitney U test
- B. ANOVA test
- C. Chi-squared test
- **D. Paired t-test**

**Answer: D**

Explanation:

The paired t-test is the most appropriate statistical test to compare the performance (e.g., accuracy) of two large language models (LLMs) on the same question-answering dataset, assuming the data follows a normal distribution. This test evaluates whether the mean difference in paired observations (e.g., accuracy on each question) is statistically significant. NVIDIA's documentation on model evaluation in NeMo suggests using paired statistical tests for comparing model performance on identical datasets to account for correlated errors.

Option A (Chi-squared test) is for categorical data, not continuous metrics like accuracy. Option C (Mann-Whitney U test) is non-parametric and used for non-normal data. Option D (ANOVA) is for comparing more than two groups, not two models.

References:

NVIDIA NeMo Documentation: [https://docs.nvidia.com/deeplearning/nemo/user-guide/docs/en/stable/nlp/model\\_finetuning.html](https://docs.nvidia.com/deeplearning/nemo/user-guide/docs/en/stable/nlp/model_finetuning.html)

### NEW QUESTION # 61

In the context of a natural language processing (NLP) application, which approach is most effective for implementing zero-shot learning to classify text data into categories that were not seen during training?

- **A. Use a pre-trained language model with semantic embeddings.**
- B. Train the new model from scratch for each new category encountered.
- C. Use rule-based systems to manually define the characteristics of each category.
- D. Use a large, labeled dataset for each possible category.

**Answer: A**

Explanation:

Zero-shot learning allows models to perform tasks or classify data into categories without prior training on those specific categories. In NLP, pre-trained language models (e.g., BERT, GPT) with semantic embeddings are highly effective for zero-shot learning because they encode general linguistic knowledge and can generalize to new tasks by leveraging semantic similarity. NVIDIA's NeMo documentation on NLP tasks explains that pre-trained LLMs can perform zero-shot classification by using prompts or embeddings to map input text to unseen categories, often via techniques like natural language inference or cosine similarity in embedding space. Option A (rule-based systems) lacks scalability and flexibility. Option B contradicts zero-shot learning, as it requires labeled data. Option C (training from scratch) is impractical and defeats the purpose of zero-shot learning.

References:

NVIDIA NeMo Documentation: <https://docs.nvidia.com/deeplearning/nemo/user-guide/docs/en/stable/nlp/intro.html>

Brown, T., et al. (2020). "Language Models are Few-Shot Learners."

### NEW QUESTION # 62

In the context of language models, what does an autoregressive model predict?

- **A. The probability of the next token in a text given the previous tokens.**
- B. The probability of the next token by looking at the previous and future input tokens.
- C. The next token solely using recurrent network or LSTM cells.
- D. The probability of the next token using a Monte Carlo sampling of past tokens.

**Answer: A**

Explanation:

Autoregressive models are a cornerstone of modern language modeling, particularly in large language models (LLMs) like those discussed in NVIDIA's Generative AI and LLMs course. These models predict the probability of the next token in a sequence based solely on the preceding tokens, making them inherently sequential and unidirectional. This process is often referred to as "next-token prediction," where the model learns to generate text by estimating the conditional probability distribution of the next token given the context of all previous tokens. For example, given the sequence "The cat is," the model predicts the likelihood of the next word being "on," "in," or another token. This approach is fundamental to models like GPT, which rely on autoregressive decoding to

generate coherent text. Unlike bidirectional models (e.g., BERT), which consider both previous and future tokens, autoregressive models focus only on past tokens, making option D incorrect. Options B and C are also inaccurate, as Monte Carlo sampling is not a standard method for next-token prediction in autoregressive models, and the prediction is not limited to recurrent networks or LSTM cells, as modern LLMs often use Transformer architectures. The course emphasizes this concept in the context of Transformer-based NLP: "Learn the basic concepts behind autoregressive generative models, including next-token prediction and its implementation within Transformer-based models." References: NVIDIA Building Transformer-Based Natural Language Processing Applications course; NVIDIA Introduction to Transformer-Based Natural Language Processing.

### NEW QUESTION # 63

When designing prompts for a large language model to perform a complex reasoning task, such as solving a multi-step mathematical problem, which advanced prompt engineering technique is most effective in ensuring robust performance across diverse inputs?

- A. Retrieval-augmented generation with external mathematical databases.
- **B. Chain-of-thought prompting with step-by-step reasoning examples.**
- C. Few-shot prompting with randomly selected examples.
- D. Zero-shot prompting with a generic task description.

**Answer: B**

Explanation:

Chain-of-thought (CoT) prompting is an advanced prompt engineering technique that significantly enhances a large language model's (LLM) performance on complex reasoning tasks, such as multi-step mathematical problems. By including examples that explicitly demonstrate step-by-step reasoning in the prompt, CoT guides the model to break down the problem into intermediate steps, improving accuracy and robustness.

NVIDIA's NeMo documentation on prompt engineering highlights CoT as a powerful method for tasks requiring logical or sequential reasoning, as it leverages the model's ability to mimic structured problem-solving. Research by Wei et al. (2022) demonstrates that CoT outperforms other methods for mathematical reasoning. Option A (zero-shot) is less effective for complex tasks due to lack of guidance. Option B (few-shot with random examples) is suboptimal without structured reasoning. Option D (RAG) is useful for factual queries but less relevant for pure reasoning tasks.

References:

NVIDIA NeMo Documentation: <https://docs.nvidia.com/deeplearning/nemo/user-guide/docs/en/stable/nlp/intro.html> Wei, J., et al. (2022). "Chain-of-Thought Prompting Elicits Reasoning in Large Language Models."

### NEW QUESTION # 64

What is the main difference between forward diffusion and reverse diffusion in diffusion models of Generative AI?

- A. Forward diffusion focuses on generating a sample from a given noise vector, while reverse diffusion reverses the process by estimating the latent space representation of a given sample.
- B. Forward diffusion uses feed-forward networks, while reverse diffusion uses recurrent networks.
- **C. Forward diffusion focuses on progressively injecting noise into data, while reverse diffusion focuses on generating new samples from the given noise vectors.**
- D. Forward diffusion uses bottom-up processing, while reverse diffusion uses top-down processing to generate samples from noise vectors.

**Answer: C**

Explanation:

Diffusion models, a class of generative AI models, operate in two phases: forward diffusion and reverse diffusion. According to NVIDIA's documentation on generative AI (e.g., in the context of NVIDIA's work on generative models), forward diffusion progressively injects noise into a data sample (e.g., an image or text embedding) over multiple steps, transforming it into a noise distribution. Reverse diffusion, conversely, starts with a noise vector and iteratively denoises it to generate a new sample that resembles the training data distribution. This process is central to models like DDPM (Denoising Diffusion Probabilistic Models). Option A is incorrect, as forward diffusion adds noise, not generates samples. Option B is false, as diffusion models typically use convolutional or transformer-based architectures, not recurrent networks. Option C is misleading, as diffusion does not align with bottom-up/top-down processing paradigms.

References:

NVIDIA Generative AI Documentation: <https://www.nvidia.com/en-us/ai-data-science/generative-ai/> Ho, J., et al. (2020). "Denoising Diffusion Probabilistic Models."

## NEW QUESTION # 65

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